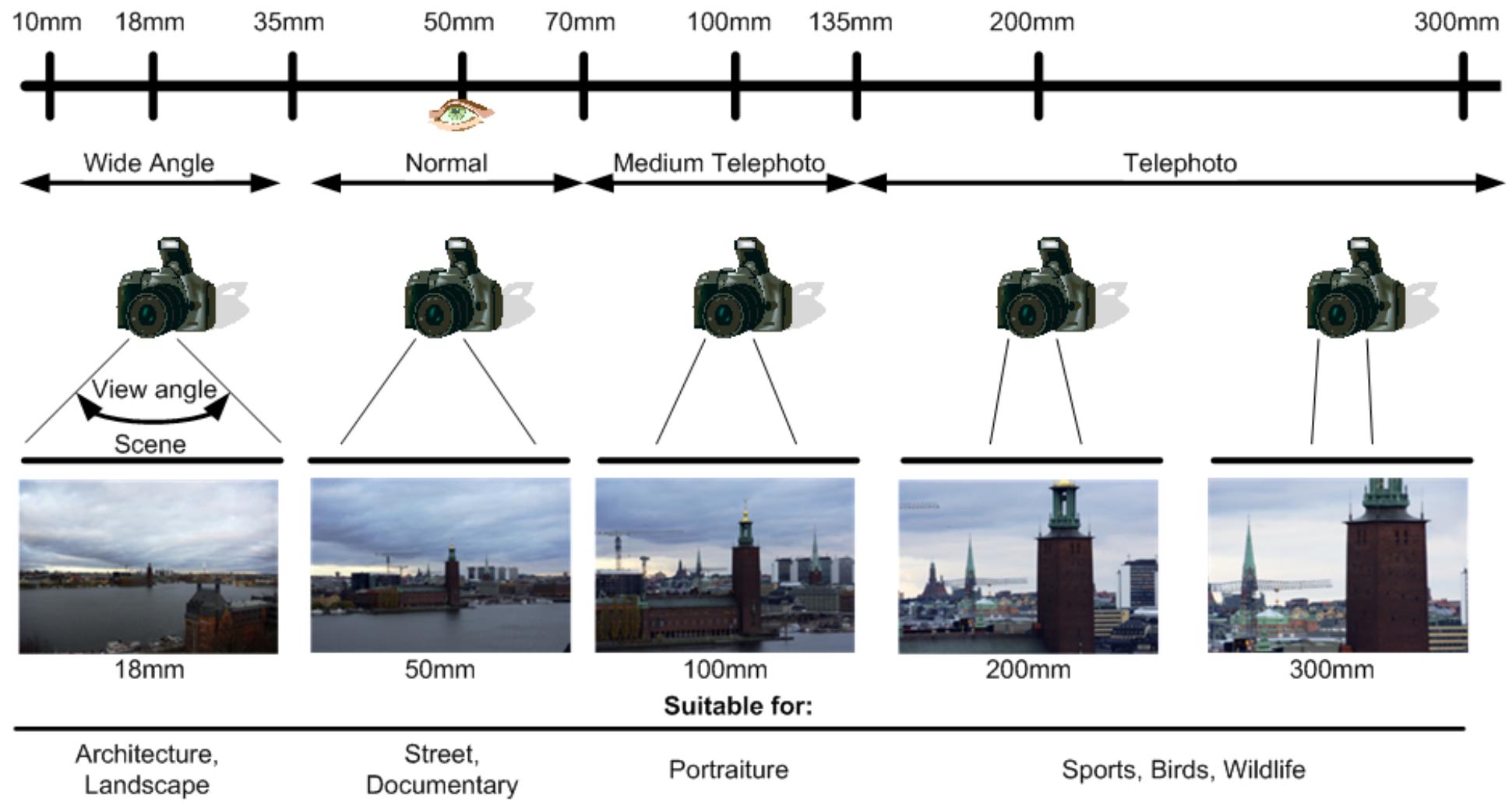


Image Projection

Field of View (Zoom)



Focal length



Large Focal Length compresses depth



400 mm

200 mm

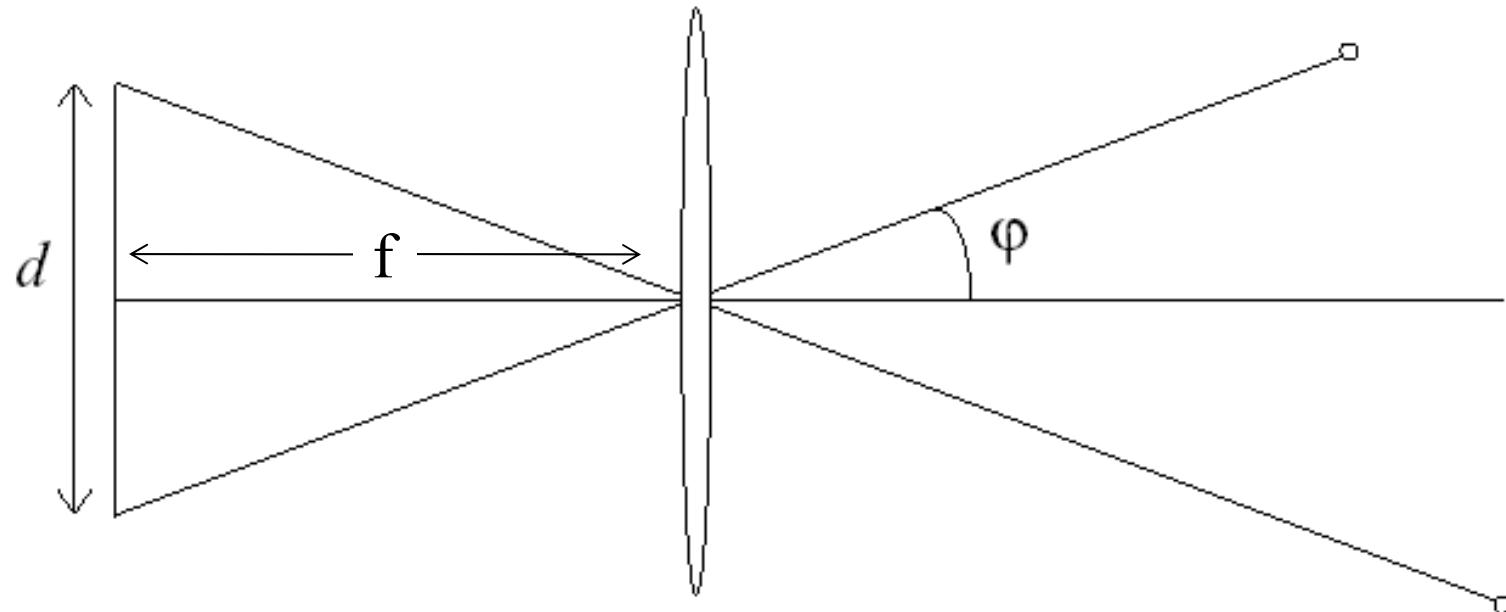
100 mm

50 mm

28 mm

17 mm

FOV depends of Focal Length

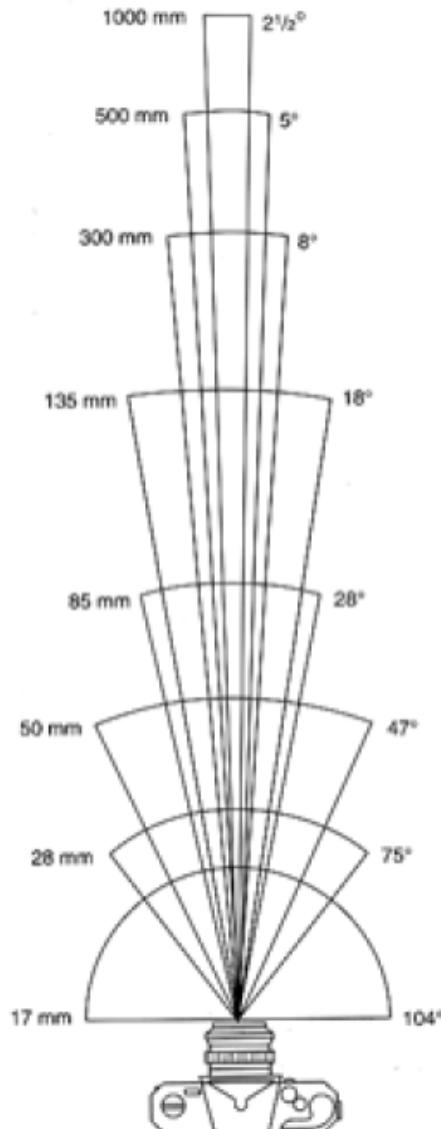


Size of field of view governed by size of the camera retina:

$$\varphi = \tan^{-1}\left(\frac{d}{2f}\right)$$

Smaller FOV = larger Focal Length

Field of View (Zoom)



17mm



28mm



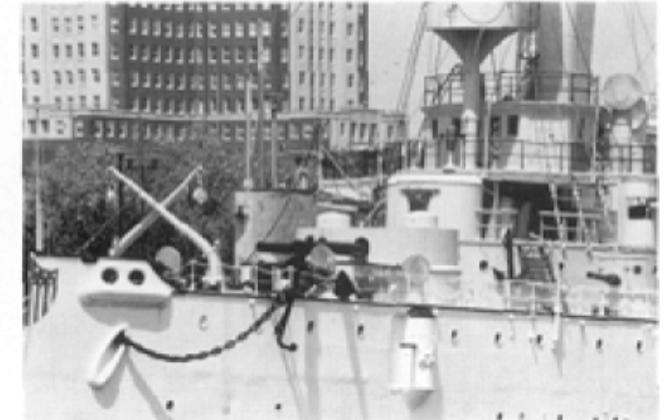
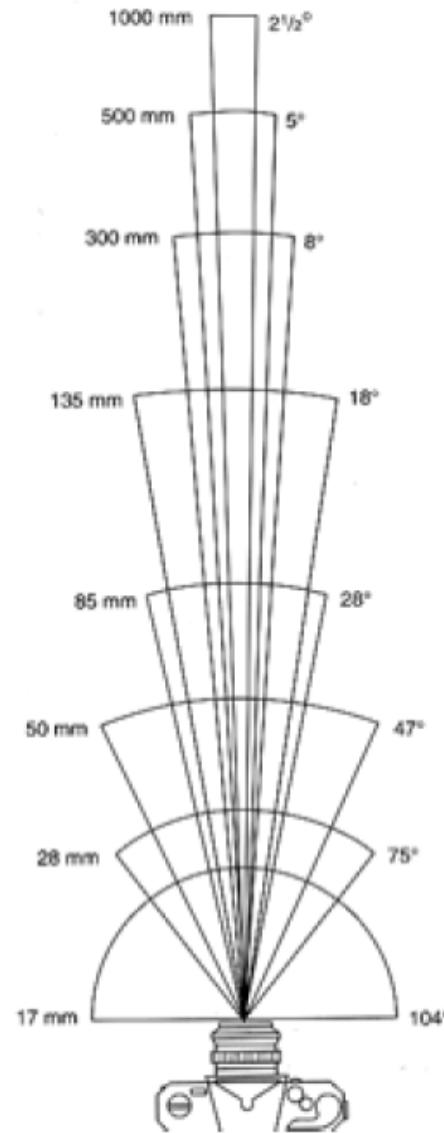
50mm



