





Image filtering

$$g[m, n] = \sum_{k, l} I(m + k, n + l) * f(k, l)$$

Image I 8x8

Kernel f
3x3

Output g

1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

1	2	3
4	5	6
7	8	9

28	39	39	39	39	39	39	24
33	45	45	45	45	45	45	27
33	45	45	45	45	45	45	27
16	21	21	21	21	21	21	12
5	6	6	6	6	6	6	3
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

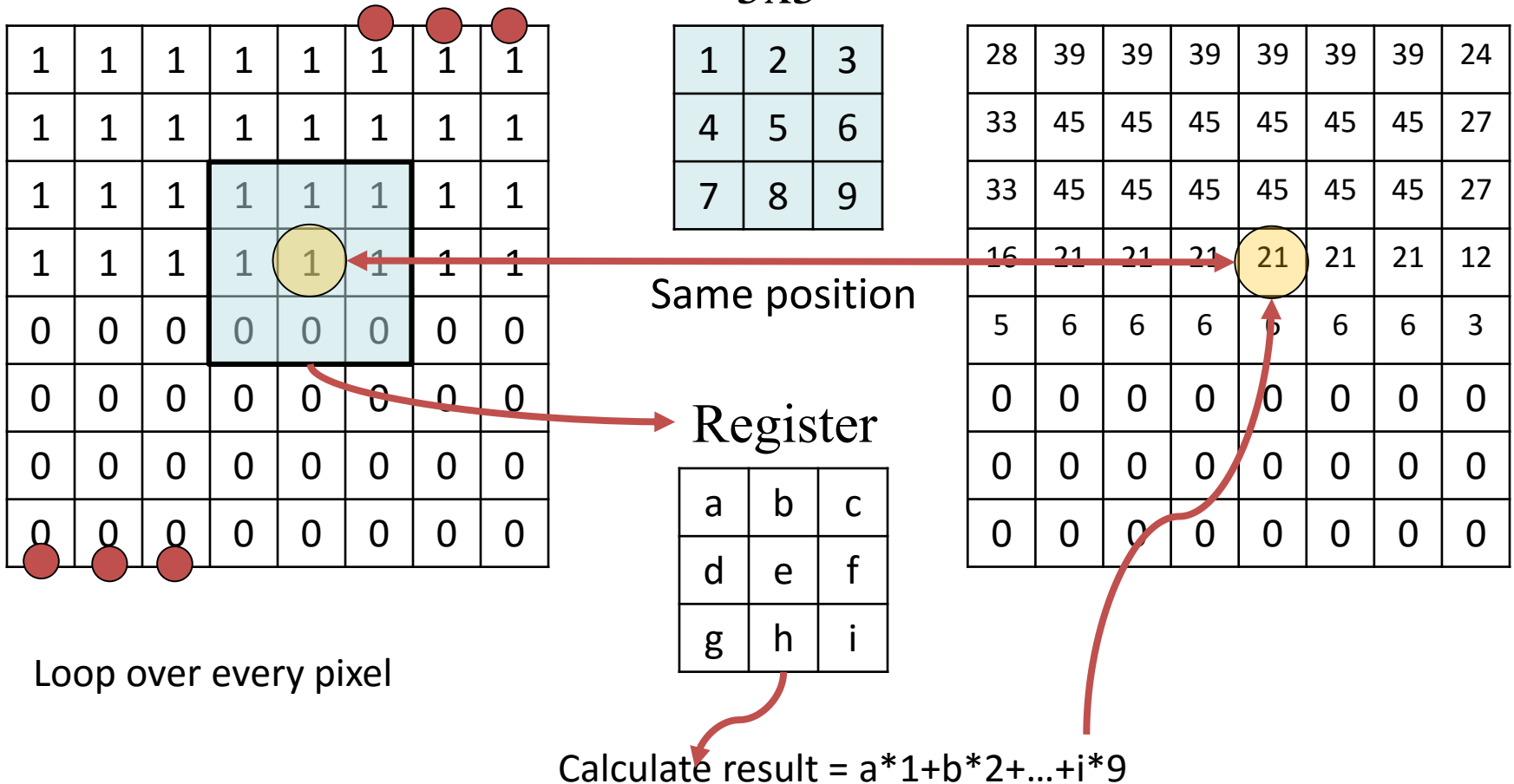
Same position

Register

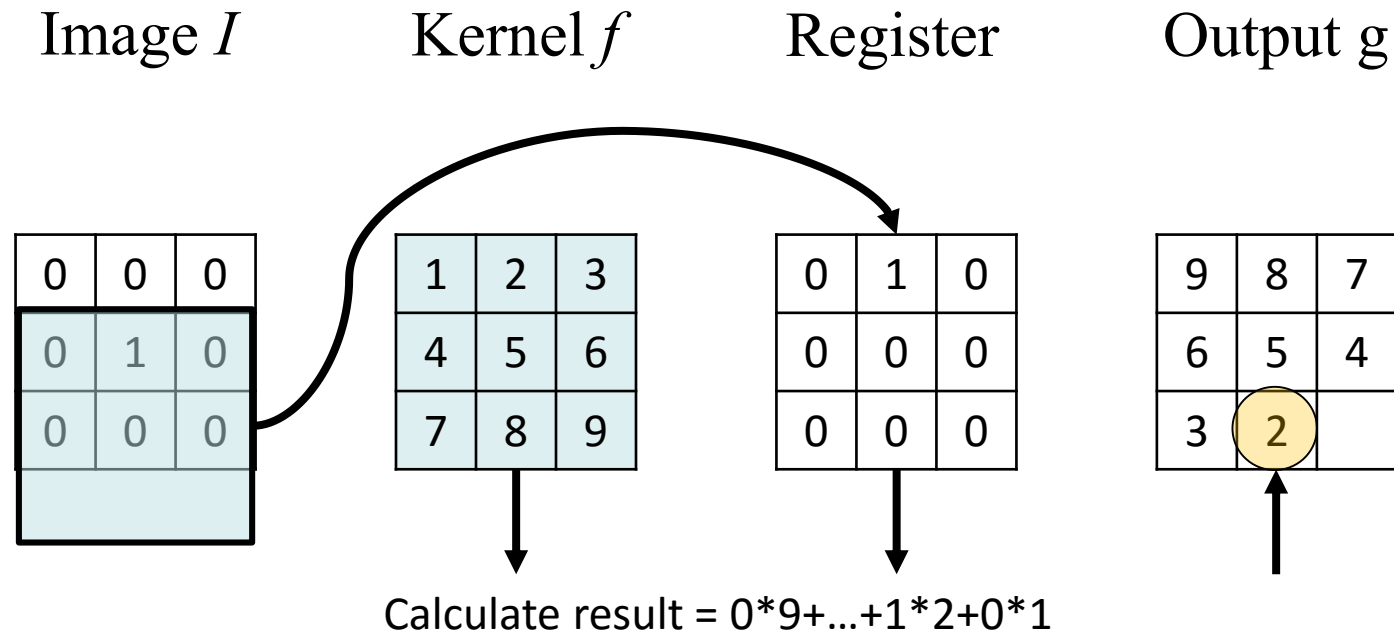
a	b	c
d	e	f
g	h	i

Loop over every pixel

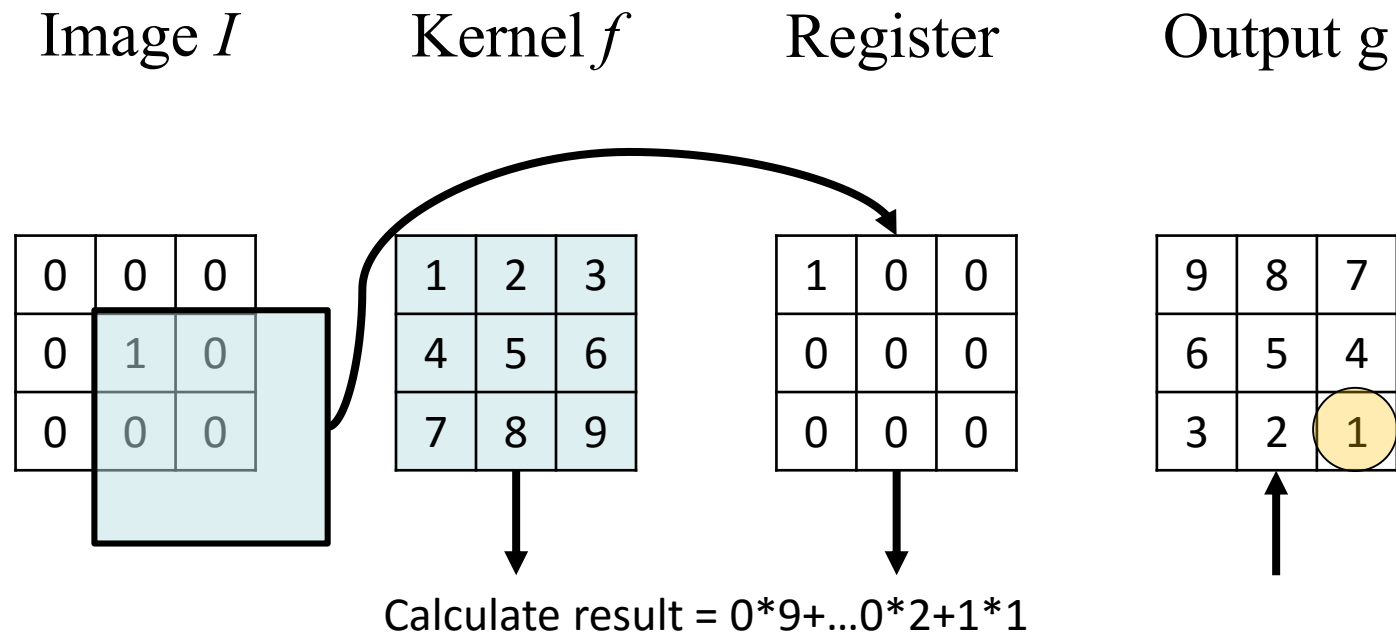
Calculate result = $a*1+b*2+\dots+i*9$



Special case: impulse function



Special case: impulse function



<Note> The output is the kernel flipped left-right, up-down!

Convolution

- Let I be an Signal(image), Convolution kernel g ,

$$f[m, n] = I \otimes g = \sum_{k,l} I[m-k, n-l]g[k, l]$$

Convolution

- $g[m, n] = I \otimes f = \sum_{k,l} I(m - k, n - l) * f(k, l)$
- Convolution is filtering with kernel flipped

