

Image Pyramid, CIS581



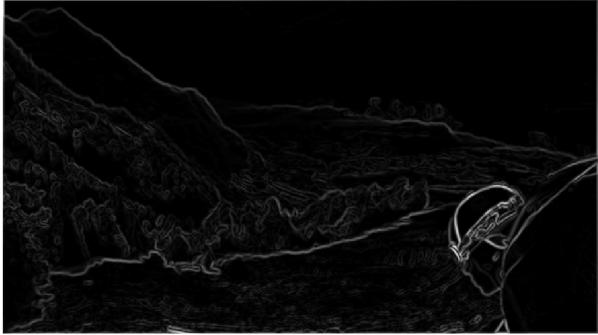




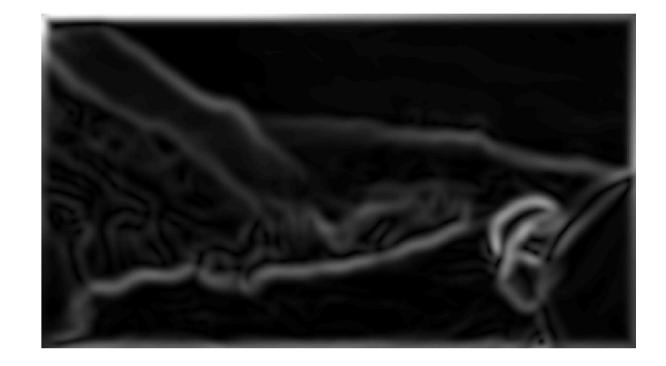


Image Scale



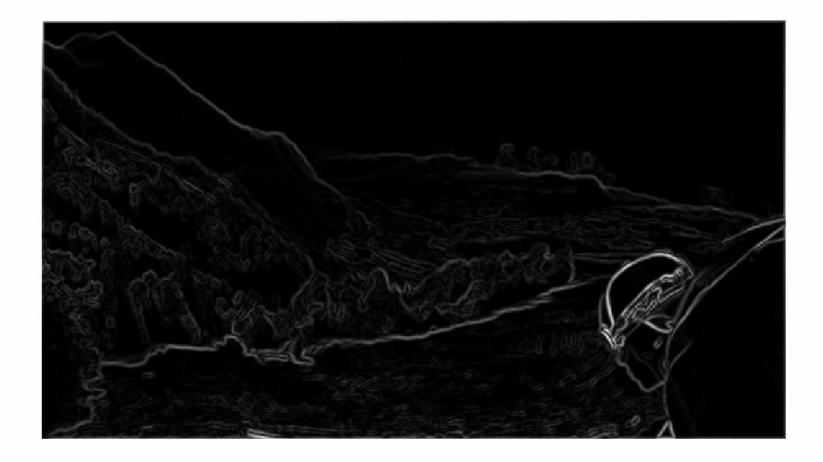






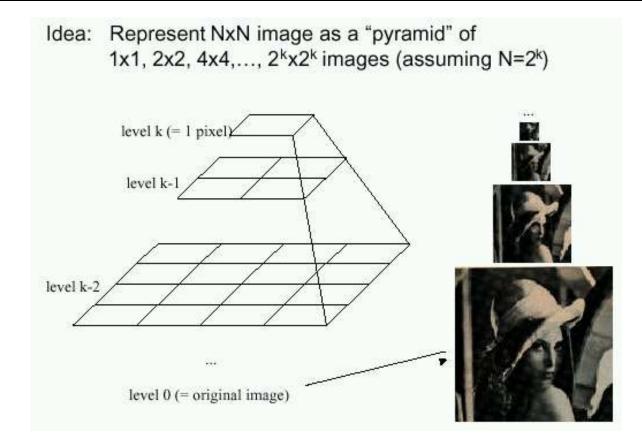






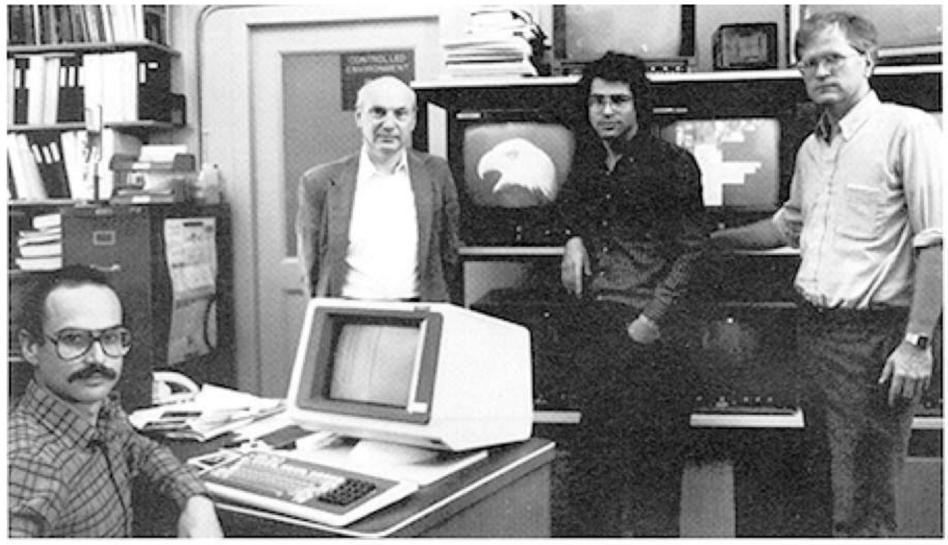
Different scale of image encodes different edge response.

Image Pyramids



Known as a Gaussian Pyramid [Burt and Adelson, 1983]

- In computer graphics, a *mip map* [Williams, 1983]
- A precursor to *wavelet transform*



Authors, left to right: Bergen, Anderson, Adelson, Burt.