85mm

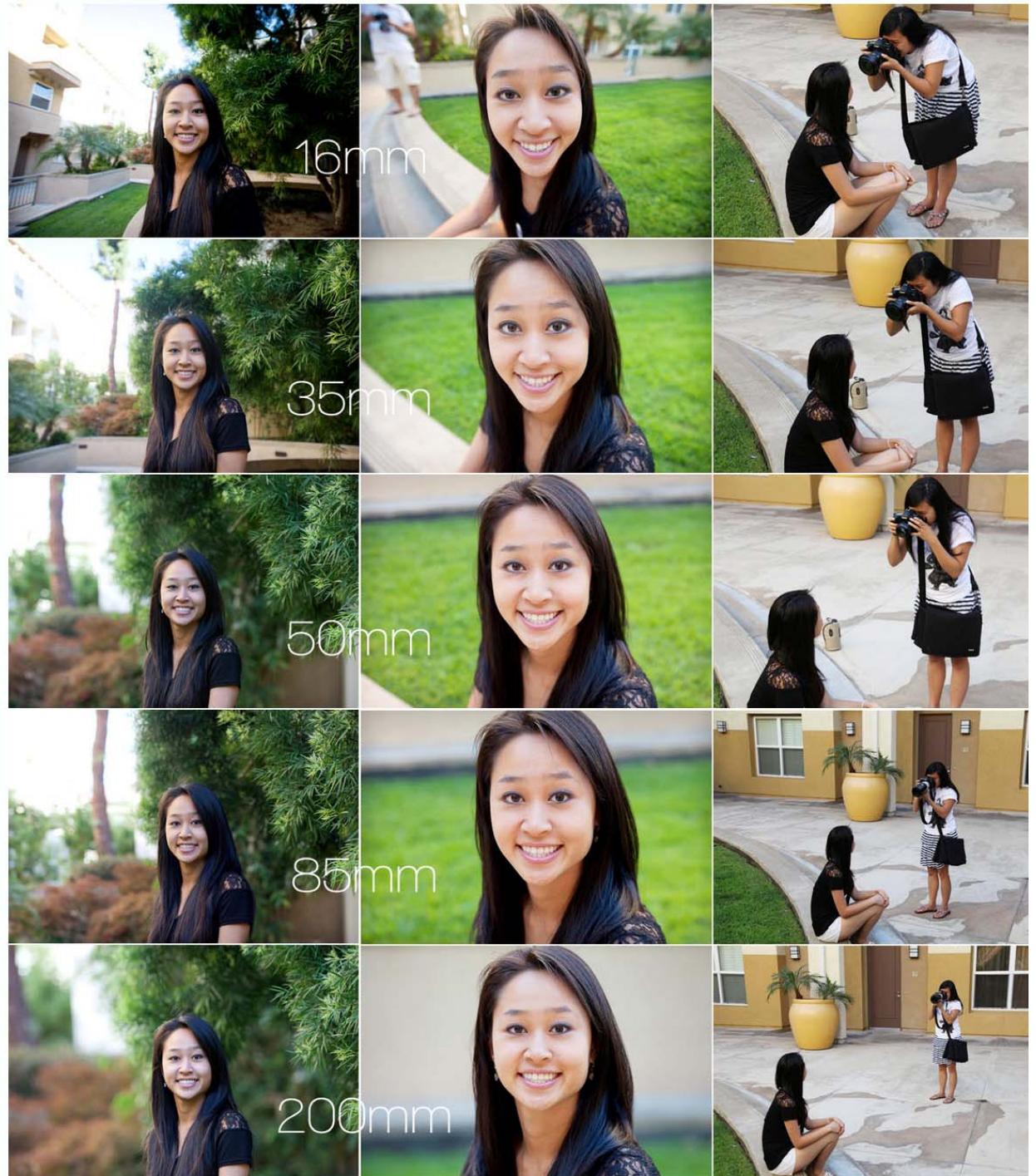
From London and Upton

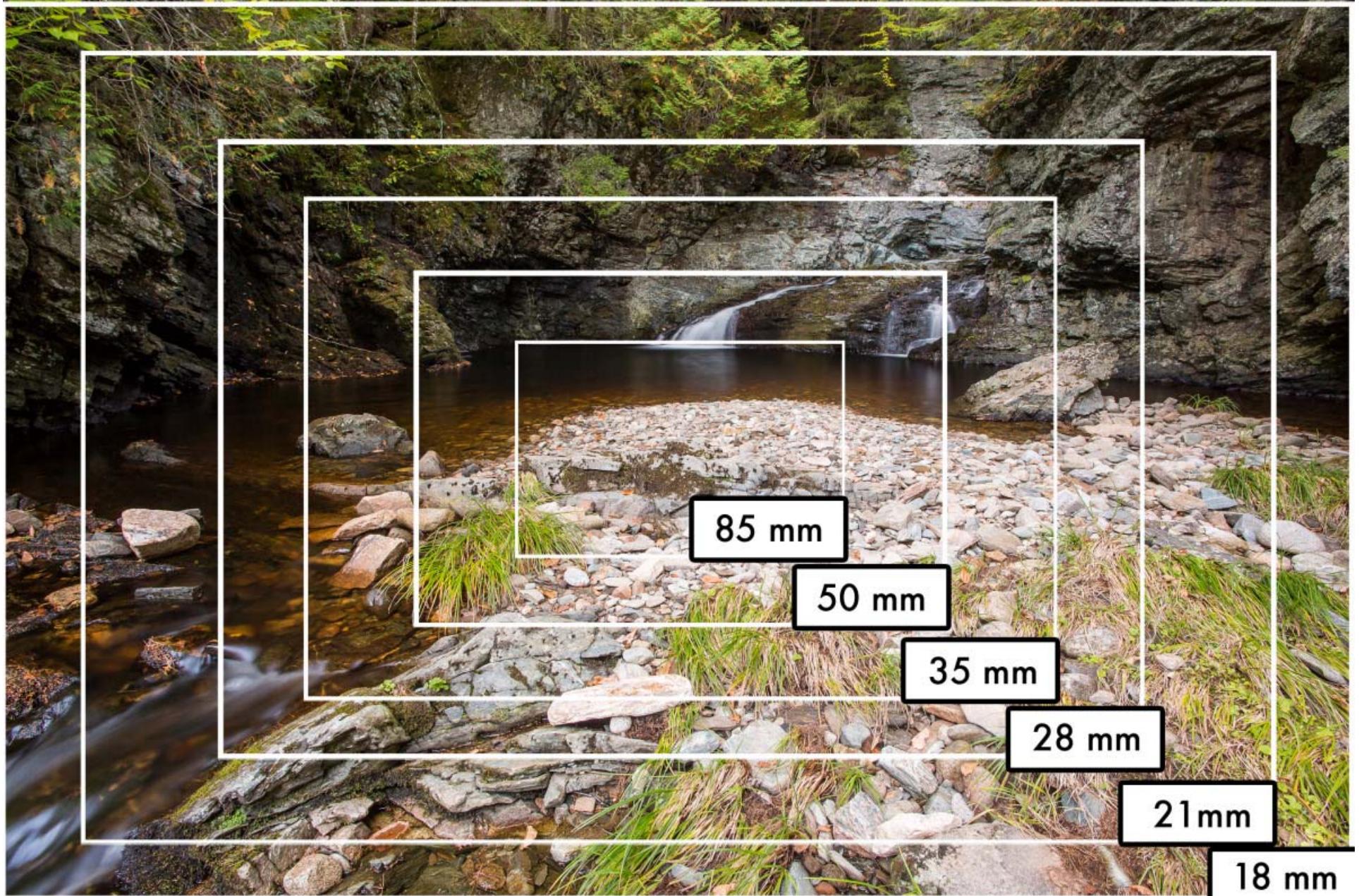
Field of View (Zoom)