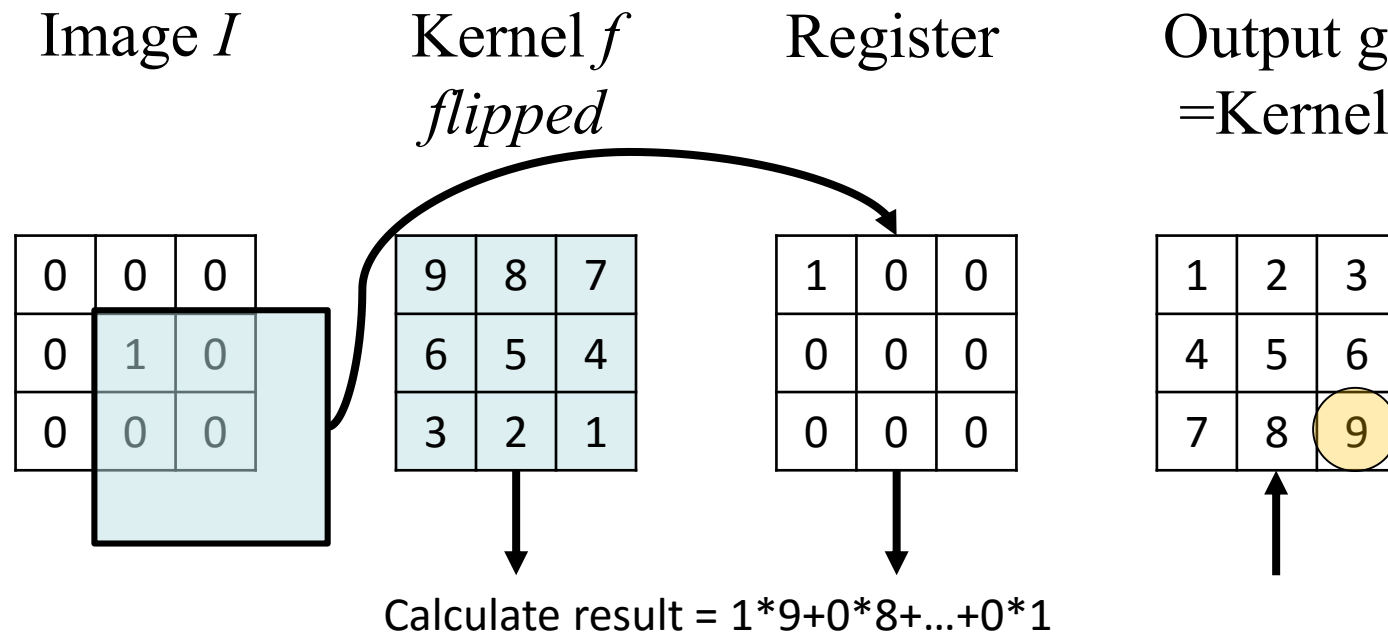


Image I

2	0	0
0	3	0
0	0	0

Kernel f
flipped

9	8	7
6	5	4
3	2	1

Output g

37	32	21
22	17	12
9	6	3

Decompose

1	0	0
0	0	0
0	0	0

*2

0	0	0
0	1	0
0	0	0

*3

Intermediate

5	4	0
2	1	0
0	0	0

*2

9	8	7
6	5	4
3	2	1

*3

Add together

