

ROBOTICS

SAAST



Text





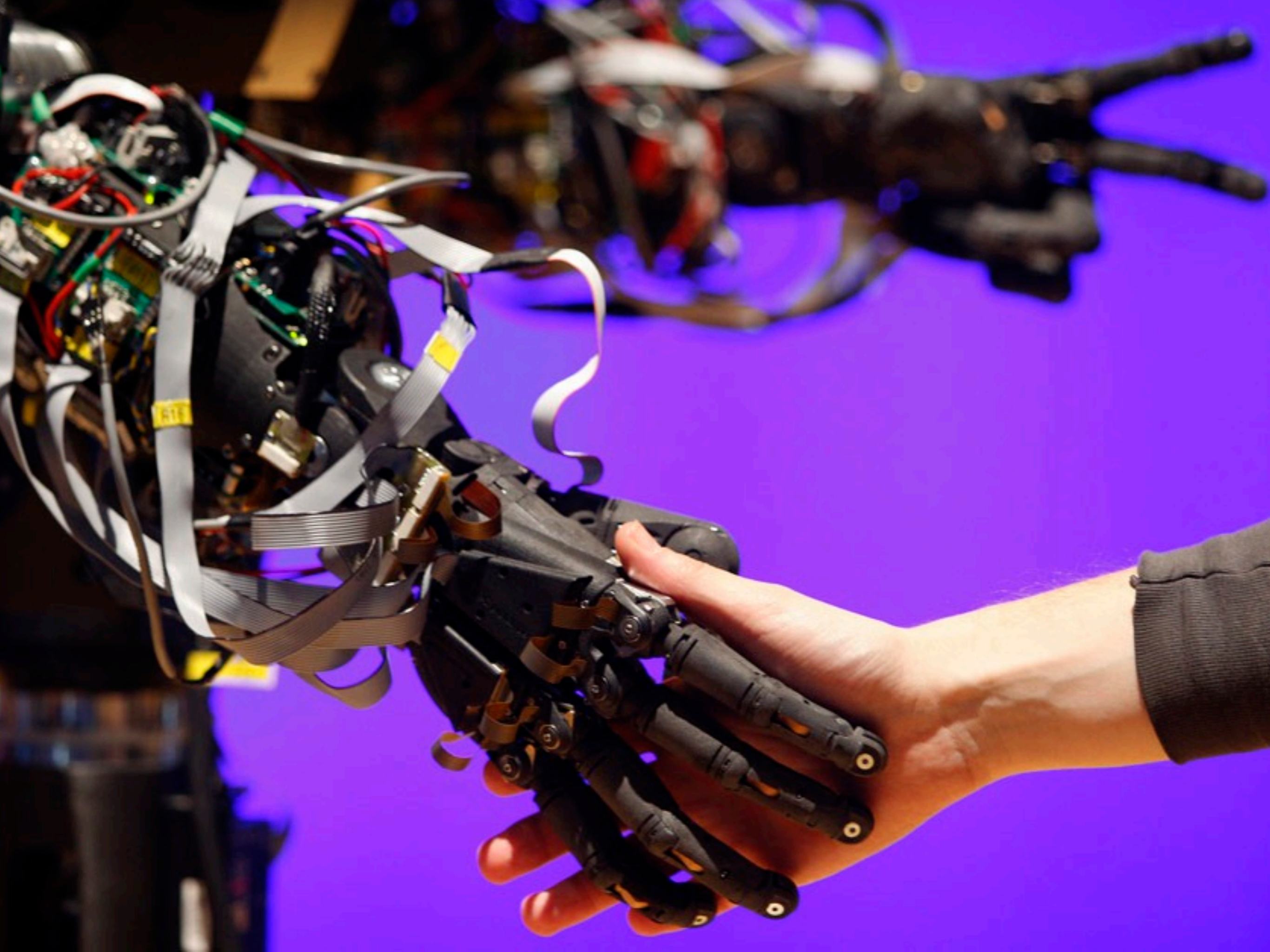


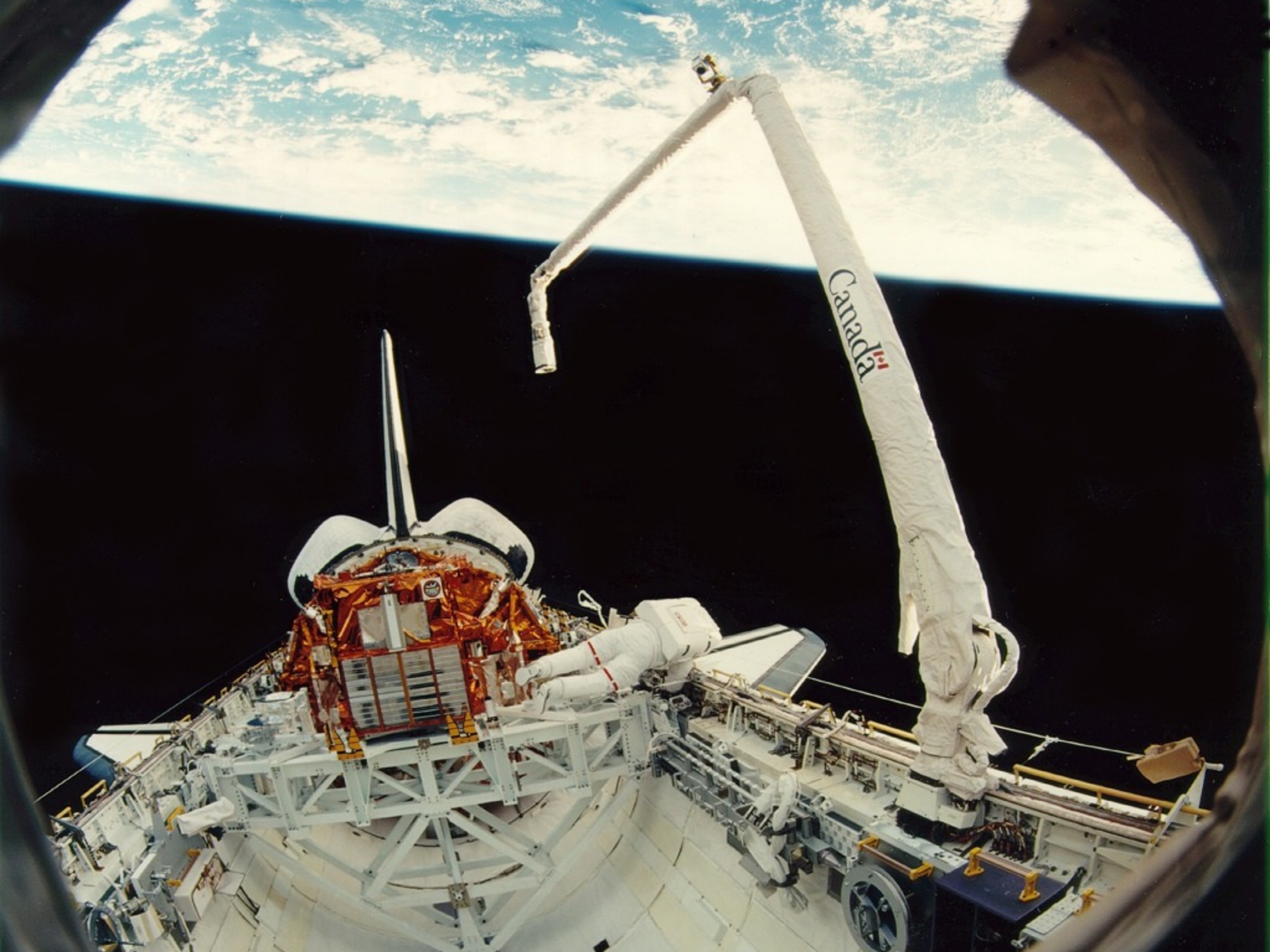
料理の鉄腕人
【好み焼きロボット】

・出展協力
【理機工業株式会社】

・特徴
の最新世代産業用ロボット
コミュニケーション
新しいメカニクス
環境









322 B.C. - “If every tool, when ordered, or even of its own accord, could do the work that befits it... then there would be no need either of apprentices for the master workers or of slaves for the lords.” - Aristotle

1495 - Leonard da Vinci designs a mechanical clockwork that sits up, waves its arms, and moves its head.