From London and Upton

<http://2blowup.com/fotografia-para-egobloggers-ii/>





Fisheye lens distortion

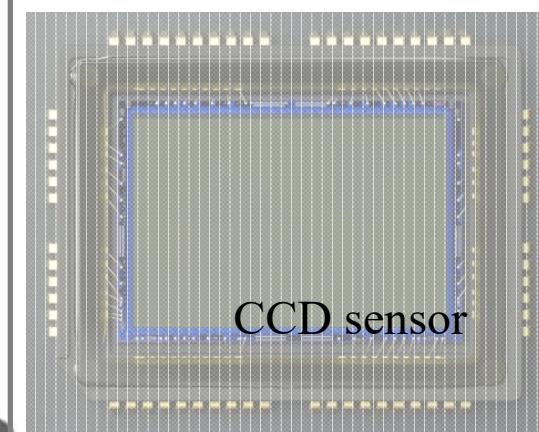




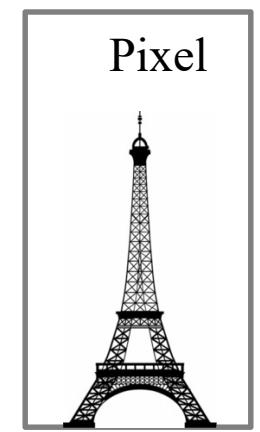
Camera Model



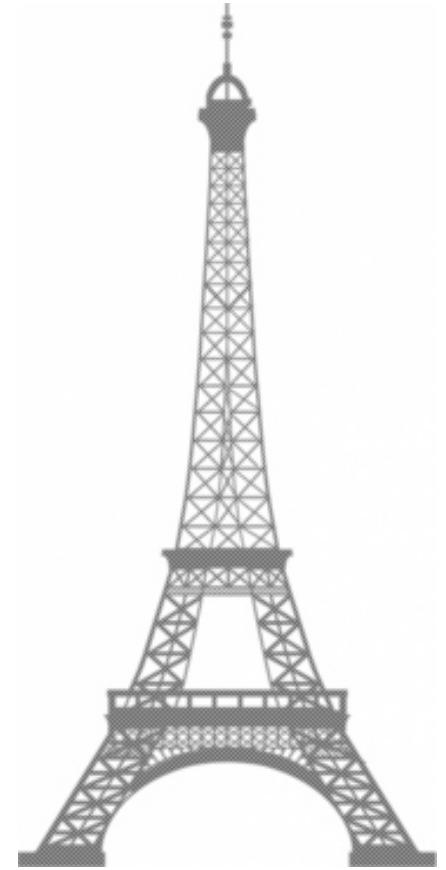
Lens



CCD sensor

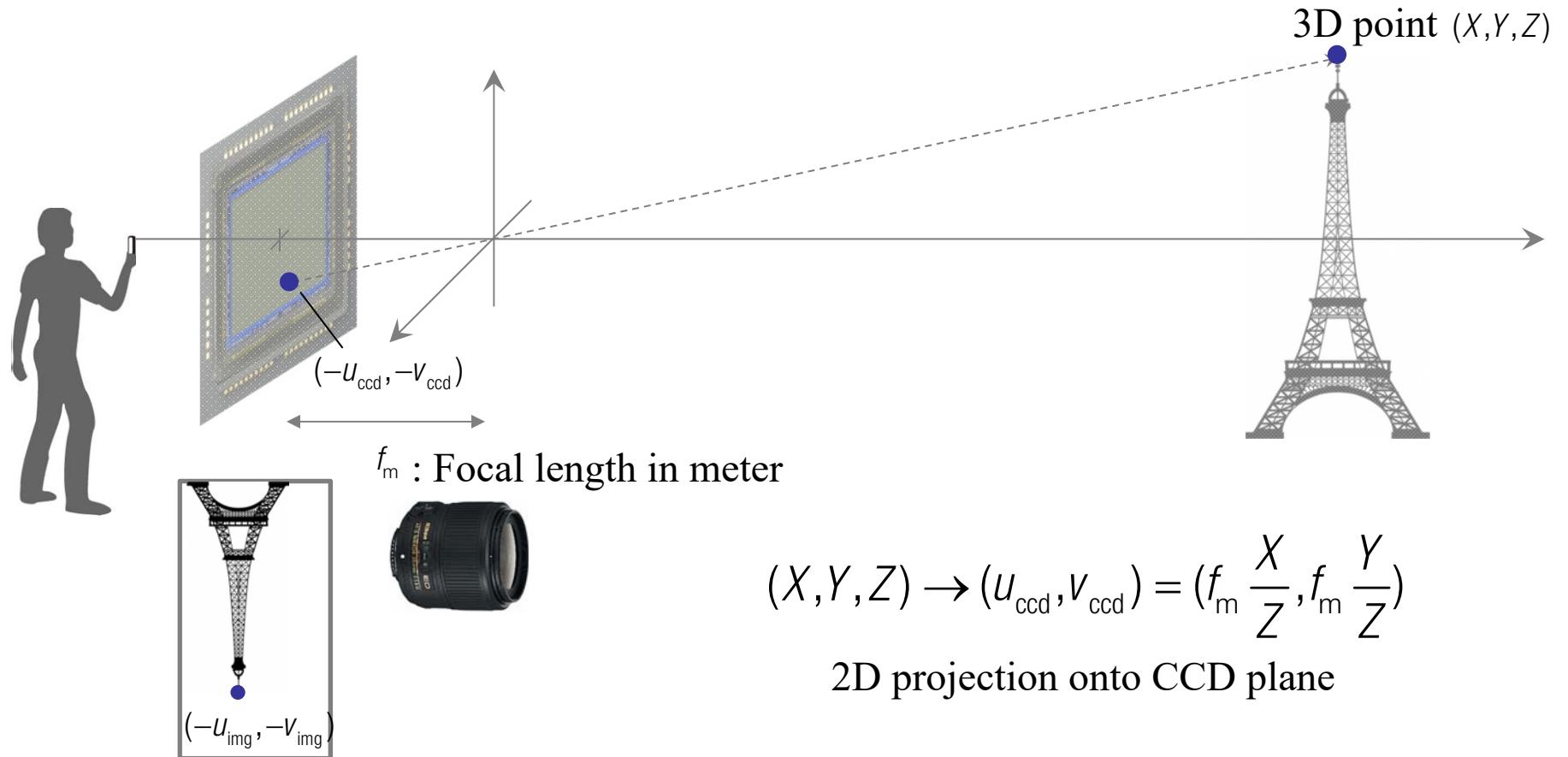


Pixel

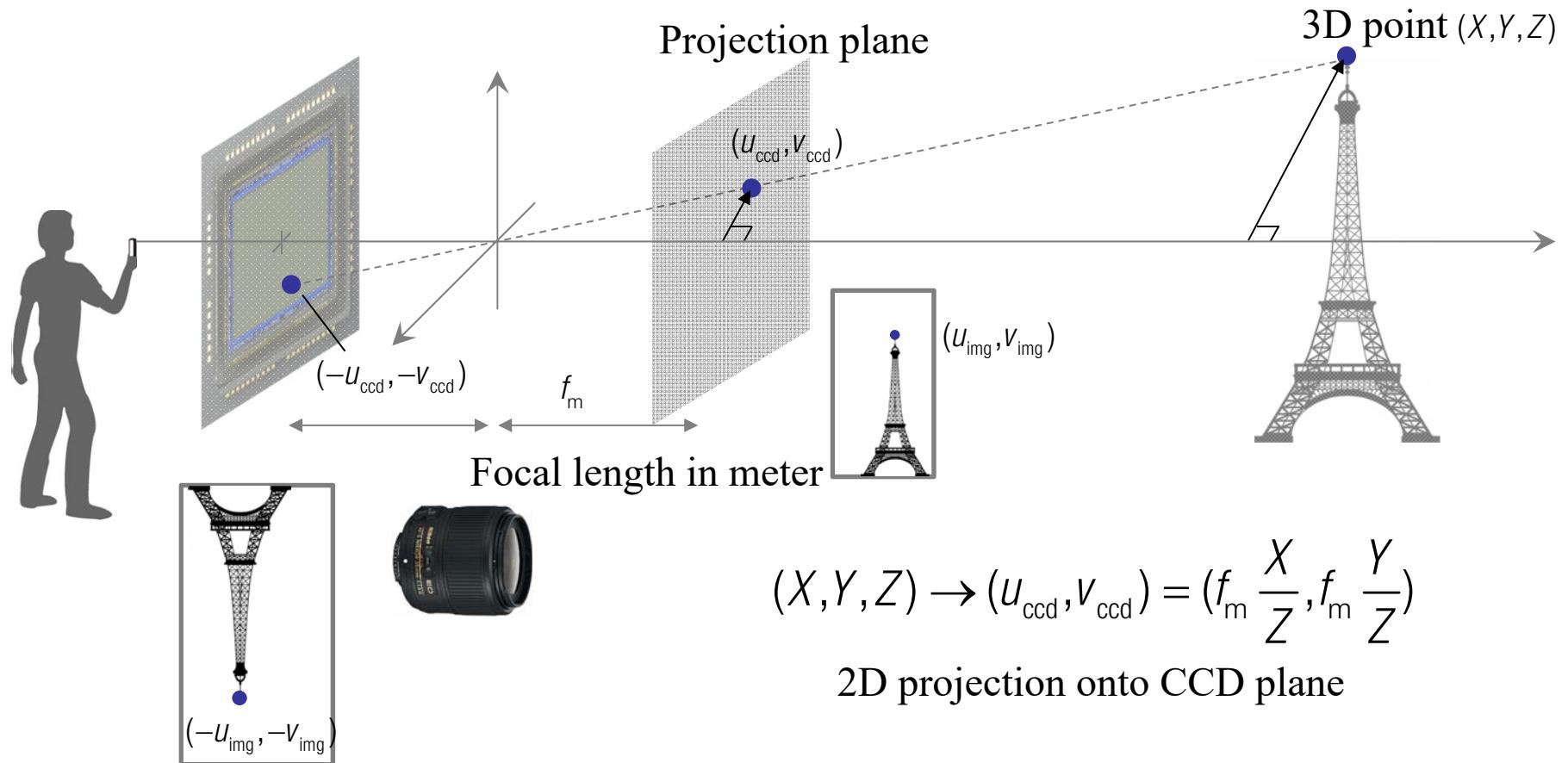


3D object

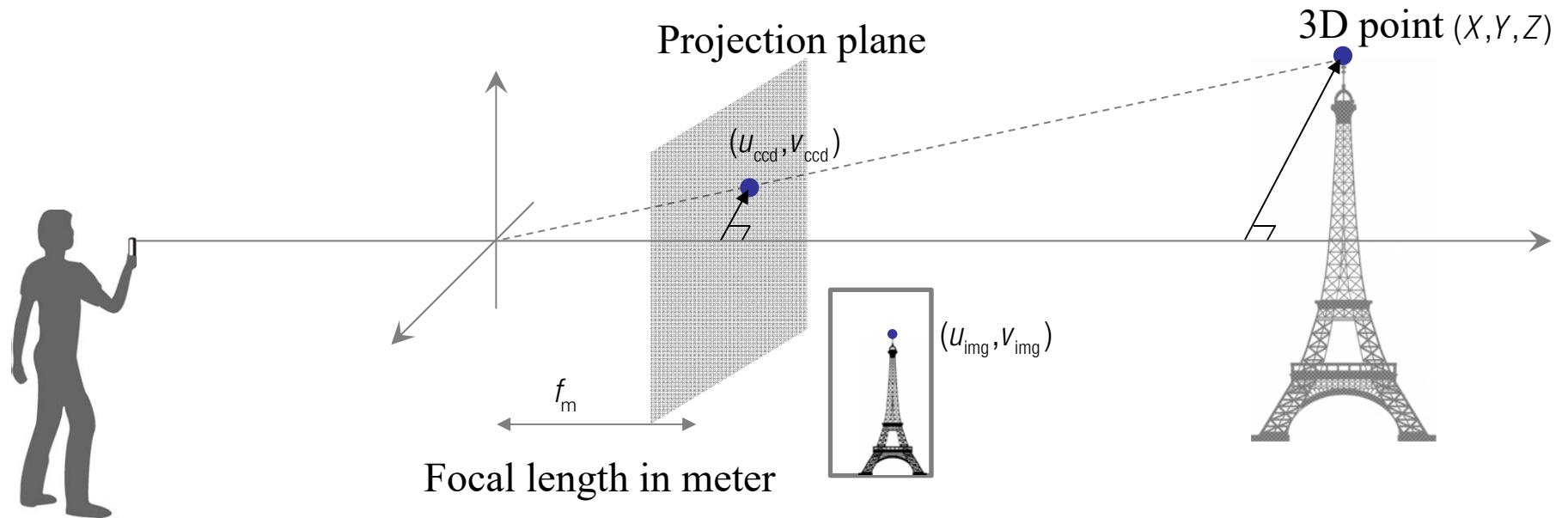
3D Point Projection (Metric Space)



3D Point Projection (Metric Space)



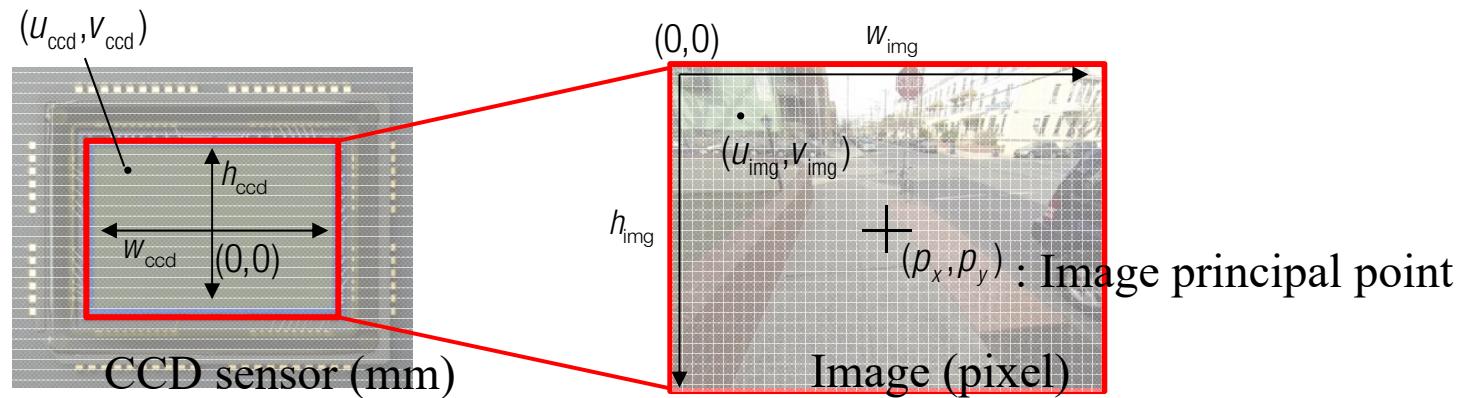
3D Point Projection (Metric Space)



$$(X, Y, Z) \rightarrow (u_{\text{ccd}}, v_{\text{ccd}}) = (f_m \frac{X}{Z}, f_m \frac{Y}{Z})$$

2D projection onto CCD plane

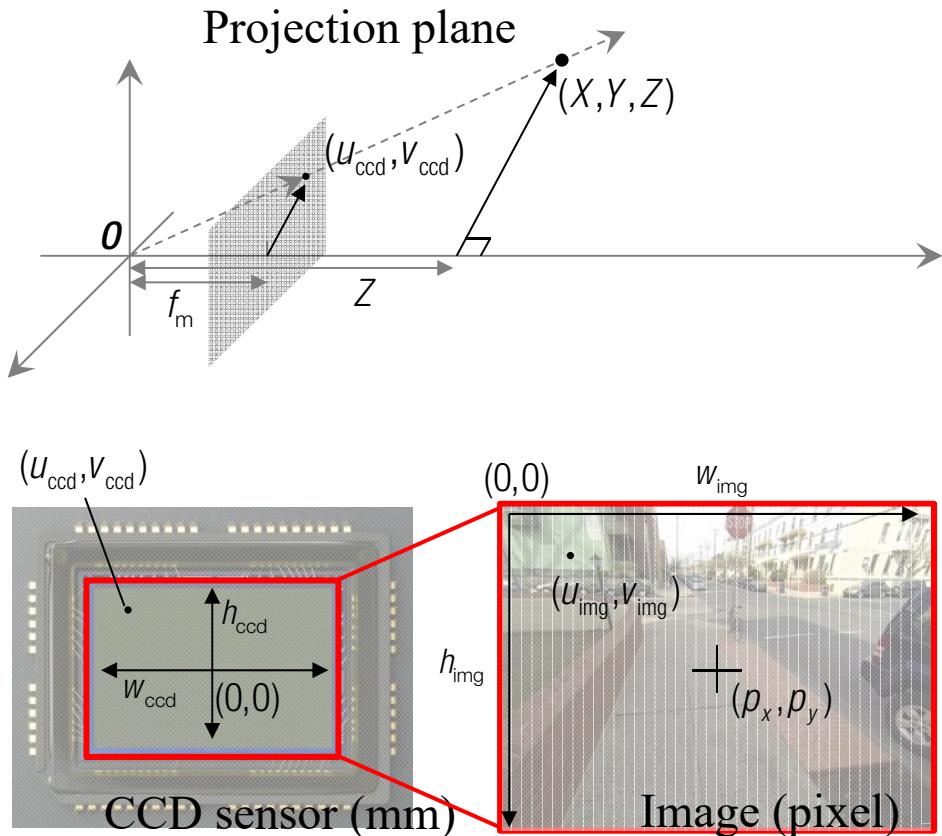
3D Point Projection (Pixel Space)



$$\frac{u_{\text{ccd}}}{w_{\text{ccd}}} = \frac{u_{\text{img}} - p_x}{w_{\text{img}}} \quad \frac{v_{\text{ccd}}}{h_{\text{ccd}}} = \frac{v_{\text{img}} - p_y}{h_{\text{img}}}$$

$$u_{\text{img}} = u_{\text{ccd}} \frac{w_{\text{img}}}{w_{\text{ccd}}} + p_x \quad v_{\text{img}} = v_{\text{ccd}} \frac{h_{\text{img}}}{h_{\text{ccd}}} + p_y$$