A detour through scale space

Image encoding-decoding

- 1) Image statistics: pixel in neighborhood are correlated, encode per pixel value is redundant
- 2) Predictive Coding:use raster scan, predict based on pass value, and store only the error in prediction. Simple and fast

signal	10	10	20	22	24	24
prediction	10	10	10	15	21	23
error-encoded	0	0	10	7	3	1

Image encoding-decoding (part1)

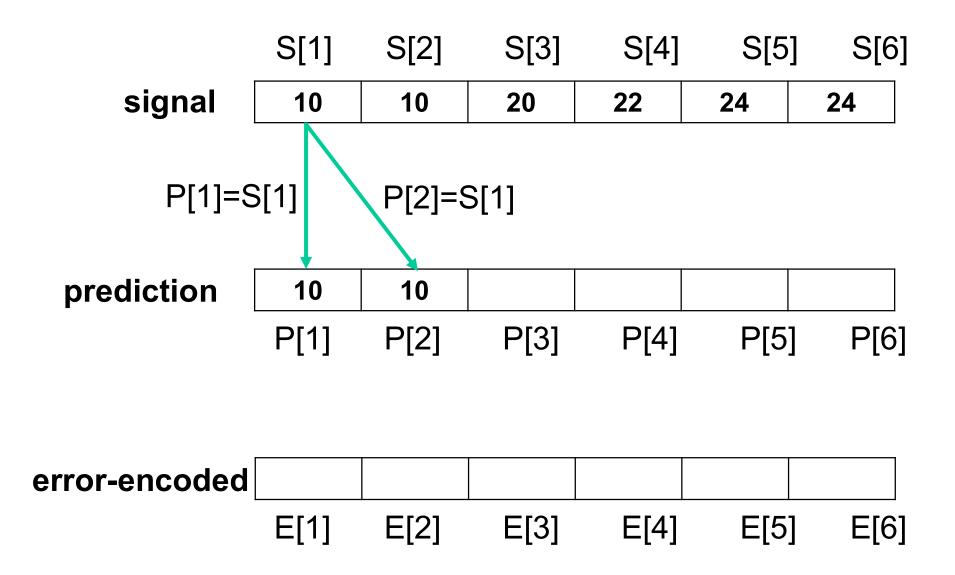


Image encoding-decoding (part2)

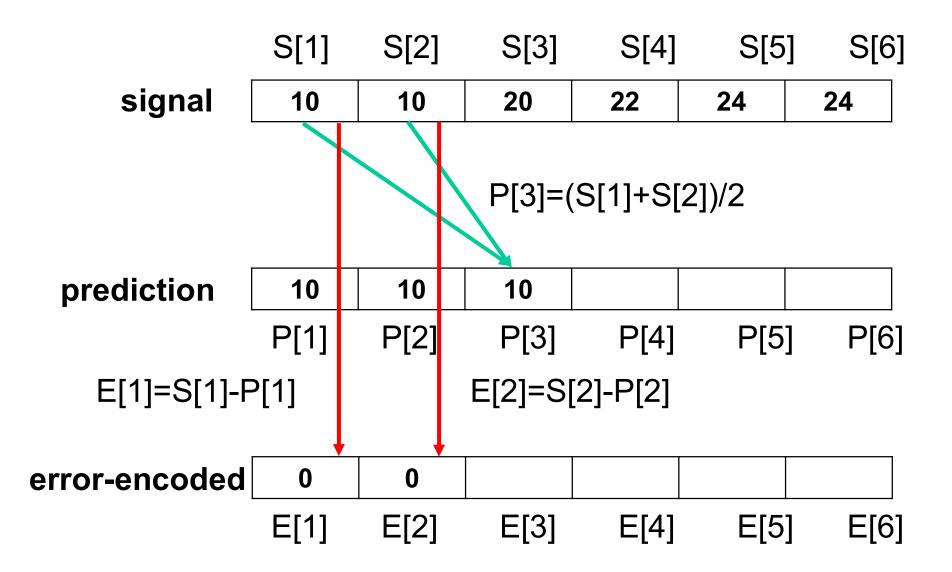


Image encoding-decoding (part2)

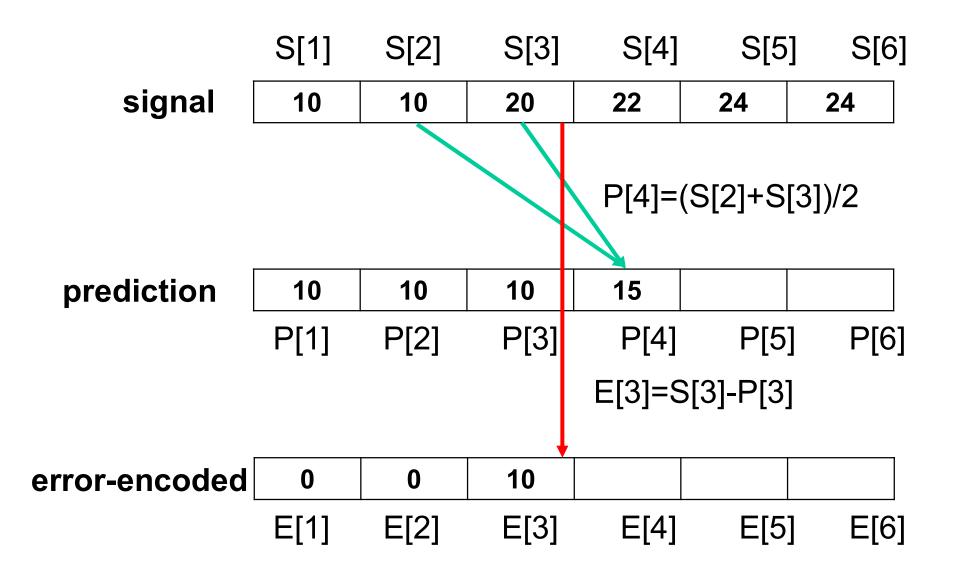
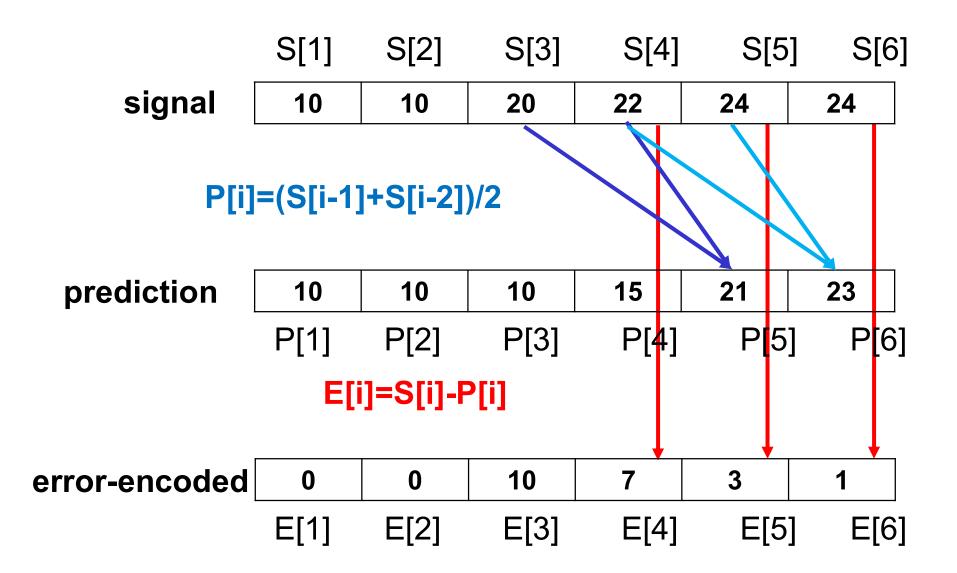
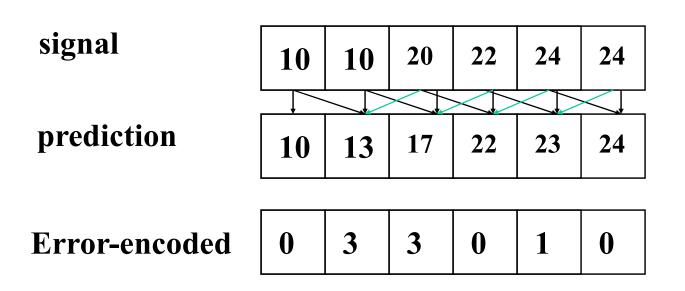