1769 - Wolfgang von Kempelen builds “The Turk”, which gains fame as an automaton capable of playing chess - until the hidden human operator was discovered!

1921 - Karel Capek popularizes the term “robot” in a play called *R.U.R.* (*Rossum’s Universal Robots*) wherein robot workers take over the earth.



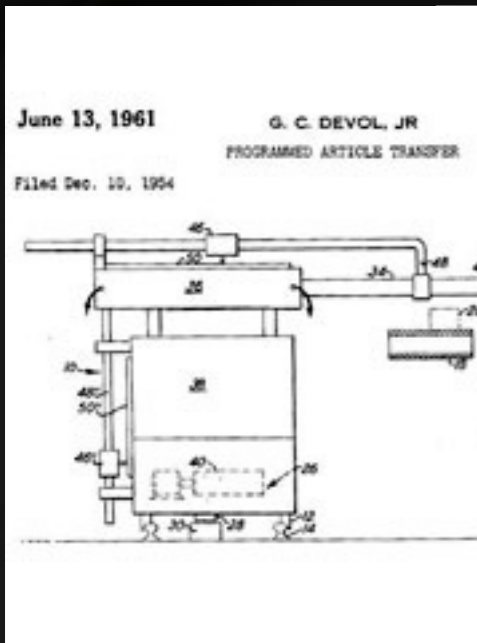


1942 - Isaac Asimov publishes *Runaround*, which introduces the three “laws” of robotics.

1951 - Raymond Goertz builds the first master/slave teleoperation system for handling radioactive material.



1954 - George Devol files a patent for the first programmable robot, and calls it “universal automation”.



