

Design Process



Find as many ways as possible to use **two electric motors** to create a planar mobile robot base.

TROUBLE!

1. plan for **easy access**
2. include for **observability**
3. work **incrementally** and test as you go
4. confirm **power and ground**
5. look at the **datasheet**
6. test **hypotheses**
7. **record** changes/results
8. know your **limits**