- Convolution has commutative property $I \otimes f$

Image I

a	b	c
d	e	f
g	h	i

Kernel f

1	0	0
1	0	0
1	1	0

- Convolution has commutative property $I \otimes f$

Image I

a	b	c
d	e	f
g	h	i

Kernel f

1	0	0
1	0	0
1	1	0

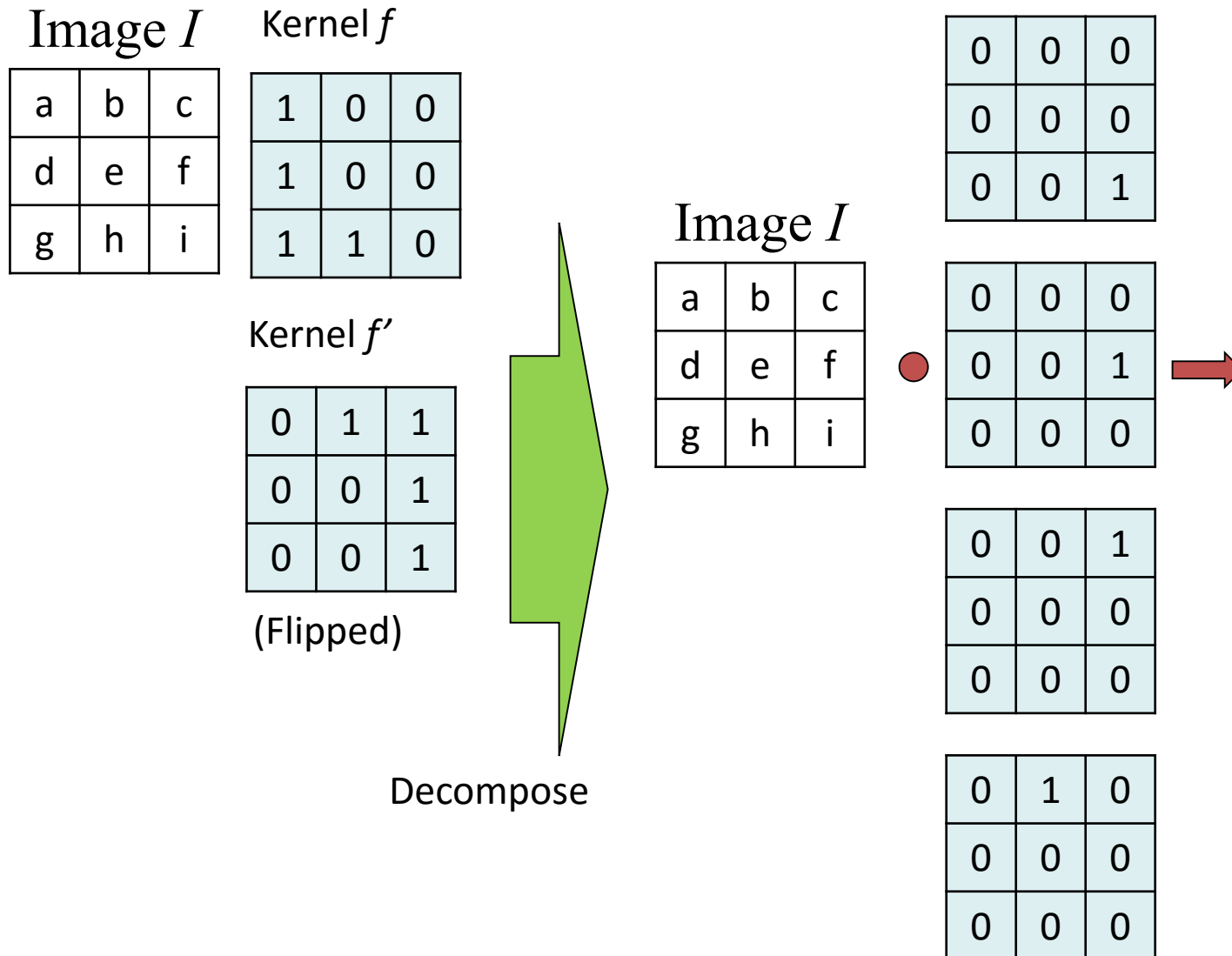
Kernel f'