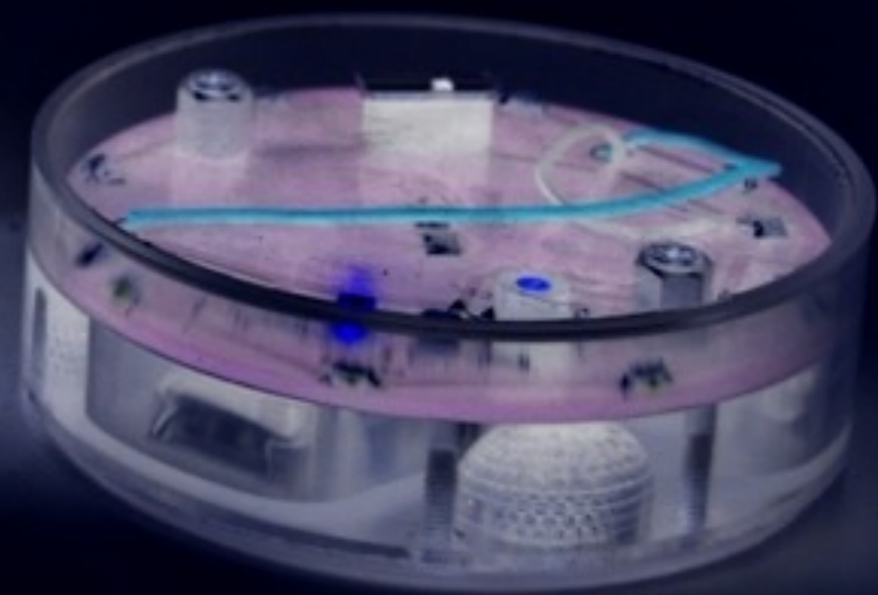
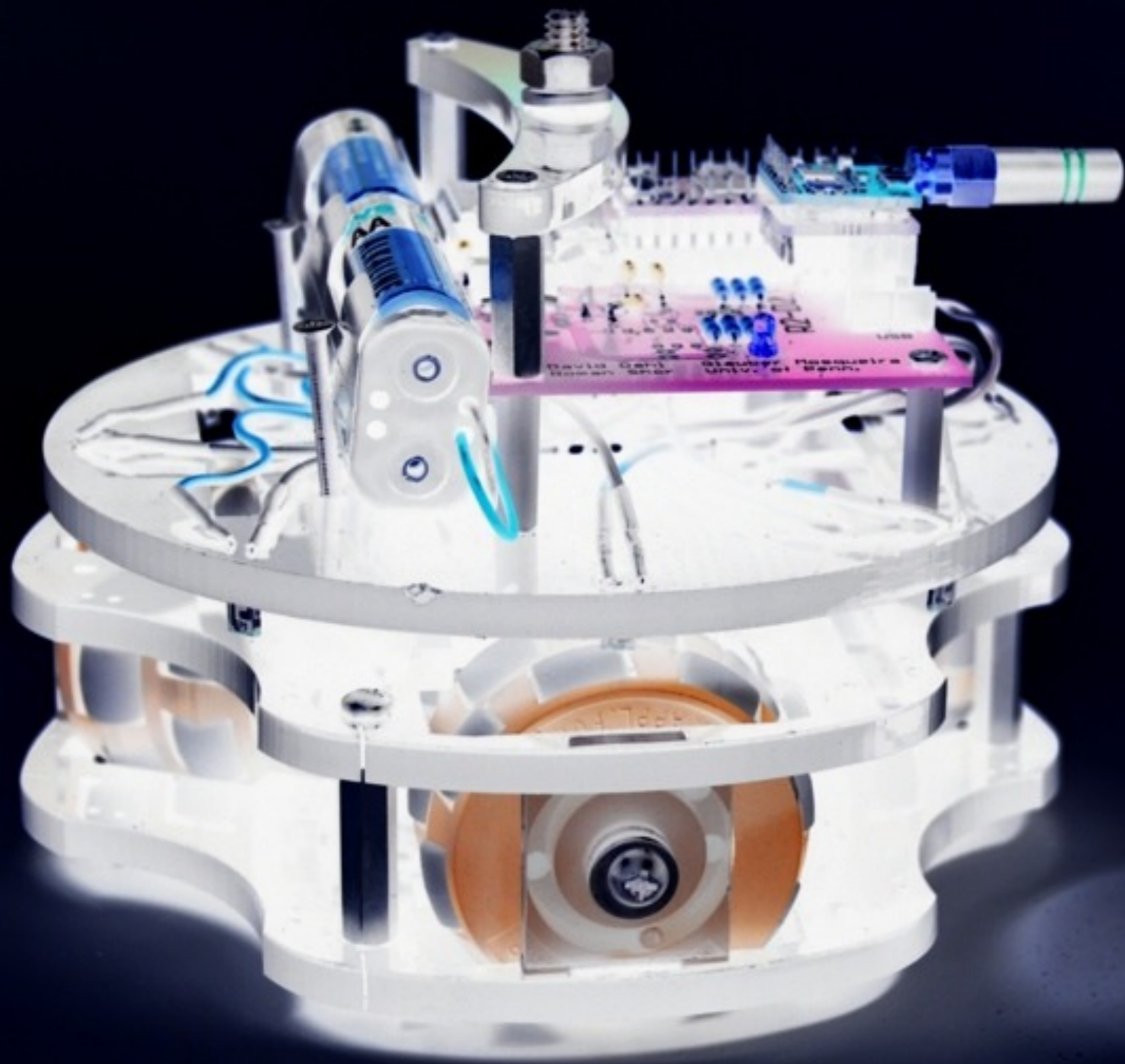
1961- *Unimate*, the first industrial robot, begins work on a General Motors assembly line.