3D Point Projection (Pixel Space)



$$(X, Y, Z) \rightarrow (u_{\text{ccd}}, v_{\text{ccd}}) = (f_m \frac{X}{Z}, f_m \frac{Y}{Z})$$

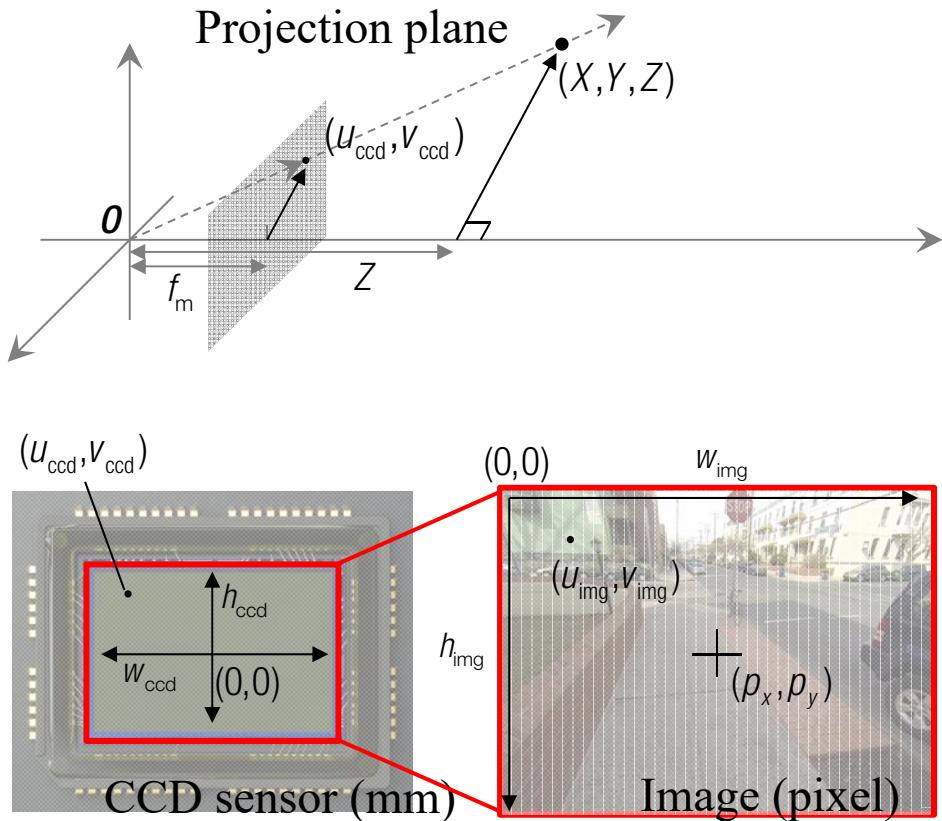
$$u_{\text{img}} = u_{\text{ccd}} \frac{w_{\text{img}}}{w_{\text{ccd}}} + p_x = f_m \frac{w_{\text{img}}}{w_{\text{ccd}}} \frac{X}{Z} + p_x$$

Focal length in pixel

$$v_{\text{img}} = v_{\text{ccd}} \frac{h_{\text{img}}}{h_{\text{ccd}}} + p_y = f_m \frac{h_{\text{img}}}{h_{\text{ccd}}} \frac{Y}{Z} + p_y$$

Focal length in pixel

3D Point Projection (Pixel Space)



$$(X, Y, Z) \rightarrow (u_{\text{ccd}}, v_{\text{ccd}}) = (f_m \frac{X}{Z}, f_m \frac{Y}{Z})$$

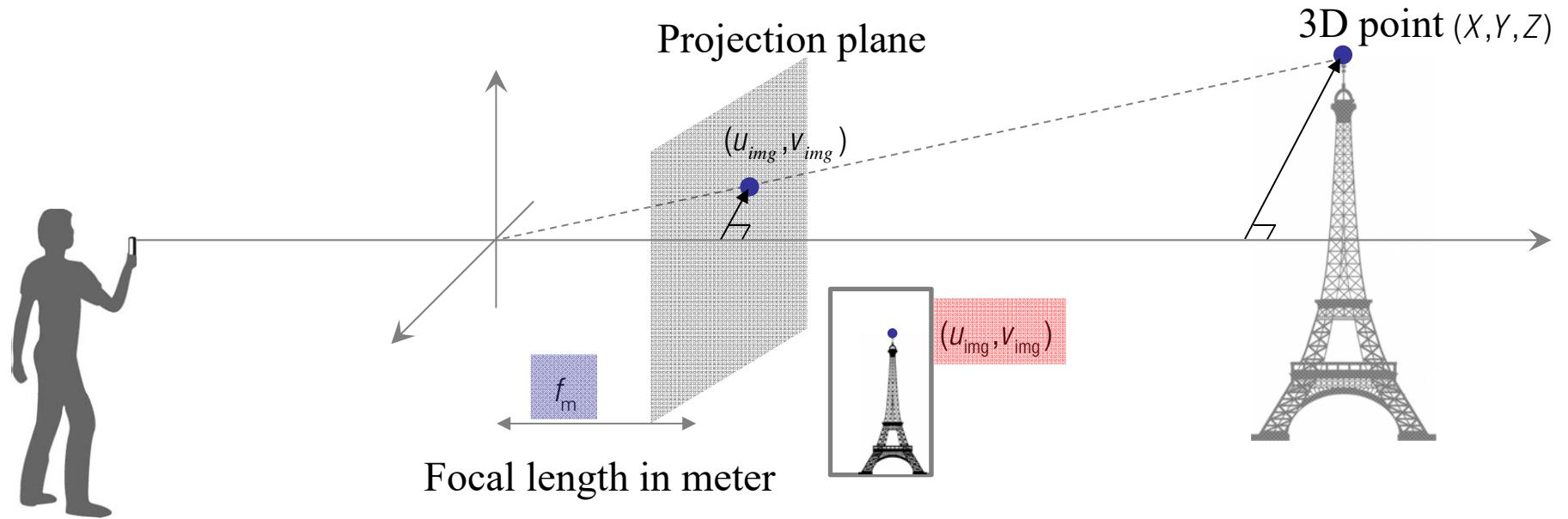
$$u_{\text{img}} = u_{\text{ccd}} \frac{w_{\text{img}}}{w_{\text{ccd}}} + p_x = f_m \frac{w_x}{w_{\text{ccd}}} \frac{X}{Z} + p_x$$

Focal length in pixel

$$v_{\text{img}} = v_{\text{ccd}} \frac{h_{\text{img}}}{h_{\text{ccd}}} + p_y = f_m \frac{h_y}{h_{\text{ccd}}} \frac{Y}{Z} + p_y$$

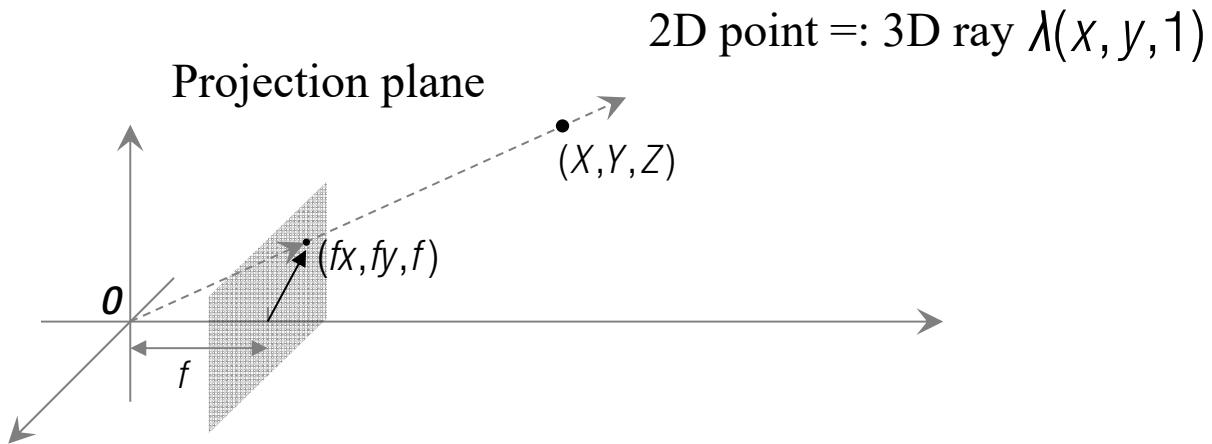
Focal length in pixel

3D Point Projection (Pixel Space)



$$(X, Y, Z) \rightarrow (u_{img}, v_{img}) = \left(f_m \frac{W_{img}}{W_{ccd}} \frac{X}{Z}, f_m \frac{h_{img}}{h_{ccd}} \frac{Y}{Z} \right)$$

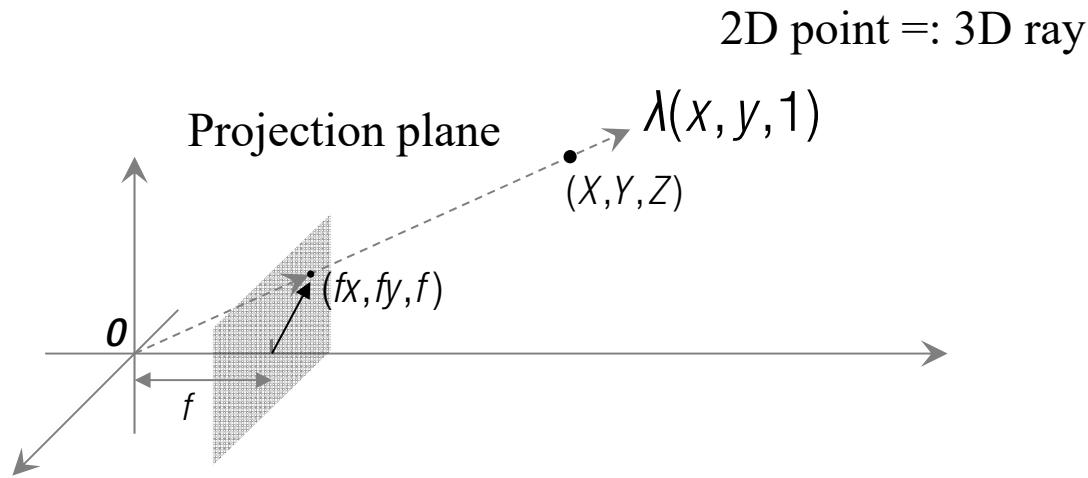
Homogeneous Coordinate



$$\begin{aligned}(x, y) &\rightarrow (x, y, 1) \\&= f(x, y, 1) \\&= \lambda(x, y, 1)\end{aligned}$$

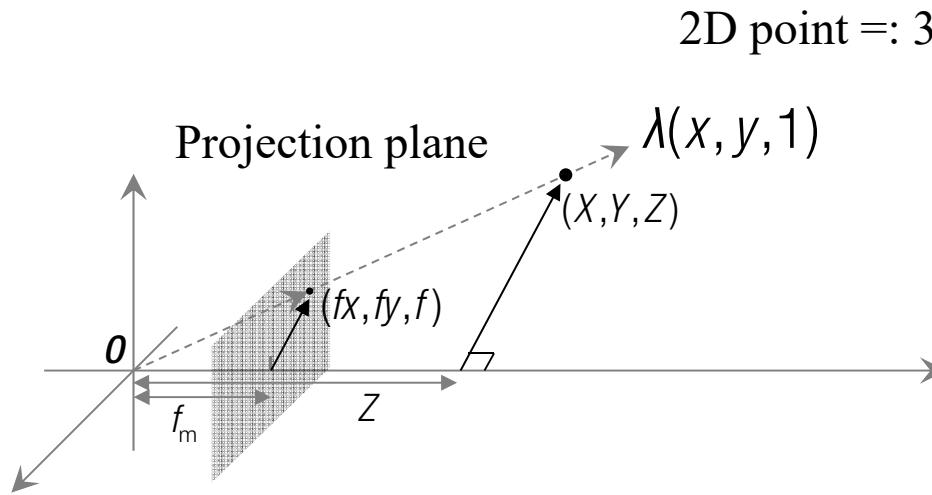
: A point in Euclidean space (\mathbb{E}^2) can be represented by a homogeneous representation in Projective space (\mathbb{P}^2) (3 numbers).