0	1	1
0	0	1
0	0	1

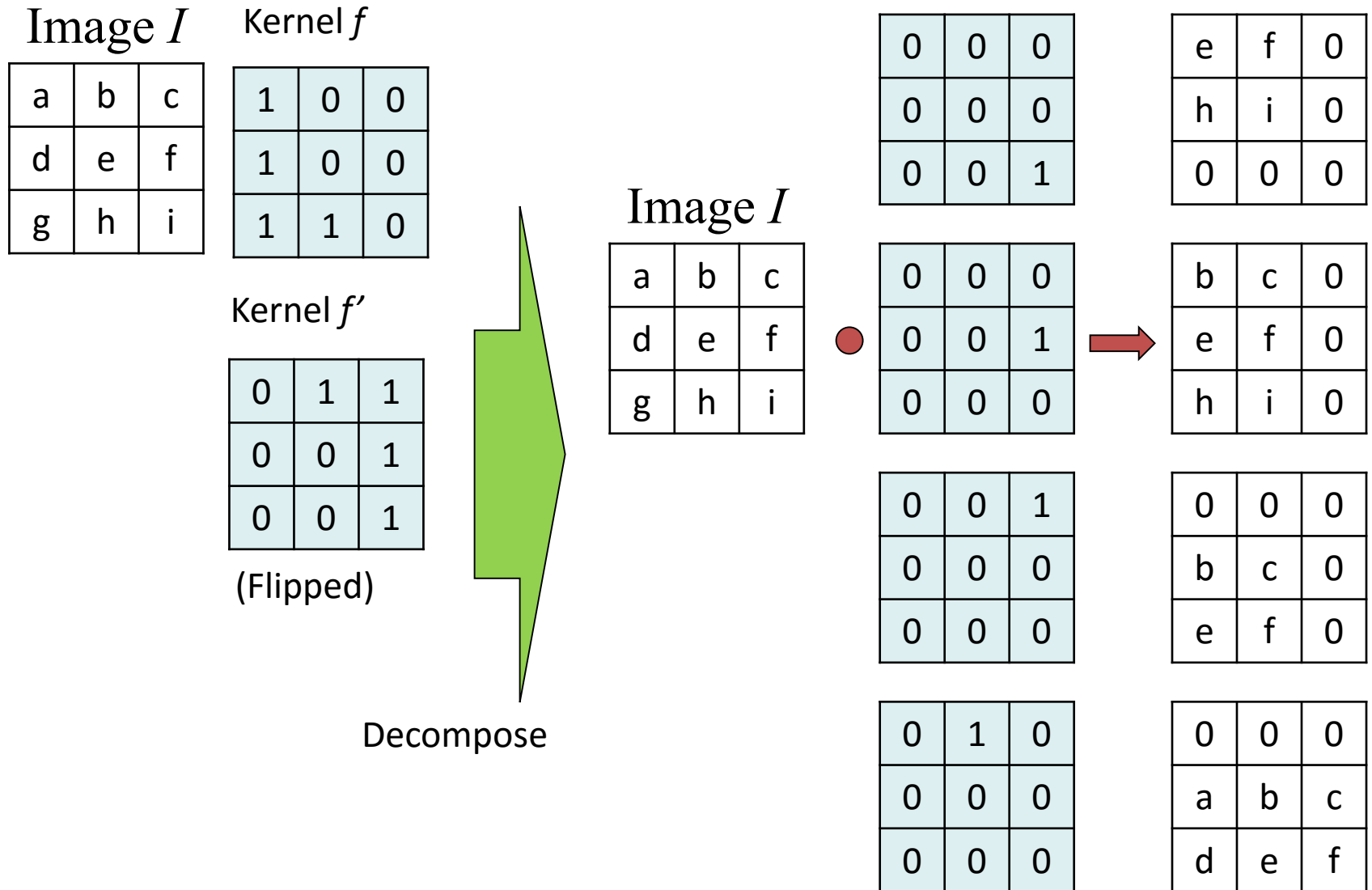
(Flipped)