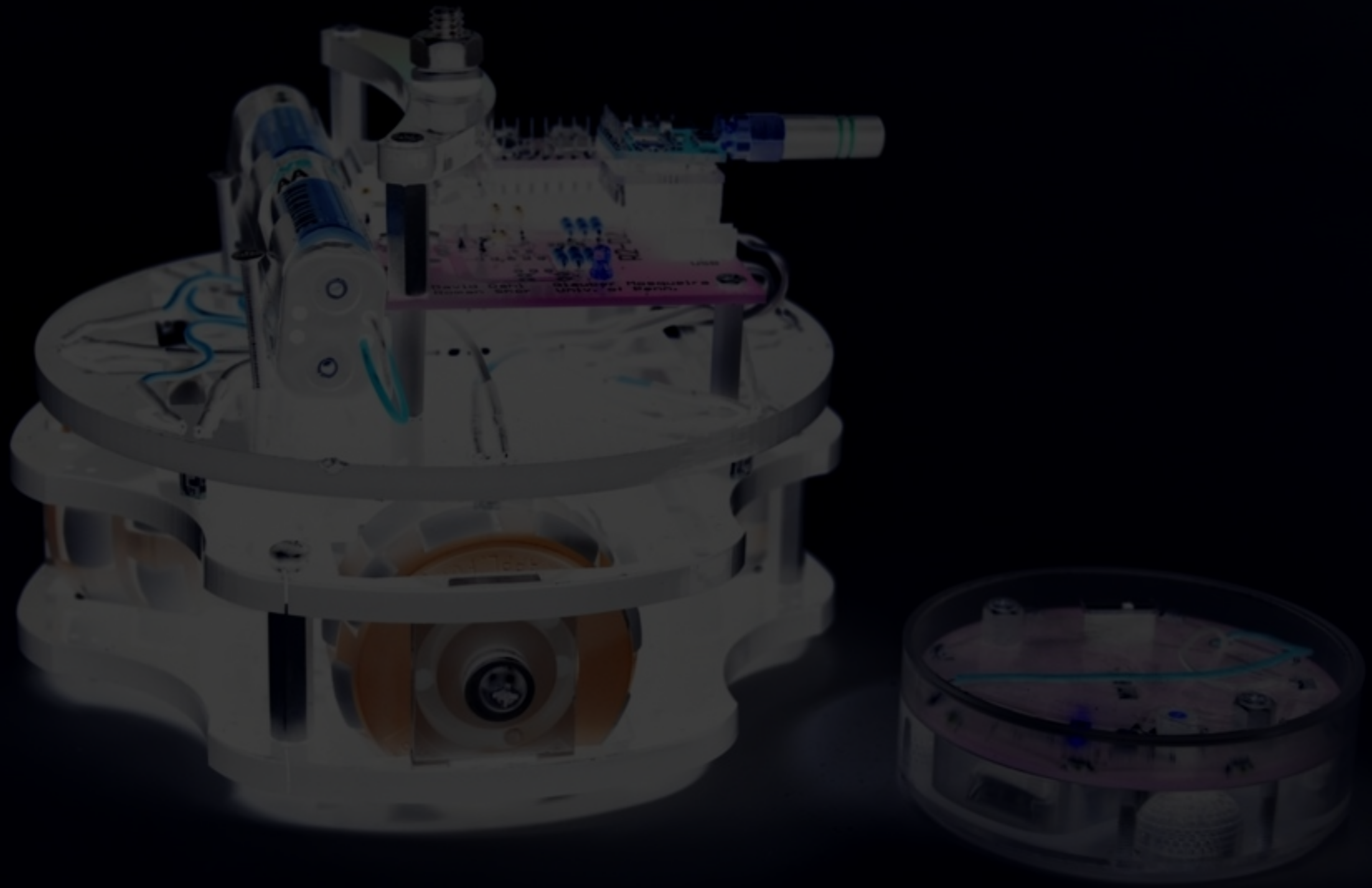
“A robot is a reprogrammable, multifunctional manipulator designed to move material, parts, tools, or specialized devices through variable programmed motions for the performance of a variety of tasks.”