Homogeneous Coordinate



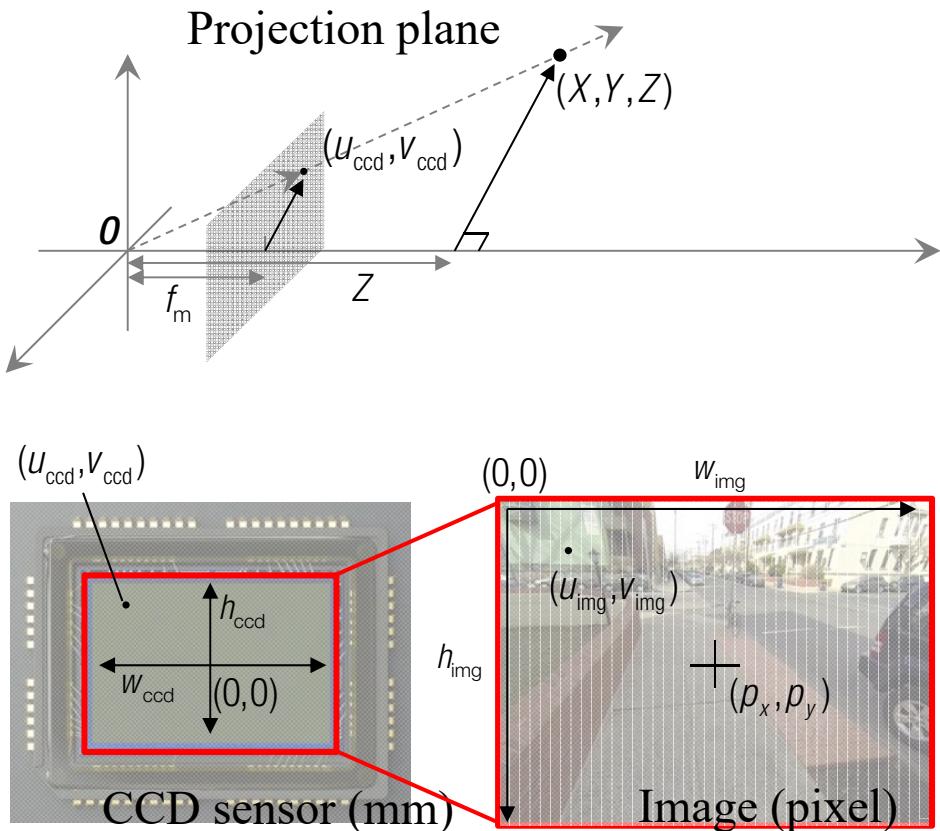
$\underline{\lambda(x, y, 1)} = (X, Y, Z)$: 3D point lies in the 3D ray passing 2D image point.
Homogeneous coordinate

3D Point Projection (Metric Space)



$$(x, y, 1) = (f_m x, f_m y, f_m) = \left(f_m \frac{X}{Z}, f_m \frac{Y}{Z}, f_m\right)$$

3D Point Projection (Pixel Space)



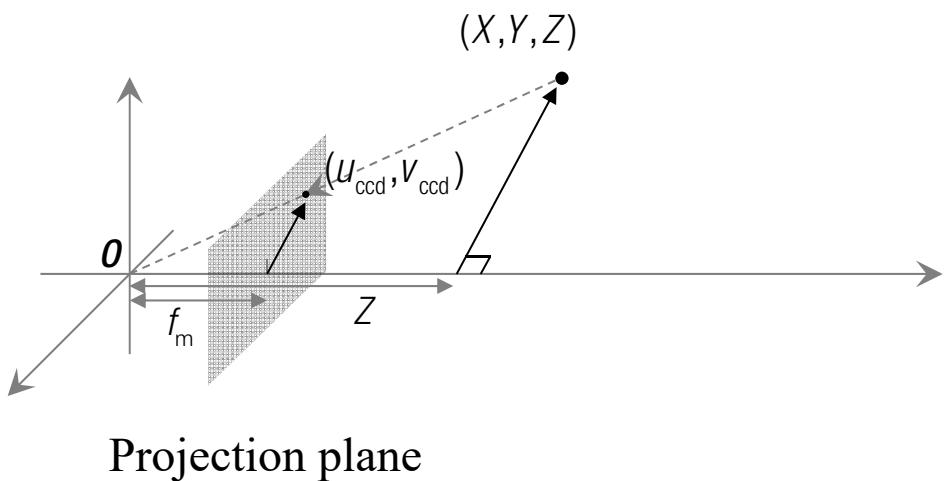
$$(X, Y, Z) \rightarrow (u_{\text{ccd}}, v_{\text{ccd}}) = (f_m \frac{X}{Z}, f_m \frac{Y}{Z})$$

$$u_{\text{img}} = f_x \frac{X}{Z} + p_x \quad v_{\text{img}} = f_y \frac{Y}{Z} + p_y$$

$$\lambda \begin{bmatrix} u_{\text{img}} \\ v_{\text{img}} \\ 1 \end{bmatrix} = \begin{bmatrix} f_x & p_x \\ f_y & p_y \\ 1 \end{bmatrix} \begin{bmatrix} X \\ Y \\ Z \end{bmatrix}$$

Homogeneous representation

Camera Intrinsic Parameter



$$\lambda \begin{bmatrix} u_{\text{img}} \\ v_{\text{img}} \\ 1 \end{bmatrix} = \begin{bmatrix} f_x & p_x \\ f_y & p_y \\ 1 & 1 \end{bmatrix} \begin{bmatrix} X \\ Y \\ Z \end{bmatrix}$$

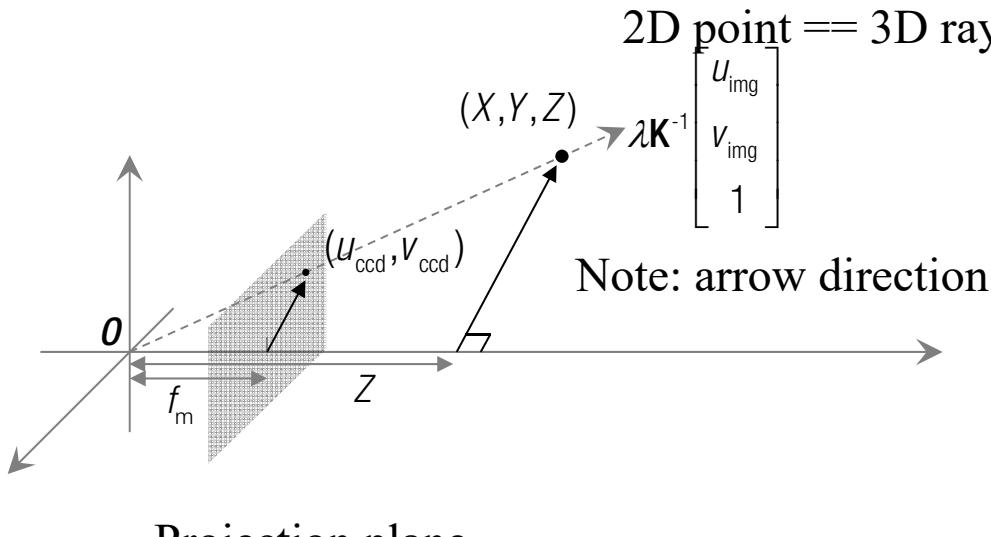
Metric space

Pixel space

A camera lens is shown next to a grid representing a sensor, illustrating the mapping from metric space to pixel space.

Camera intrinsic parameter
: metric space to pixel space

2D Inverse Projection



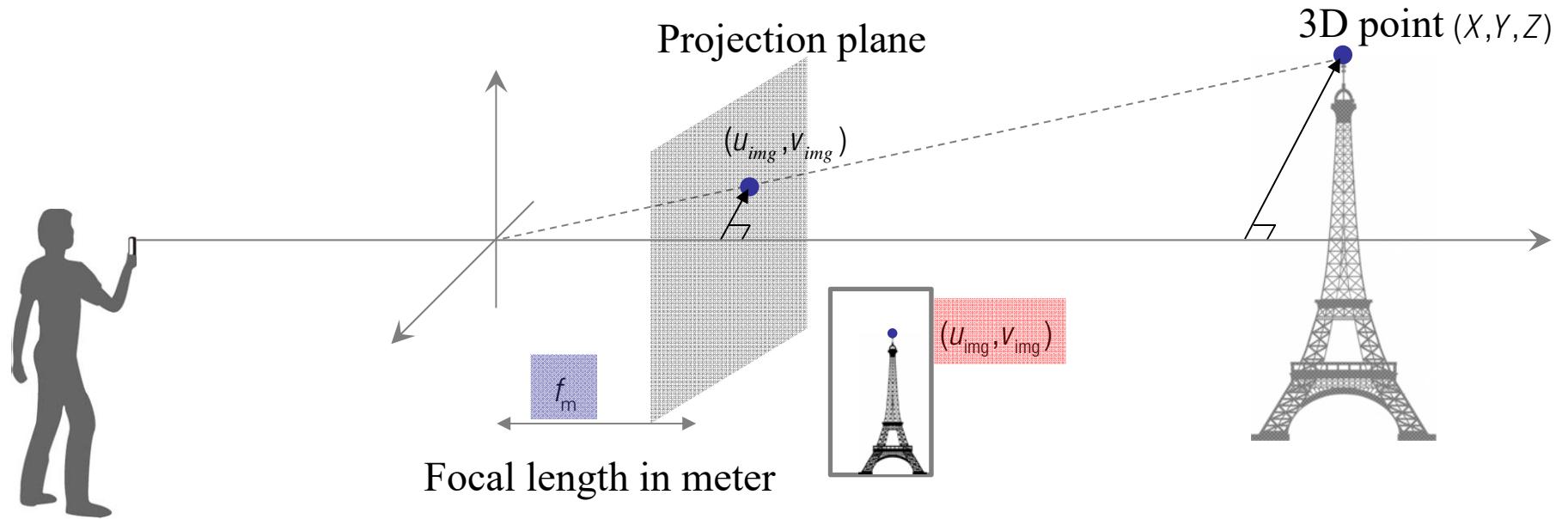
The 3D point must lie in
the *3D ray* passing through the origin and 2D image point.

$$\begin{array}{l} \text{Pixel space} \\ \lambda \begin{bmatrix} u_{\text{img}} \\ v_{\text{img}} \\ 1 \end{bmatrix} = \begin{bmatrix} f_x \\ f_y \\ \mathbf{K} \end{bmatrix} \\ \text{Metric space} \\ \begin{bmatrix} p_x \\ p_y \\ 1 \end{bmatrix} = \begin{bmatrix} X \\ Y \\ Z \end{bmatrix} \end{array}$$

$$\lambda \mathbf{K}^{-1} \begin{bmatrix} u_{\text{img}} \\ v_{\text{img}} \\ 1 \end{bmatrix} = \begin{bmatrix} X \\ Y \\ Z \end{bmatrix}$$