Decompose

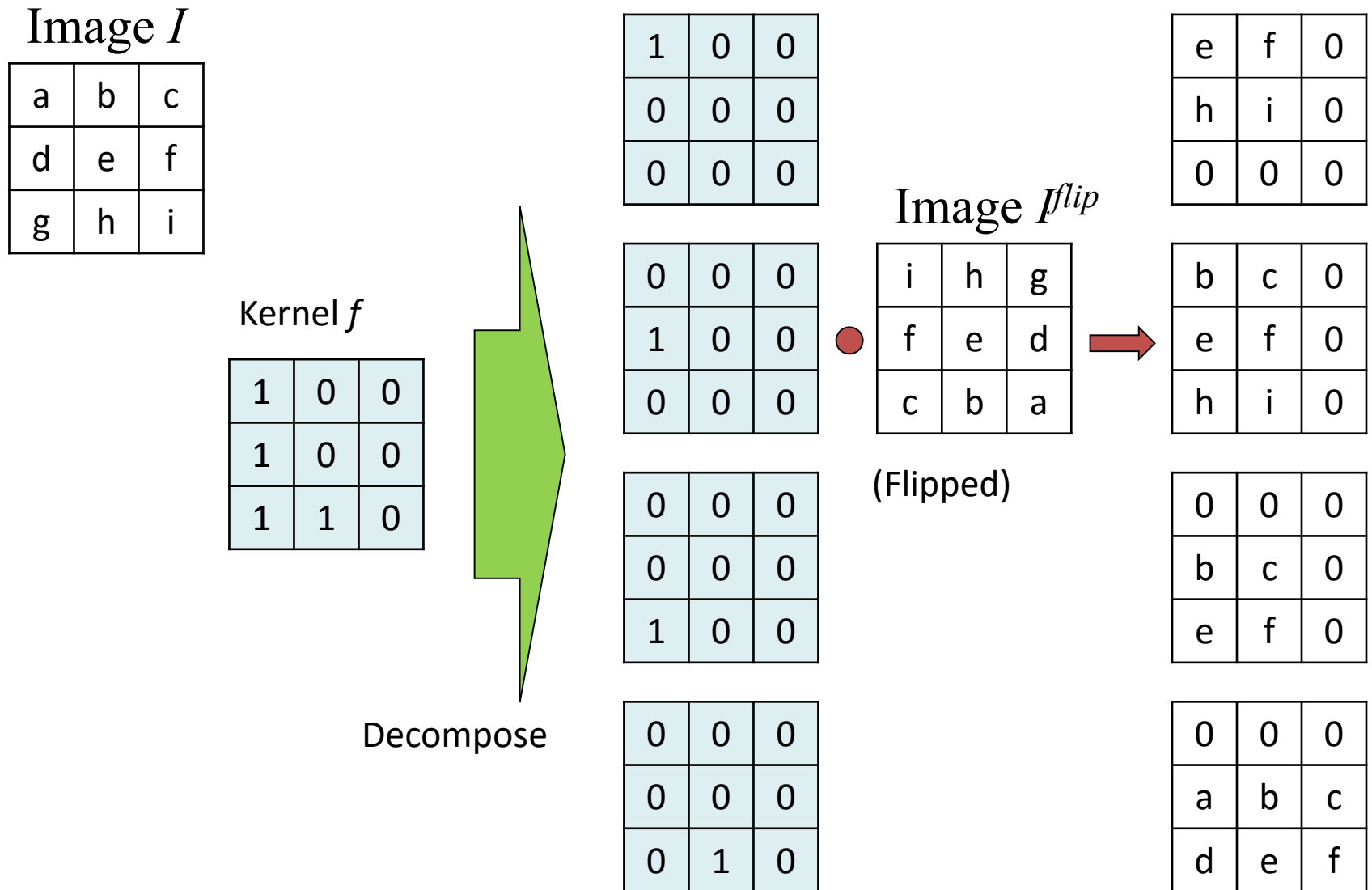
- Convolution has commutative property $I \otimes f$