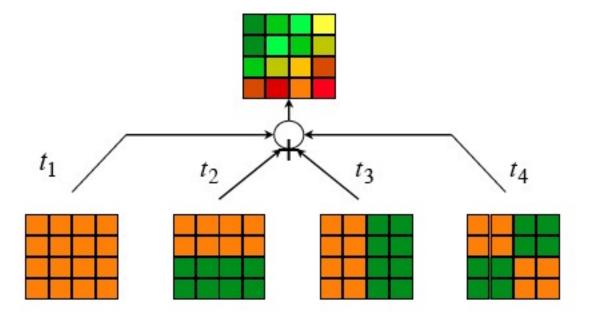
Image encoding-decoding (part3)



non-causal involves typically transform, or solution to a large sets of equations. Encode block by block. Bigger compression but slower.



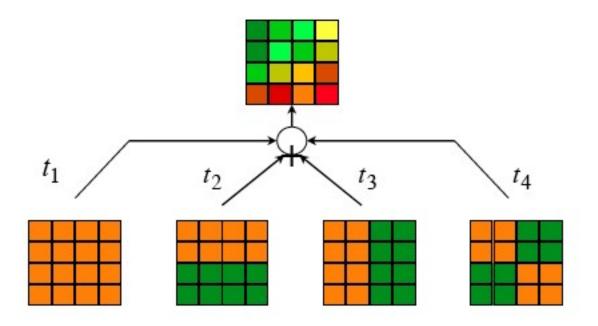
More general building blocks of image



We can have a block of pixels as a building block, "code".

Think image as made of LEGO, how to take it apart, and put it back.

More general building blocks of image



 $I = T_1 * t_1 + T_2 * t_2 + T_3 * t_3 + T_4 * t_4;$

How to estimate t_i

Coding book of DCT (discrete Cosine)

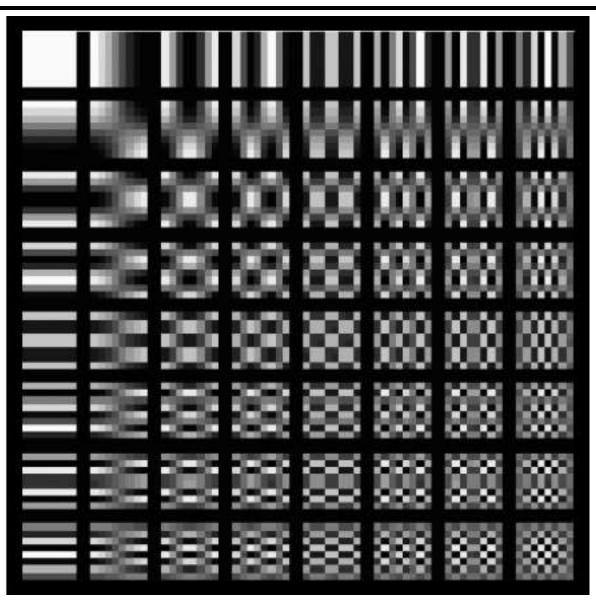
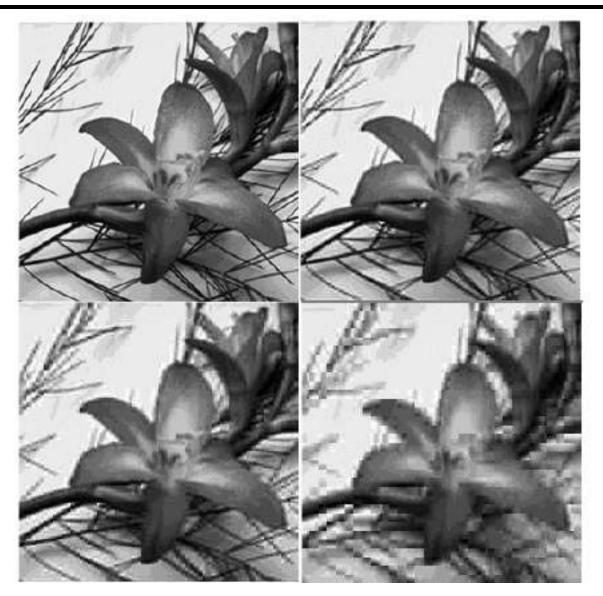