3D ray

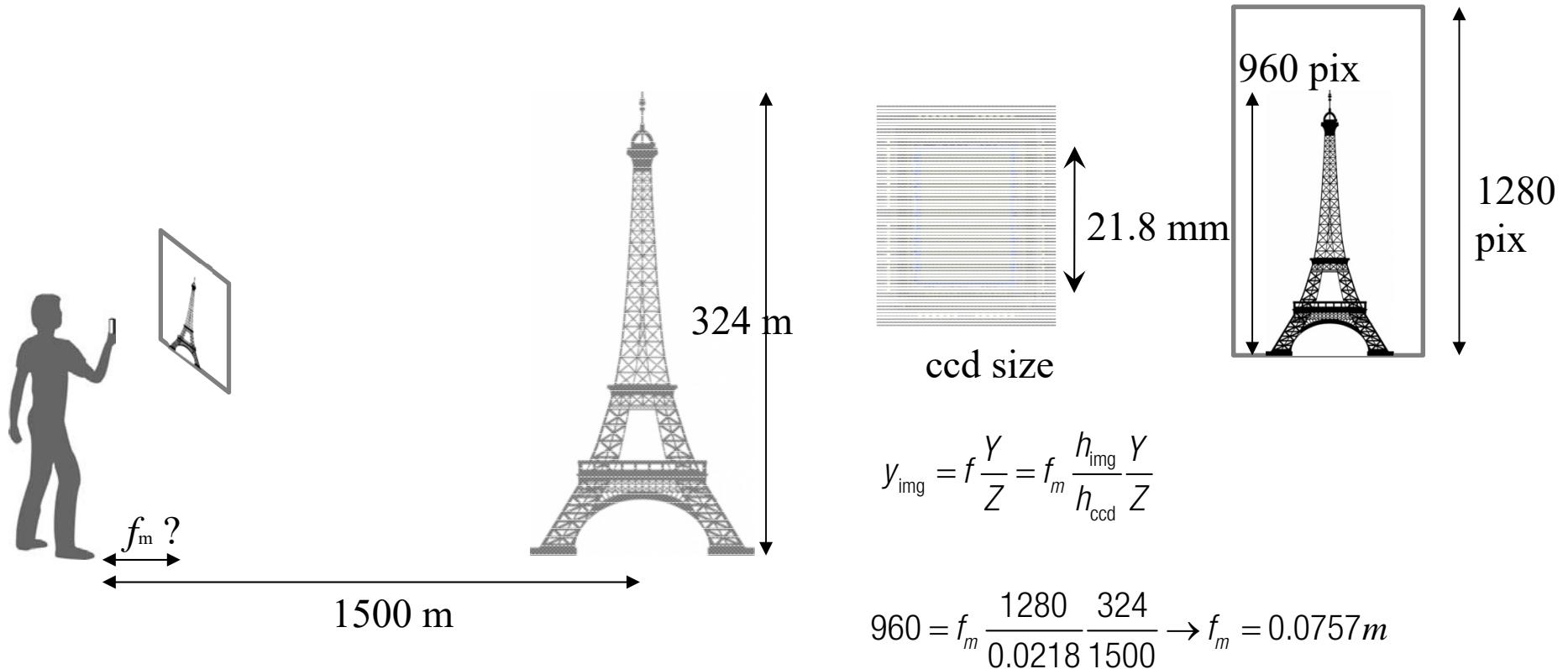
3D Point Projection (Pixel Space)



$$(X, Y, Z) \rightarrow (u_{img}, v_{img}) = \left(f_m \frac{W_{img}}{W_{ccd}} \frac{X}{Z}, f_m \frac{h_{img}}{h_{ccd}} \frac{Y}{Z} \right)$$

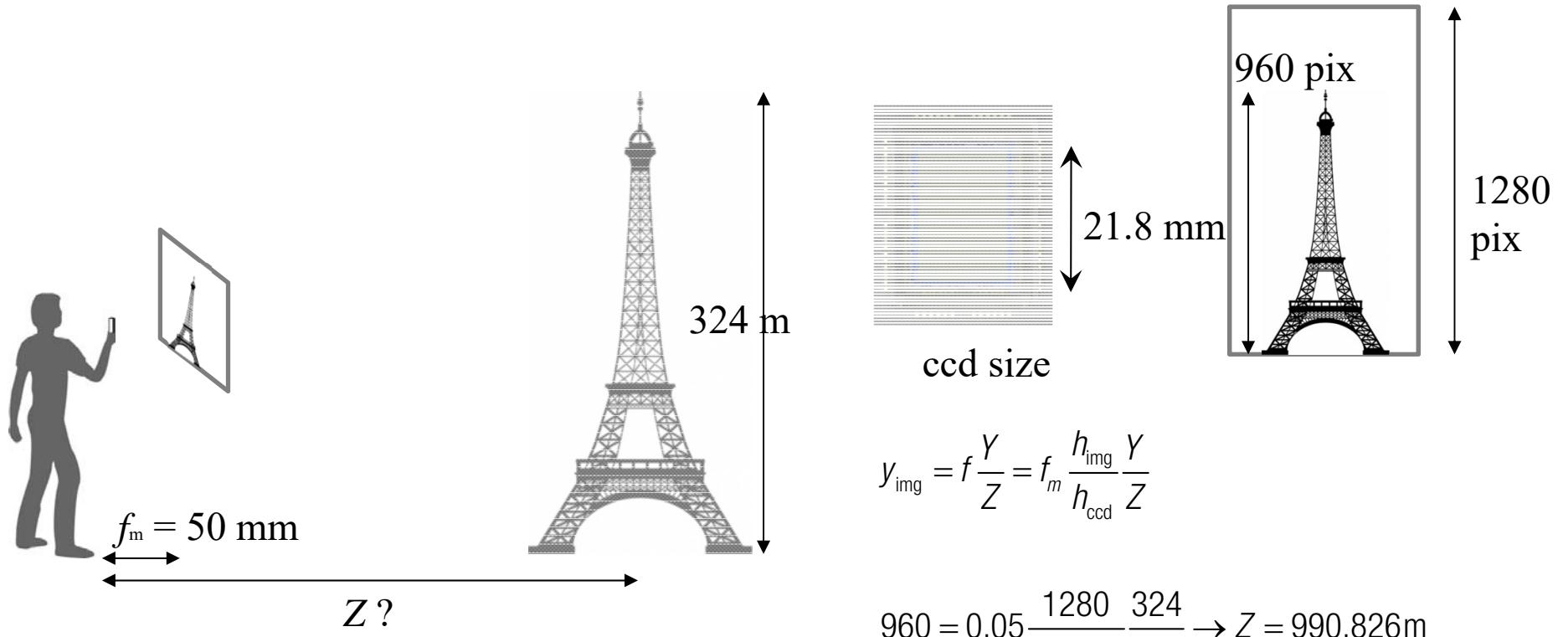
Exercise

What f to make the height of Eifel tower appear 960 pixel distance?



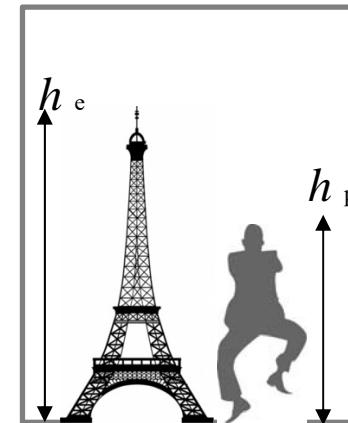
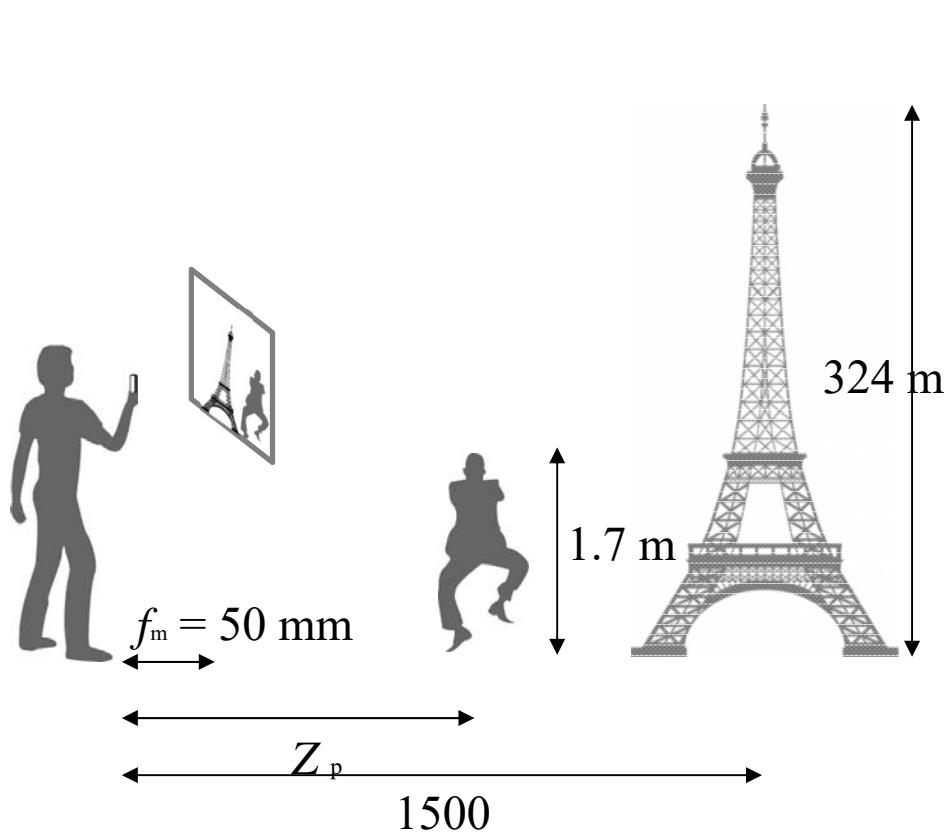
Exercise

What f to make the height of Eifel tower appear 960 pixel distance?



Exercise

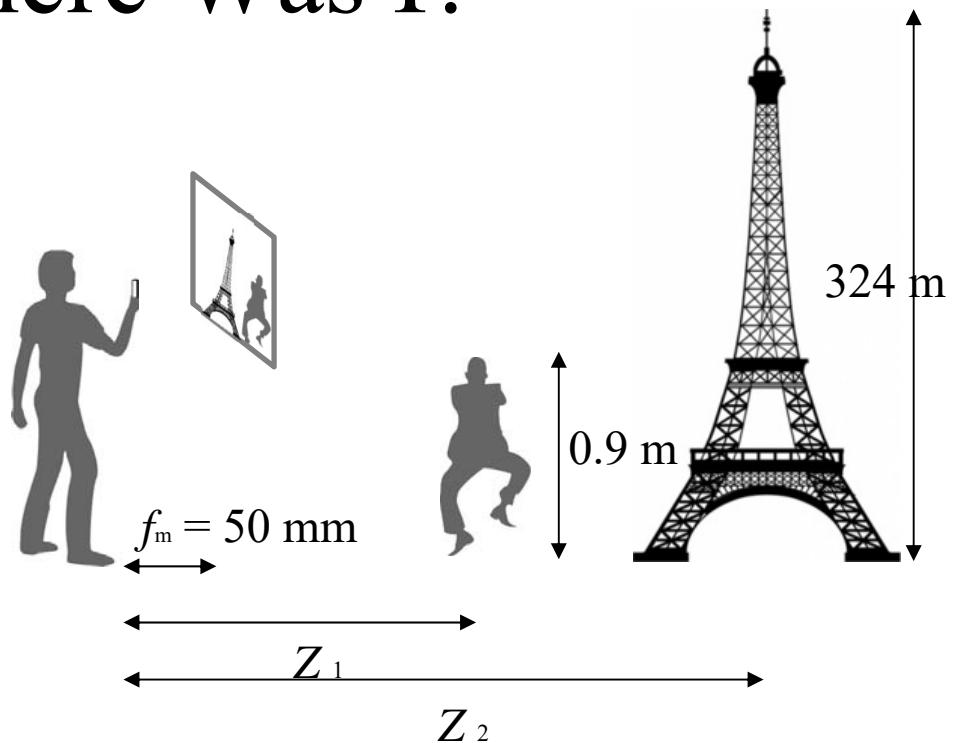
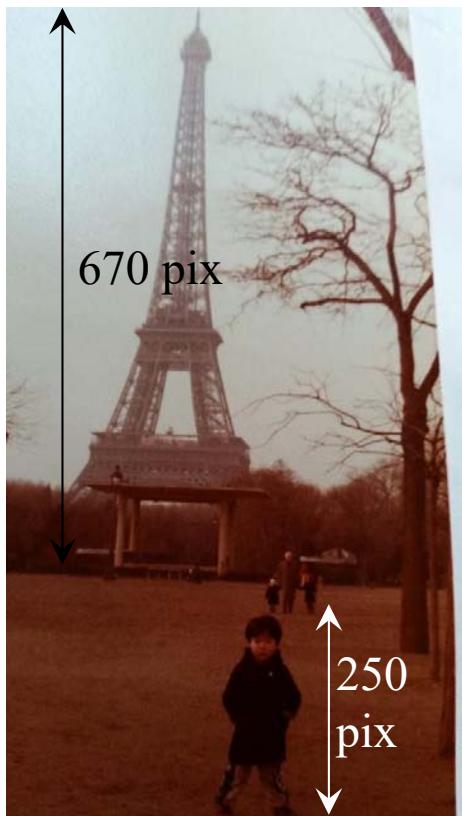
What Z_p to make the height of Eifel tower appear twice of the person?



$$h_e = f \frac{Y}{Z} \quad h_p = f \frac{Y_p}{Z_p} \quad \text{s.t.} \quad h_p = \frac{h_e}{2}$$

$$f \frac{Y_p}{Z_p} = f \frac{Y}{2Z} \rightarrow Z_p = 2 \cdot 1500 \frac{1.7}{234} = 157.41 \text{ m}$$

Where Was I?