(The Robotics Institute of America)



Mechatronics is the synergistic combination of Mechanical engineering, Electrical engineering, Computer engineering, Control engineering, and Systems Design engineering in order to design and manufacture useful products.

-Wikipedia



Logistics

Locations

Towne 100 (Heilmeyer)

lecture room

Towne 205

door code: 4-2-1-9

18 stations

SolidWorks, programming

Towne 193 (GM)

card-swipe

19 stations

electronics, programming, SolidWorks, light fabrication, assembly

Towne 167

TA supervision required

laser cutting

Schedule

Monday program overview, SolidWorks I, electronics I

Tuesday teams, electronics II, SolidWorks II

Wednesday embedded computing, C programming, mX introduction

Thursday FIELD TRIP

Friday C programming II, mX details, project details

Monday electronics III

Tuesday

Wednesday

Thursday

Friday

Monday

Tuesday

Wednesday testing and interviews

Thursday COMPETITION

Friday public showcase, graduation luncheon

Online Resources

Course Wiki - <http://medesign.seas.upenn.edu>

MEAM.Design : HomePage View Logout
Edit Upload


GENERAL
Hall of Fame
Laboratories
Contact Info

COURSES
MEAM 101
MEAM 201
MEAM 248
MEAM 410/510
MEAM 520
IPD 501
SAAST

GUIDES
Materials
Laser Cutting
3D Printing
Machining
PUMA 260
PHANTOM
BeagleBoard
MAEVARM
Phidget
Tap Chart

SOFTWARE
SolidWorks
Matlab
NX
Nastran
Fluent, Gambit
SolidCAM
Eagle
ProtoTRAK

OTHER
Vendor List
Design Links



IPD501 propeller for a custom-designed submarine.

[Repository of Past Homepage Photos](#)

Welcome to the home of MEAM.Design! By its nature, this wiki will be constantly evolving. If you'd like to join in the fun, please [register](#) to set up a username and password.

Lab kits

solderless breadboard

hookup wire kit

small screwdriver

diagonal cutters

wire strippers (20-30 AWG)