Image coding with DCT



With 16/64 Coefficients

With 4/64 Coefficients

Original

With 8/64 Coefficients

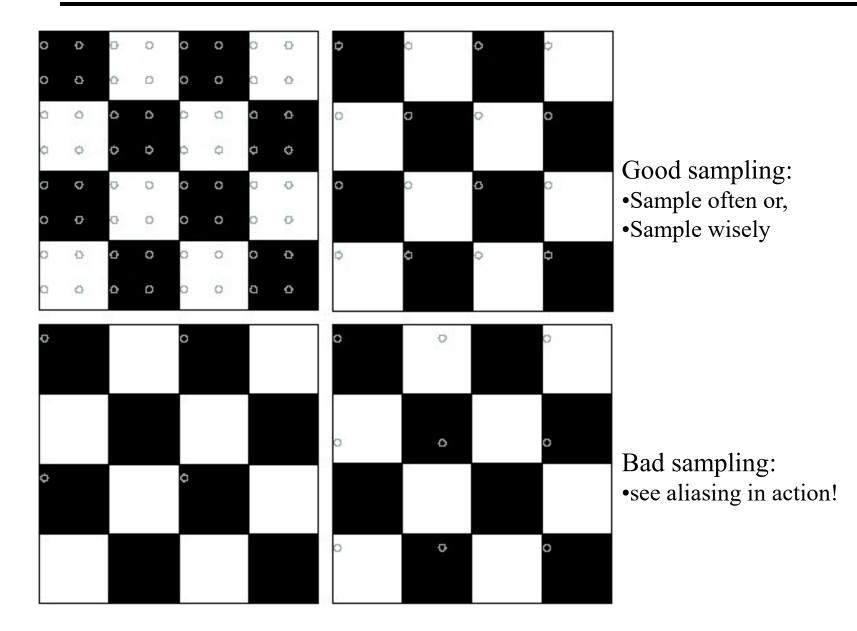
Image Pyramids



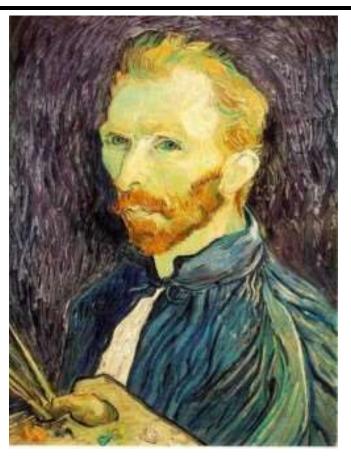
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Slides Modified from Alexei Efros, CMU,

Sampling



Gaussian pre-filtering







G 1/8

G 1/4

Gaussian 1/2

Solution: filter the image, then subsample

• Filter size should double for each $\frac{1}{2}$ size reduction. Why?

Subsampling with Gaussian pre-filtering



Gaussian 1/2

G 1/4

G 1/8

Solution: filter the image, *then* subsample

- Filter size should double for each $\frac{1}{2}$ size reduction. Why?
- How can we speed this up?

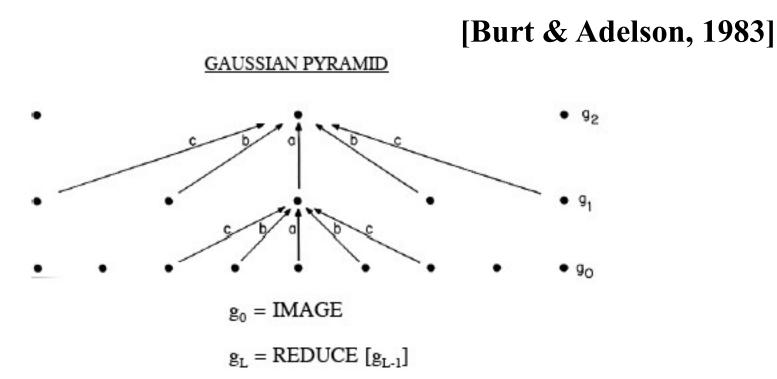
Compare with...



1/2

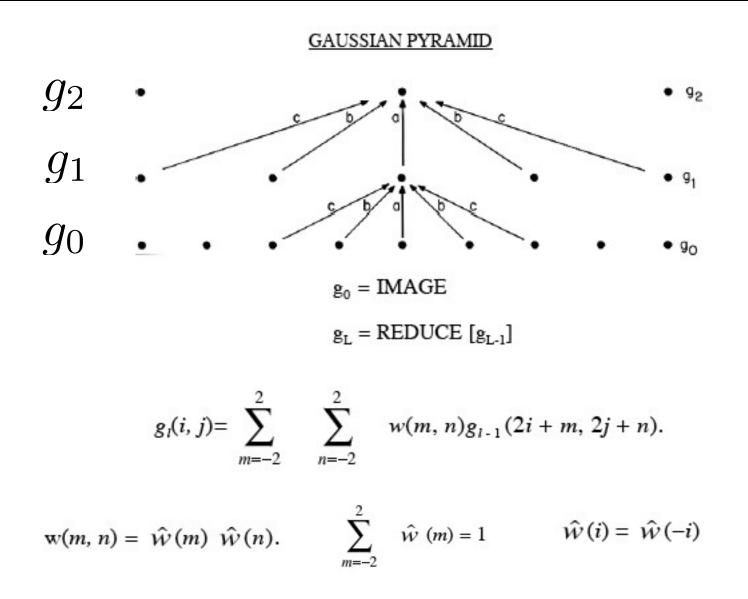
1/4 (2x zoom)

1/8 (4x zoom)