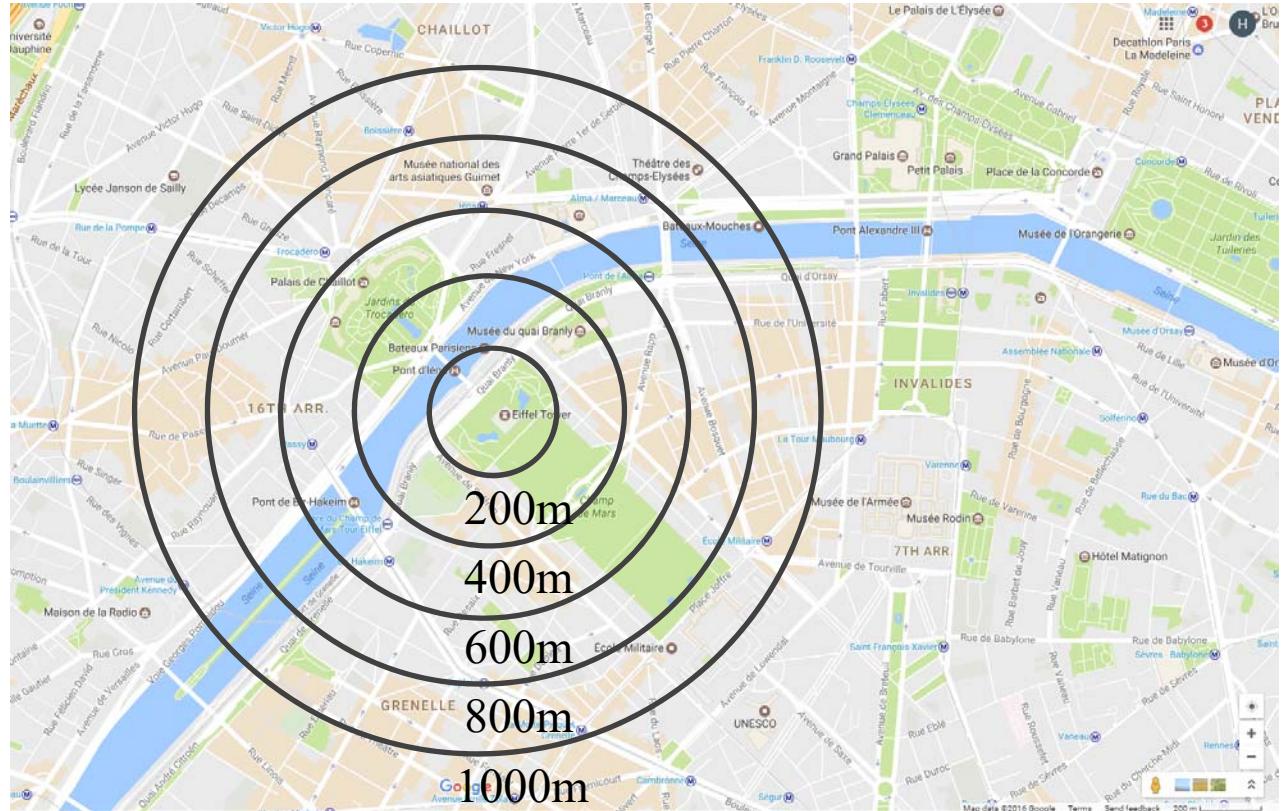


$$y_1 = f \frac{Y}{Z} = f_m \frac{h_{\text{img}}}{h_{\text{ccd}}} \frac{Y_1}{Z_1} \rightarrow Z_1 = f_m \frac{h_{\text{img}}}{h_{\text{ccd}}} \frac{Y_1}{y_1} = 0.05 \frac{1280}{0.0218} \frac{0.9}{250} = 8.03 \text{m}$$

$$y_2 = f \frac{Y_2}{Z_2} = f_m \frac{h_{\text{img}}}{h_{\text{ccd}}} \frac{Y_2}{Z_2} \rightarrow Z_2 = f_m \frac{h_{\text{img}}}{h_{\text{ccd}}} \frac{Y_2}{y_2} = 0.05 \frac{1280}{0.0218} \frac{324}{670} = 1079 \text{m}$$

Where Was I?

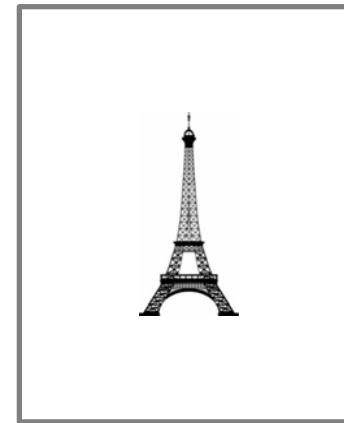
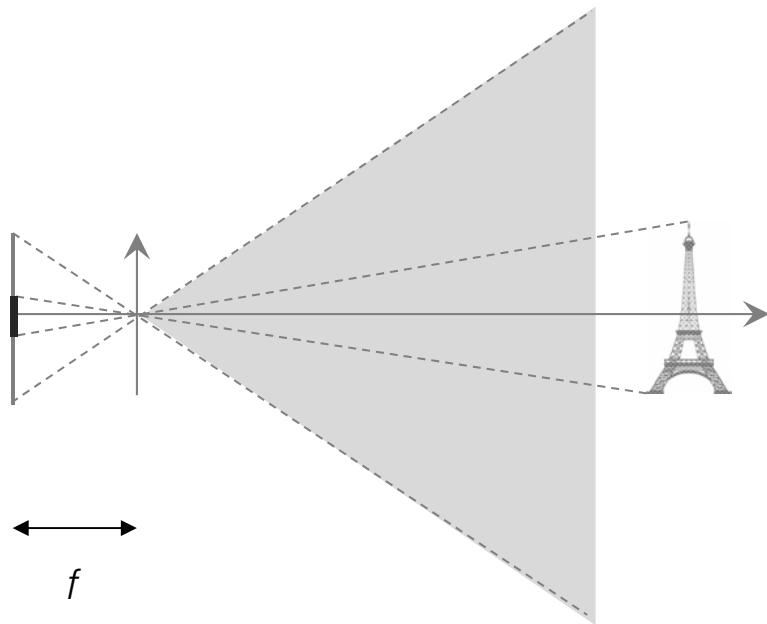
$$y_2 = f \frac{Y_2}{Z_2} = f_m \frac{h_{\text{img}}}{h_{\text{ccd}}} \frac{Y_2}{Z_2} \rightarrow Z_2 = f_m \frac{h_{\text{img}}}{h_{\text{ccd}}} \frac{Y_2}{y_2} = 0.05 \frac{1280}{0.0218} \frac{324}{670} = 1079 \text{m}$$



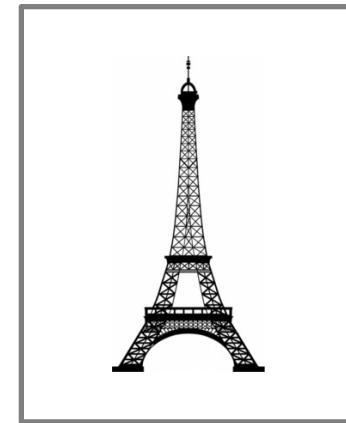
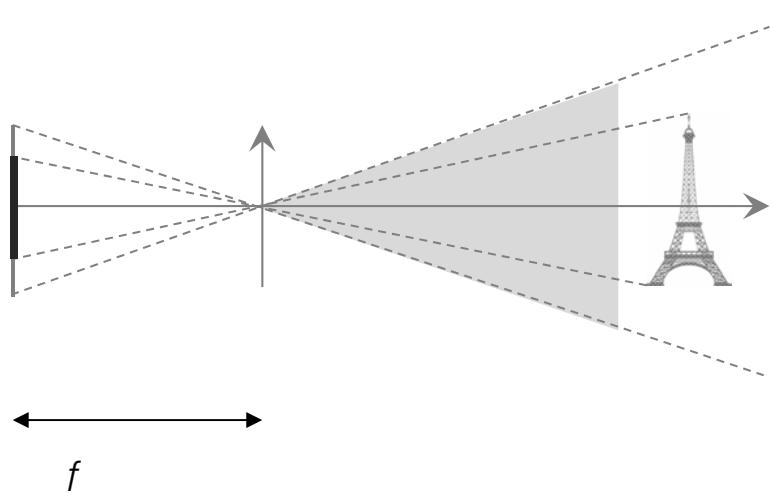
Where Was I?



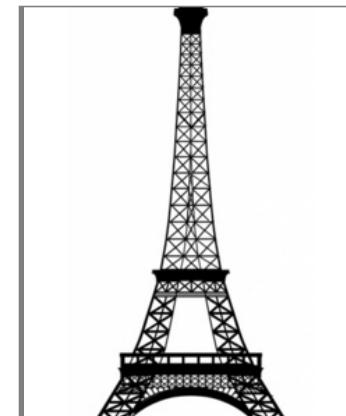
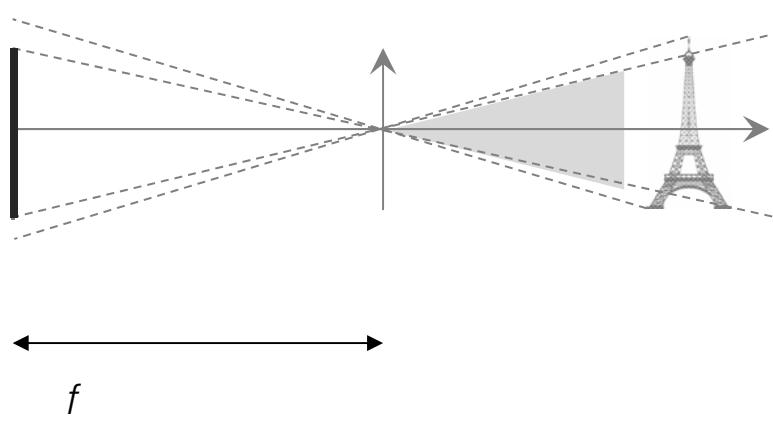
Focal Length