(5) alligator-clip wires

(5) mini-grabber wires

coaxial banana-alligator wire

mini-B USB cable

2 oz. roll of 25-gauge 63/37 solder

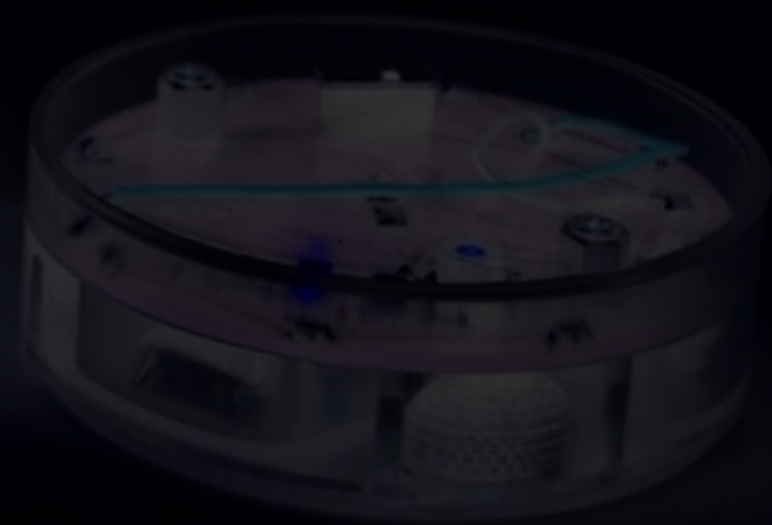
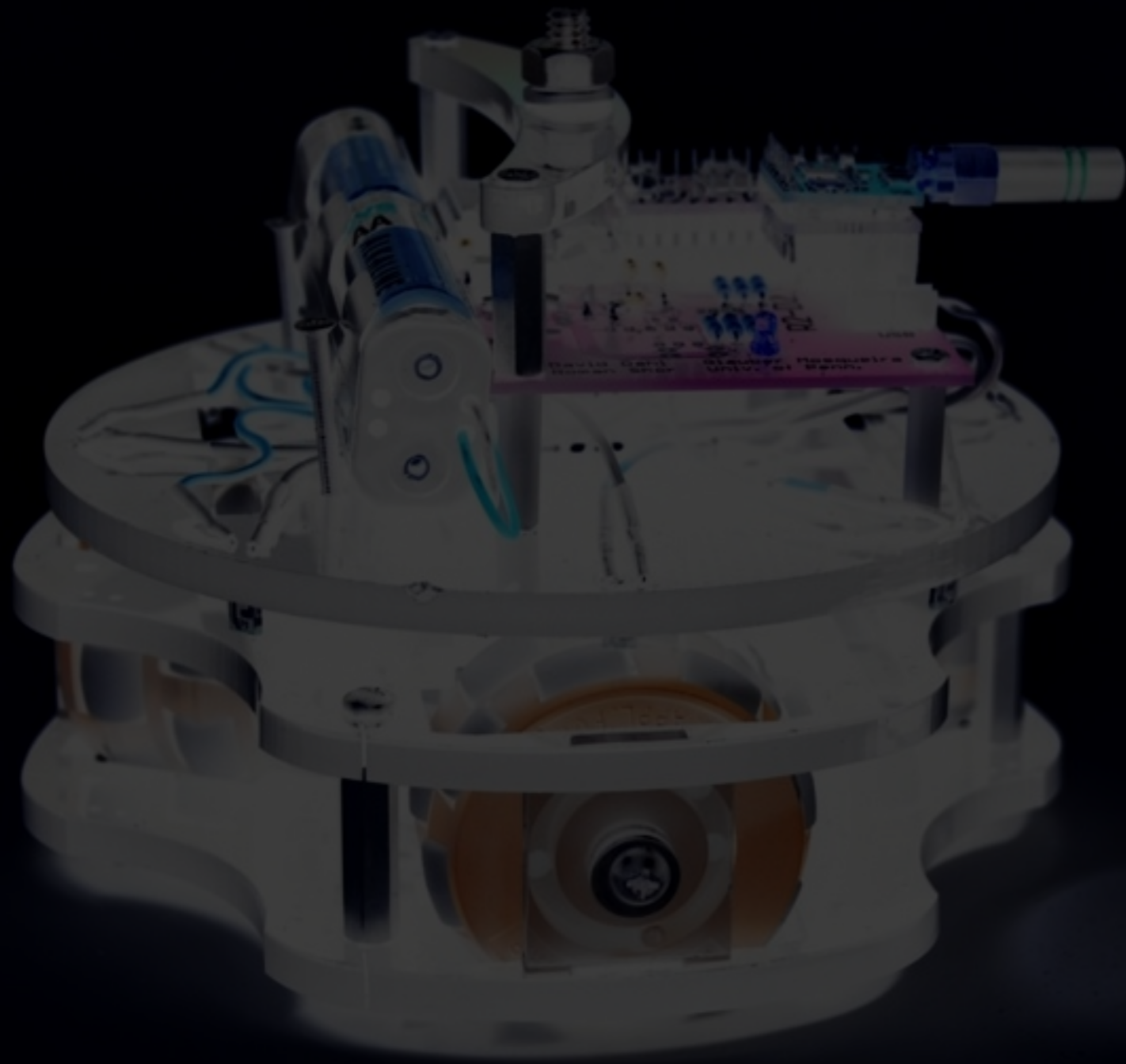
Components (& Grading)

6 individual assignments (50%)

2 team assignments (15%)

1 final team project (25%)

n quizzes (10%)



Expectations