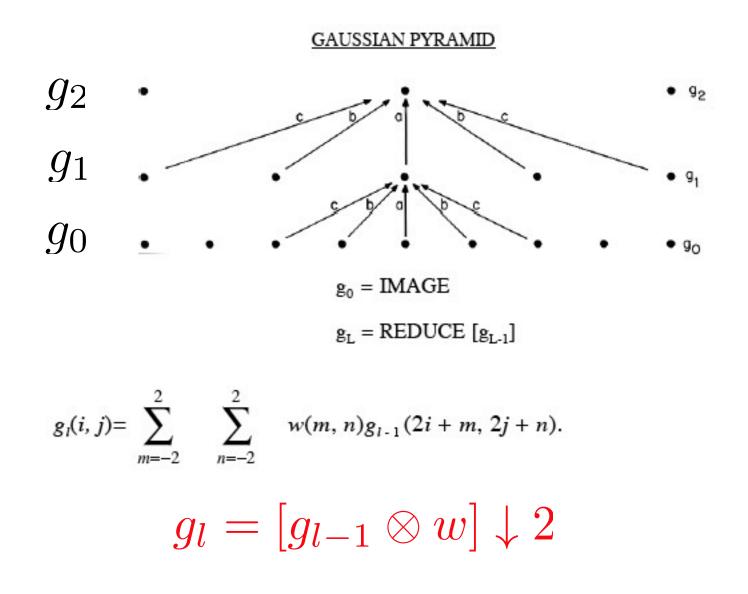


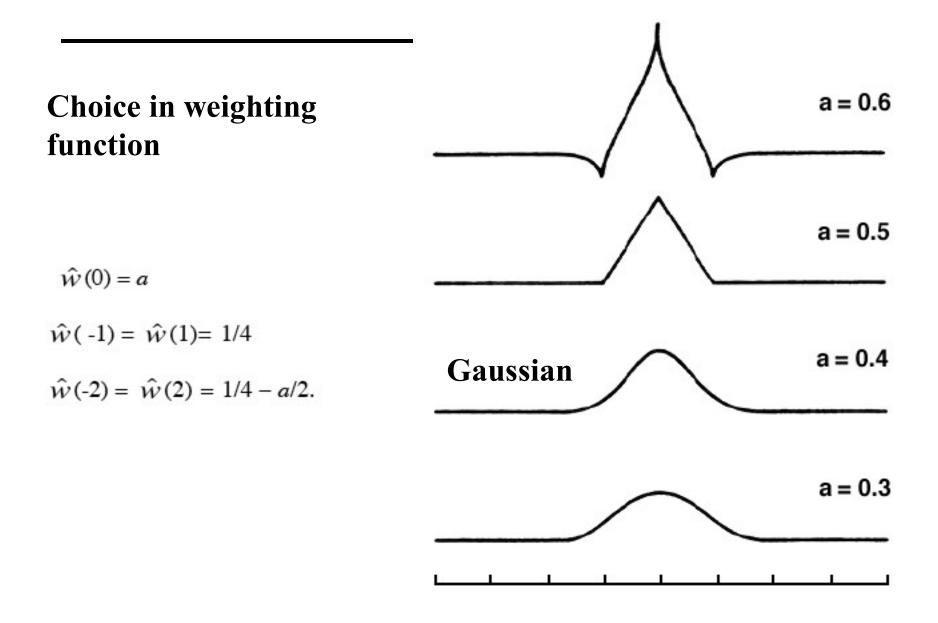
- 1) Prediction using weighted local Gaussian average
- 2) Encode the difference as the Laplacian
- 3) Both Laplacian and the Averaged image is easy to encode