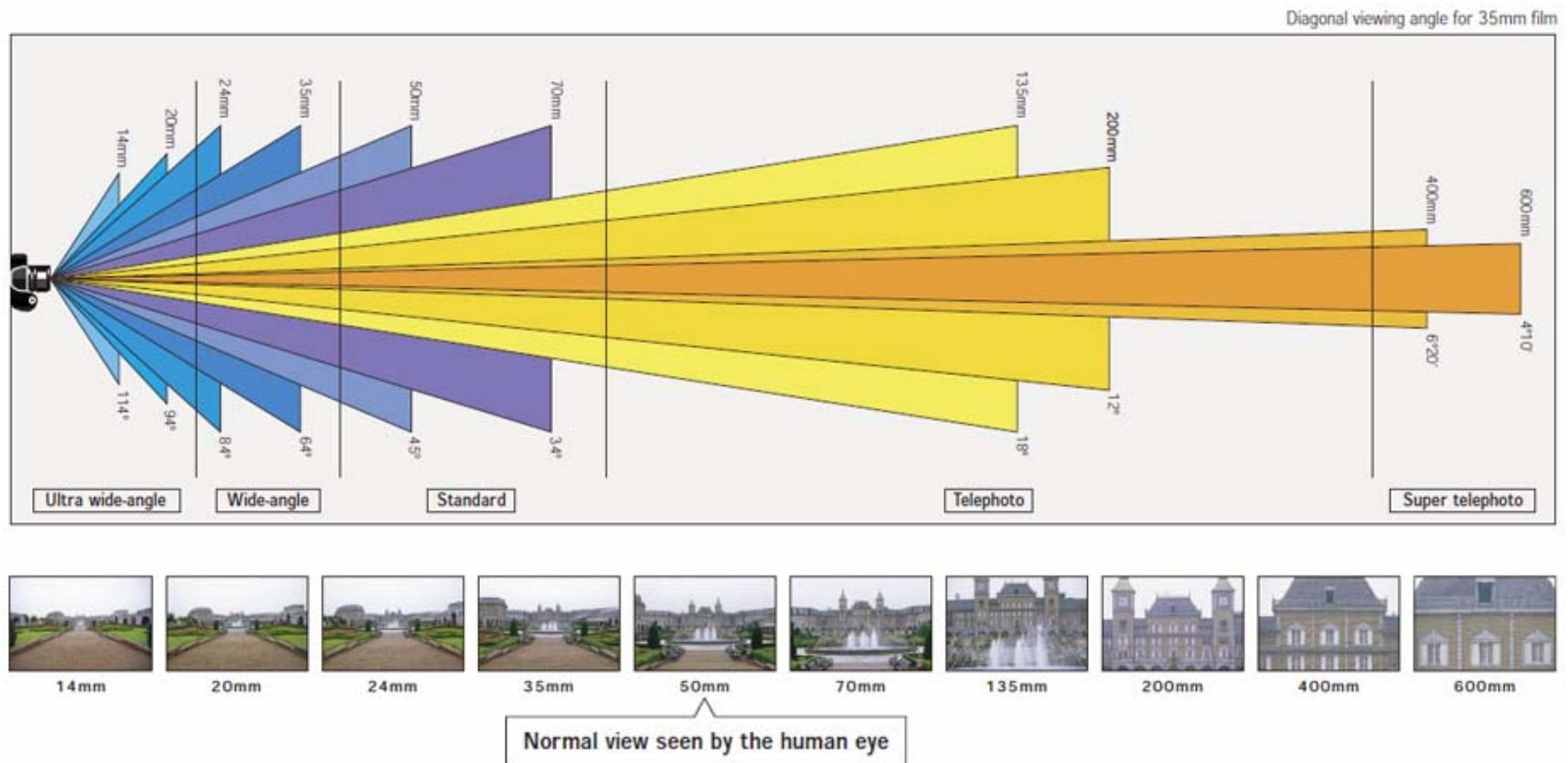
Focal Length



Focal Length



Focal Length



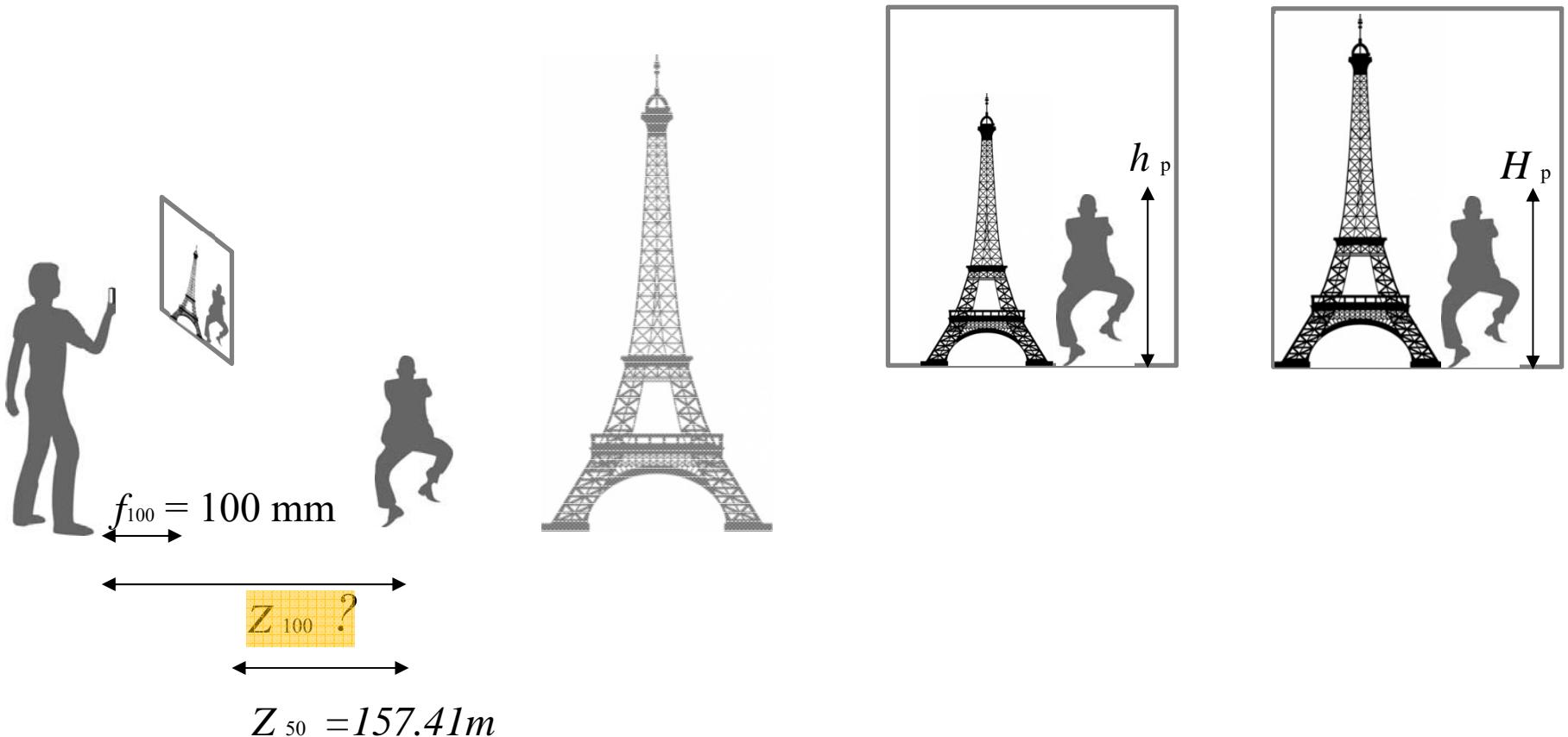
Dolly Zoom (Vertigo Effect)



(Jaws 1975)

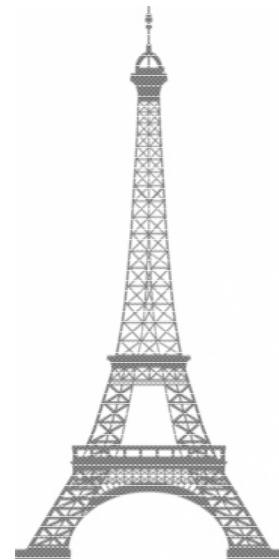
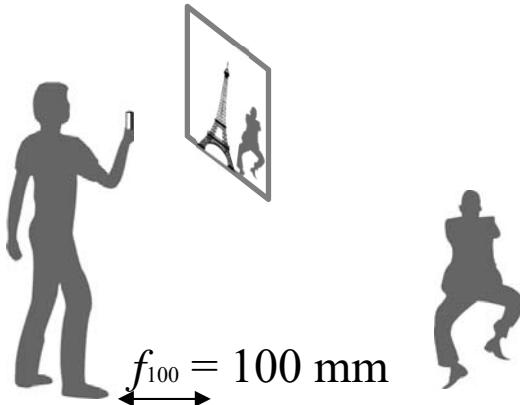
Dolly Zoom

Given focal length ($f_m=100\text{mm}$),
what Z_{100} to make the height of the person remain the same as $f_m=50\text{mm}$?



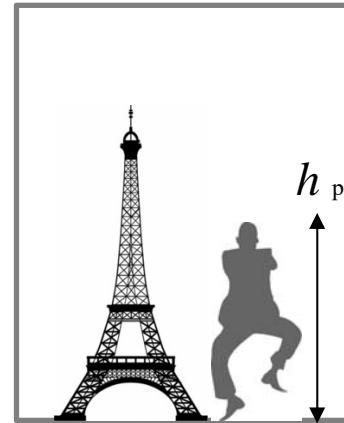
Dolly Zoom

Given focal length ($f_m=100\text{mm}$),
what Z_{100} to make the height of the person remain the same as $f_m=50\text{mm}$?

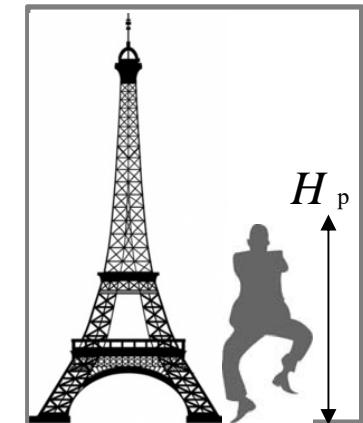


Z_{100} ?

$$Z_{50} = 157.41m$$



$$h_{50} = f_{50} \frac{Y}{Z_{50}}$$

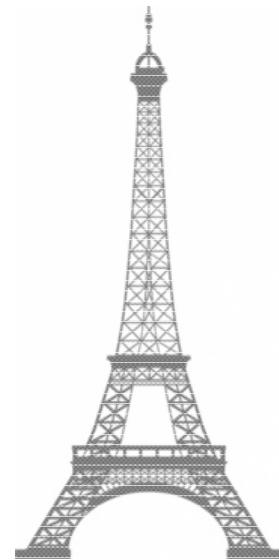
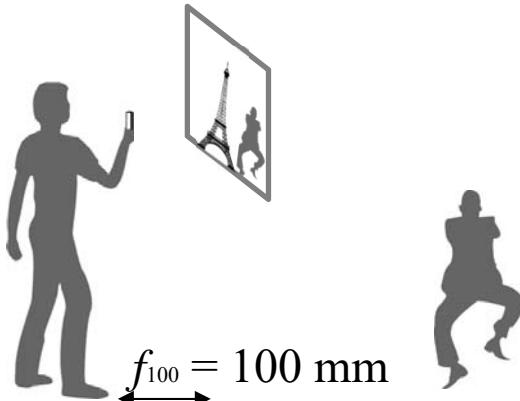


$$h_{100} = f_{100} \frac{Y}{Z_{100}}$$

s.t. $h_{100} = h_{50}$

Dolly Zoom

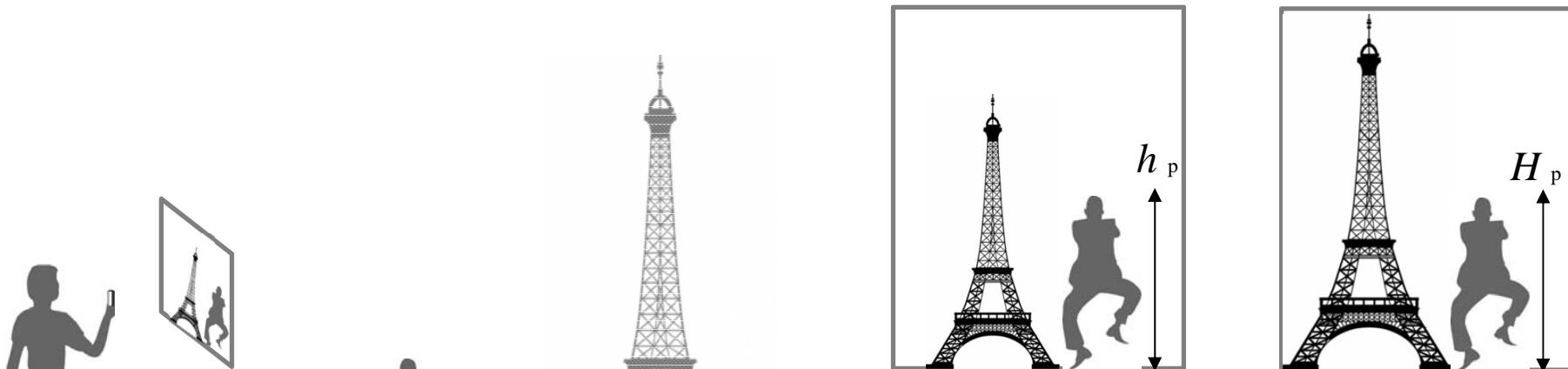
Given focal length ($f_m=100\text{mm}$),
what Z_{100} to make the height of the person remain the same as $f_m=50\text{mm}$?



$$\xrightarrow{\hspace{1cm}} Z_{100} ? \xleftarrow{\hspace{1cm}}$$

$$Z_{50} = 157.41m$$

$$Z_{100} = \frac{f_{100}}{f_{50}} Z_{50}$$



$$h_{50} = f_{50} \frac{Y}{Z_{50}}$$

$$h_{100} = f_{100} \frac{Y}{Z_{100}}$$

$$\text{s.t. } h_{100} = h_{50}$$

$$Z_{100} = \frac{100}{50} 157.41 = 314.8m$$

Dolly Zoom (Vertigo Effect)



VERTIGO (1958)