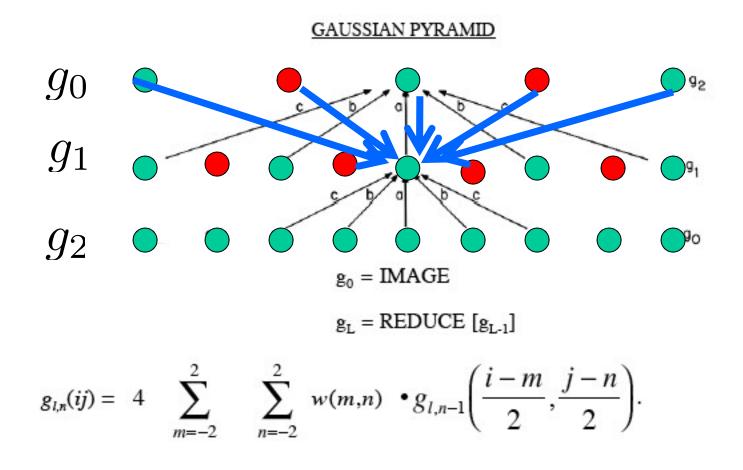
Gaussian pyramid

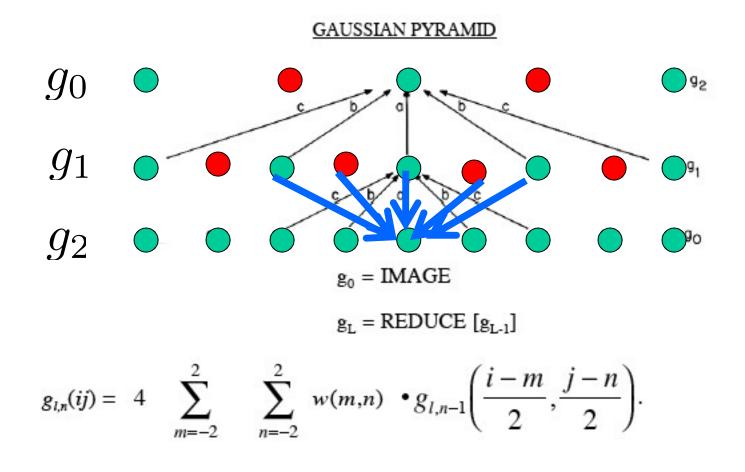


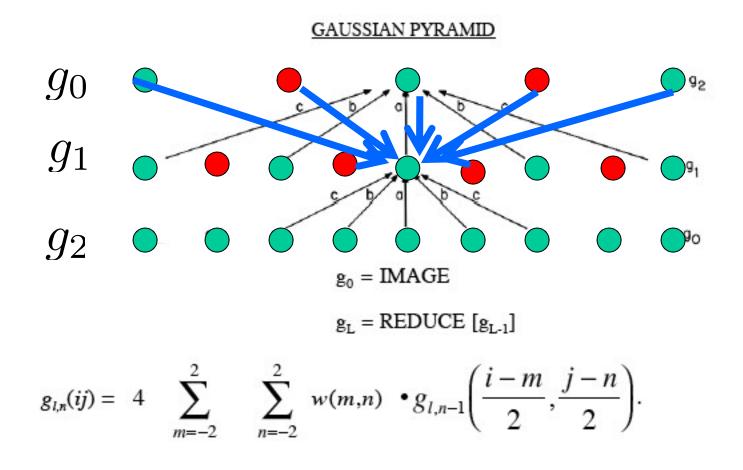
Gaussian pyramid

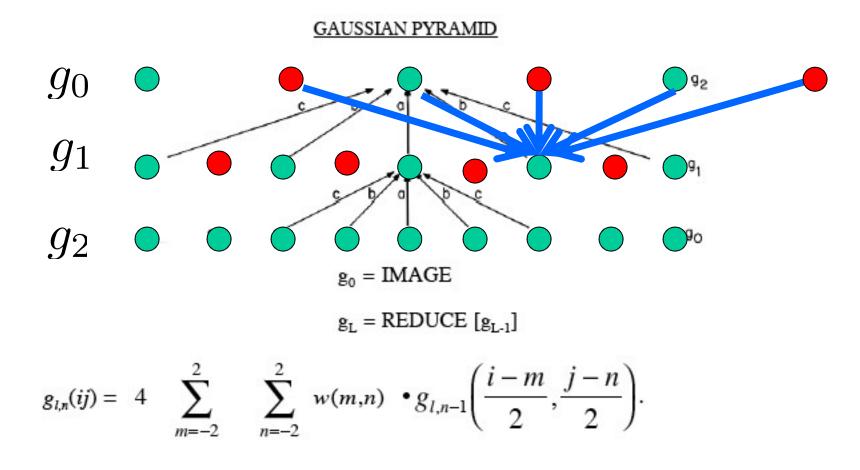




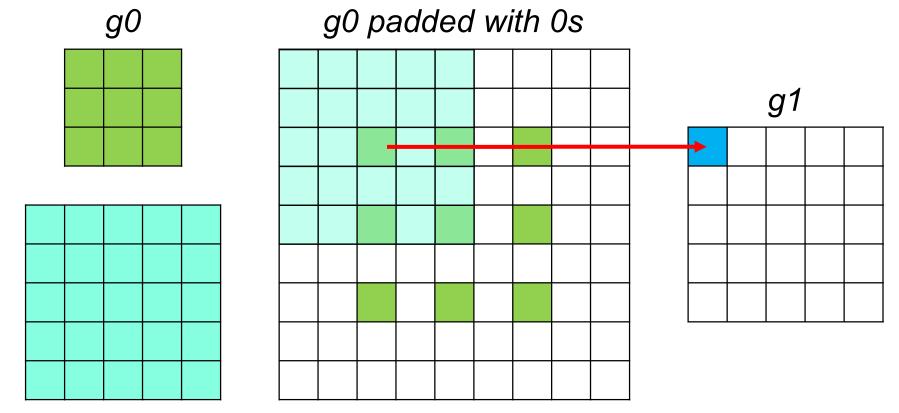




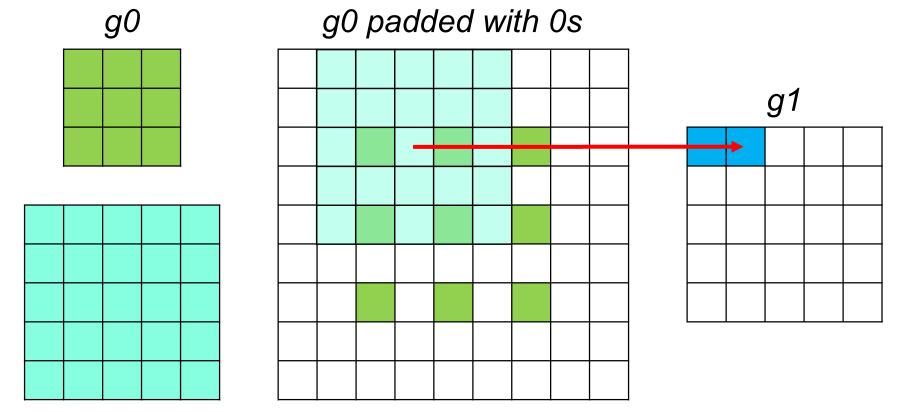




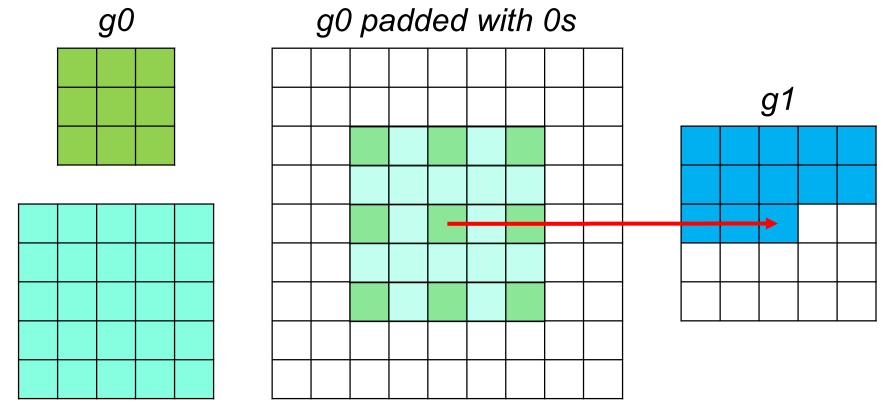
2D Image Expansion (part1)



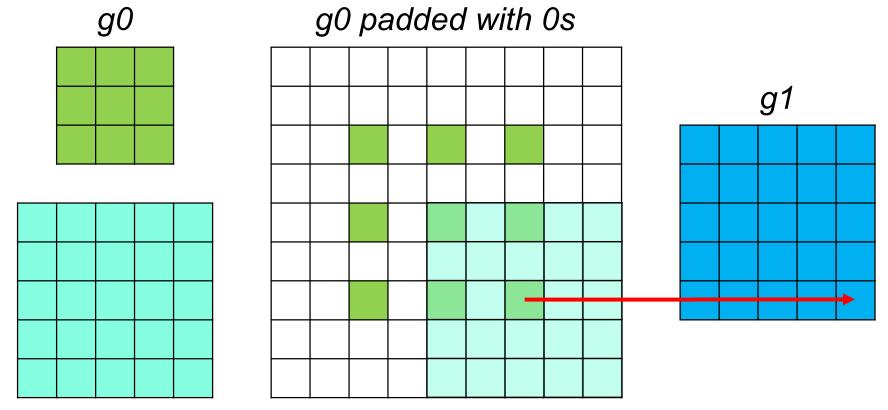
2D Image Expansion (part2)



2D Image Expansion (part3)



2D Image Expansion (part4)



What does blurring take away?



original

What does blurring take away?



smoothed (5x5 Gaussian)

High-Pass filter



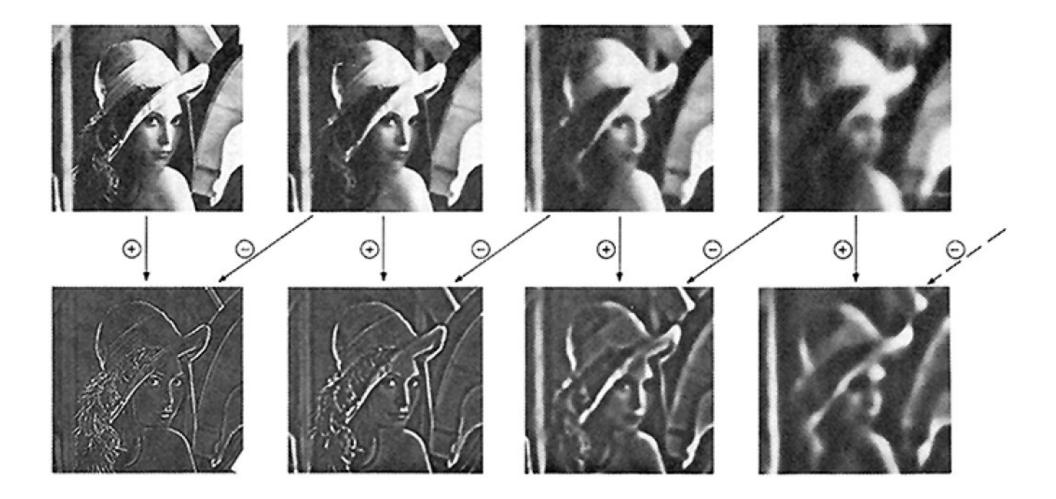
smoothed – original





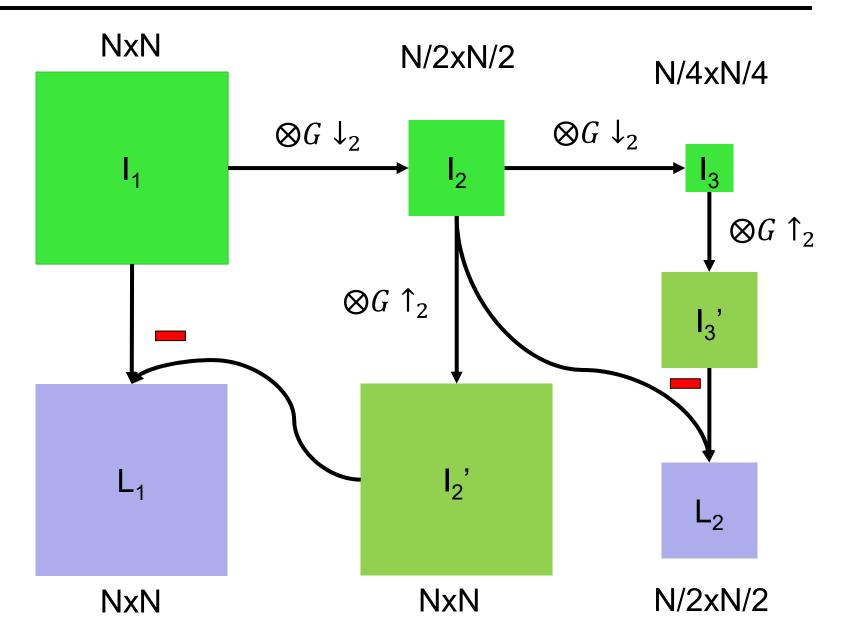
Laplacian Image

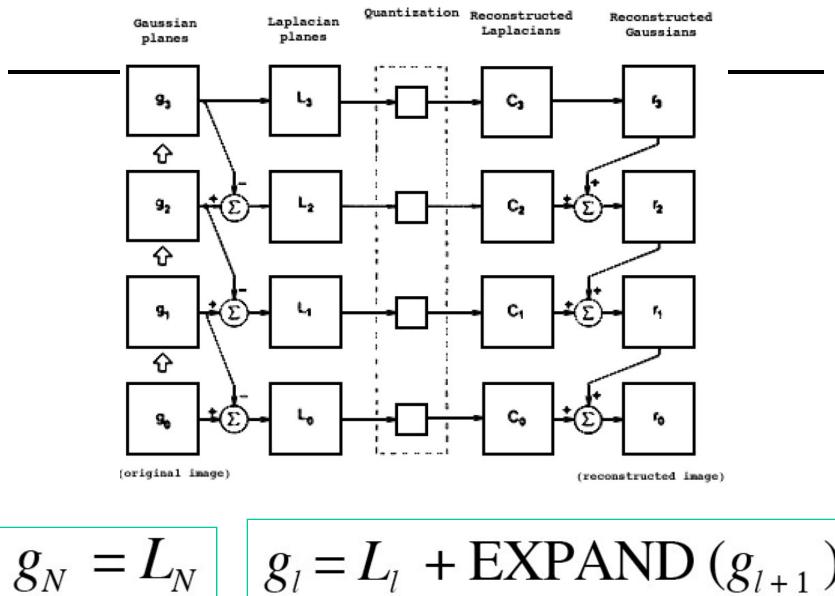
$$L_l = g_l - \text{EXPAND} \left(g_{l+1} \right)$$



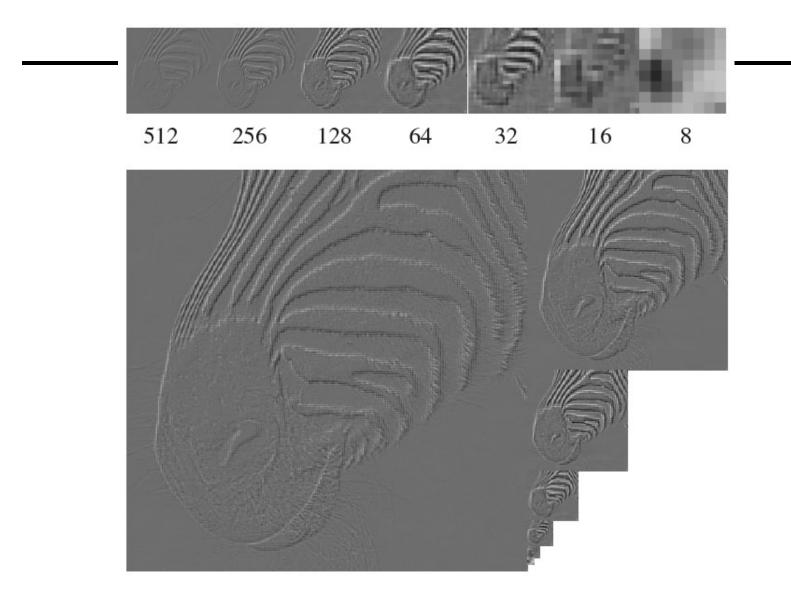
Gaussian pyramid is smooth=> can be subsampled Laplacian pyramid has narrow band of frequency=> compressed

Pyramid extraction of Laplacian

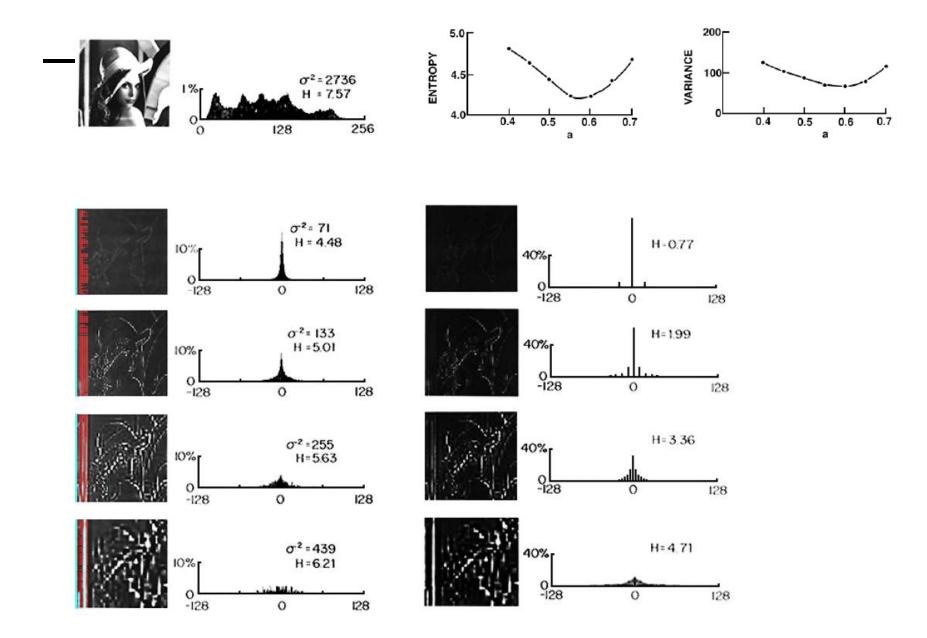




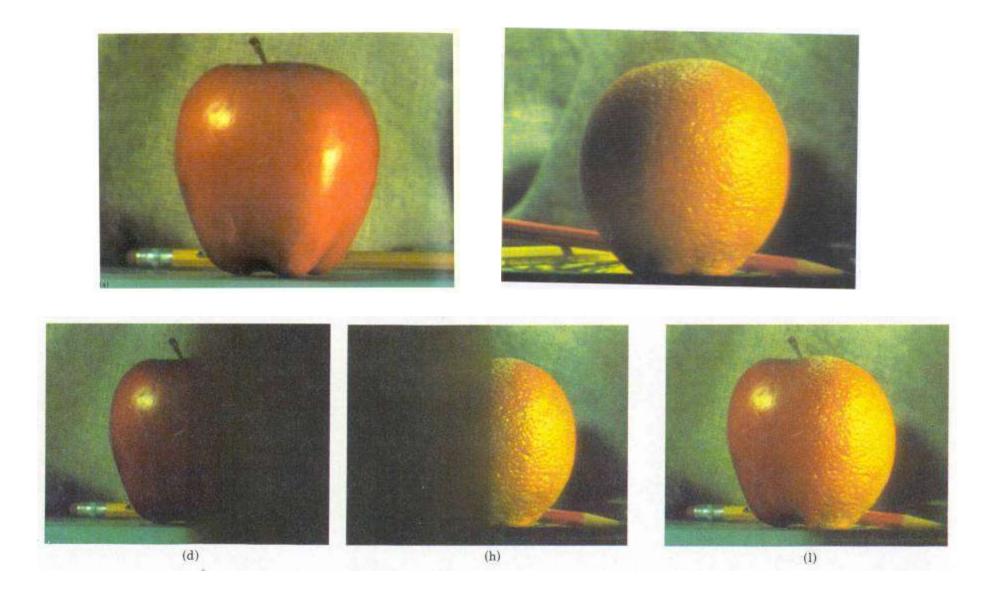
$$= L_N \quad g_l = L_l + \text{EXPAND} (g_{l+1})$$

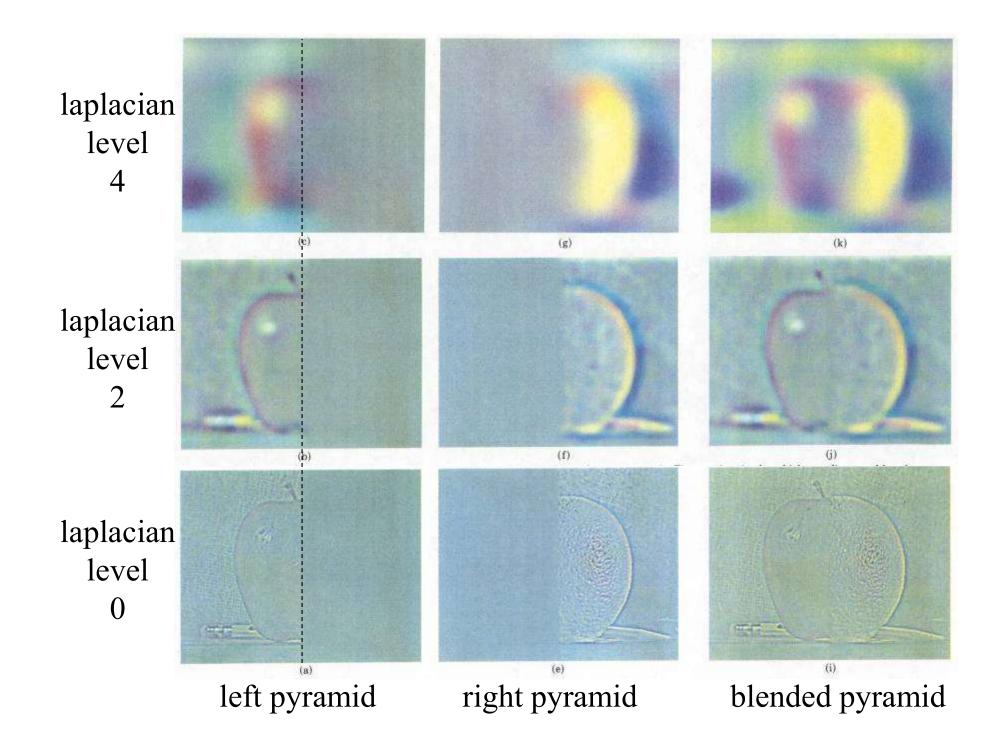


Ln = Gn



Pyramid Blending





Laplacian Pyramid: Blending

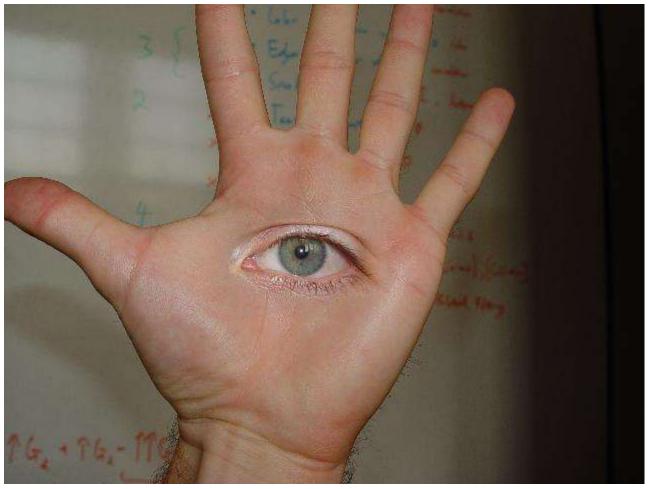
General Approach:

- 1. Build Laplacian pyramids LA and LB from images A and B
- 2. Build a Gaussian pyramid *GR* from selected region *R*
- 3. Form a combined pyramid *LS* from *LA* and *LB* using nodes of *GR* as weights:
 - LS(i,j) = GR(I,j,)*LA(I,j) + (1-GR(I,j))*LB(I,j)
- 4. Collapse the *LS* pyramid to get the final blended image

Blending Regions



Horror Photo



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