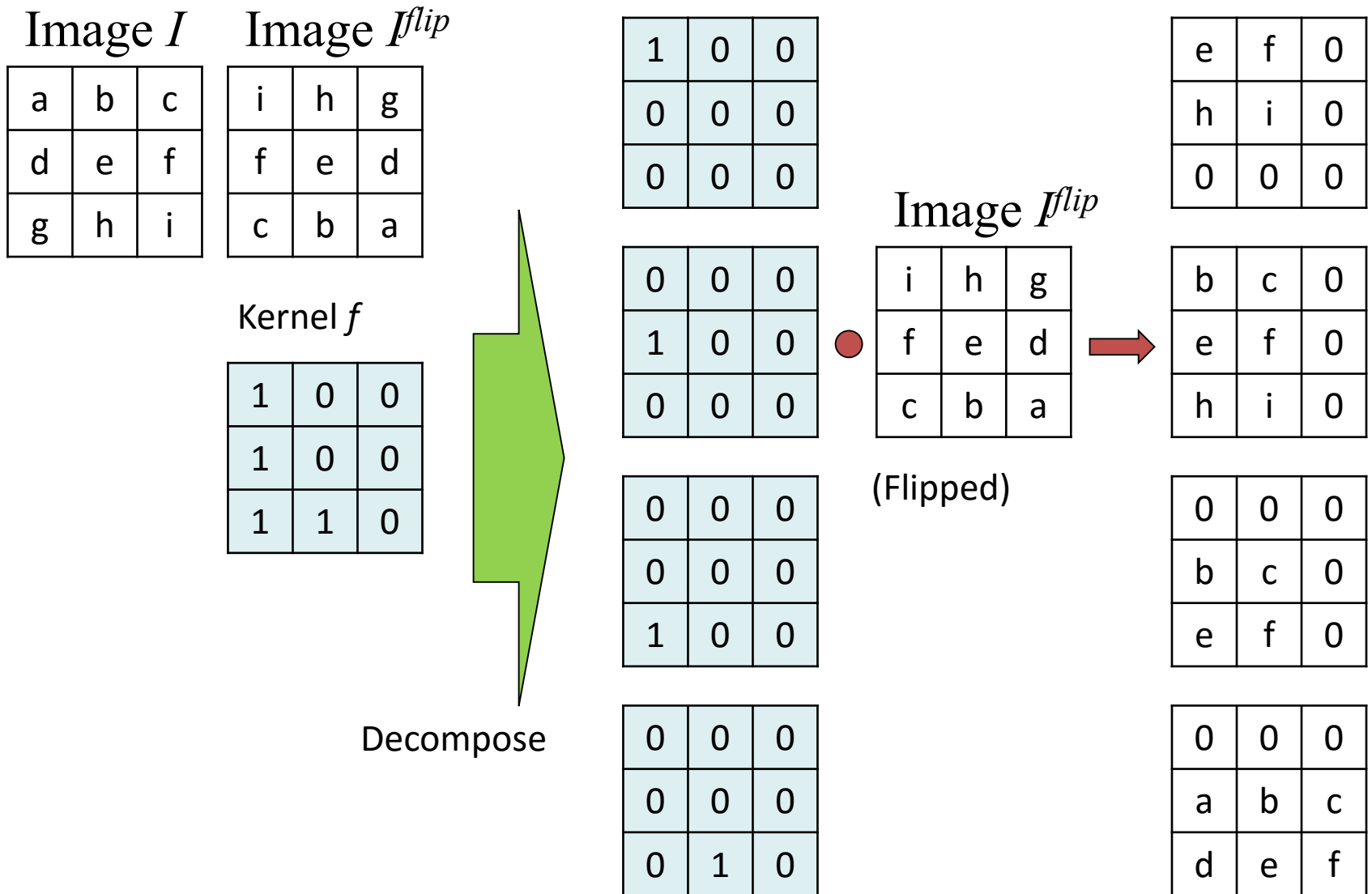
- Convolution has commutative property $I \otimes f$



- Convolution is commutative $I \otimes f = f \otimes I$



- Convolution is commutative $I \otimes f = f \otimes I$



Proof of Commutative property

- $g[m, n] = I \otimes f = f \otimes I$
- $g[m, n] = I \otimes f = \sum_{k,l} I(m - k, n - l) * f(k, l)$
- Let $k' = m - k, l' = n - l$,
then $k = m - k', l = n - l'$
- $g[m, n] = \sum_{k',l'} I(k', l') * f(m - k', m - l') = f \otimes I$

Impulse functions shift images

Image I

a	b	c
d	e	f
g	h	i

Kernel f

1	0	0
0	0	0
0	0	0

Kernel f'

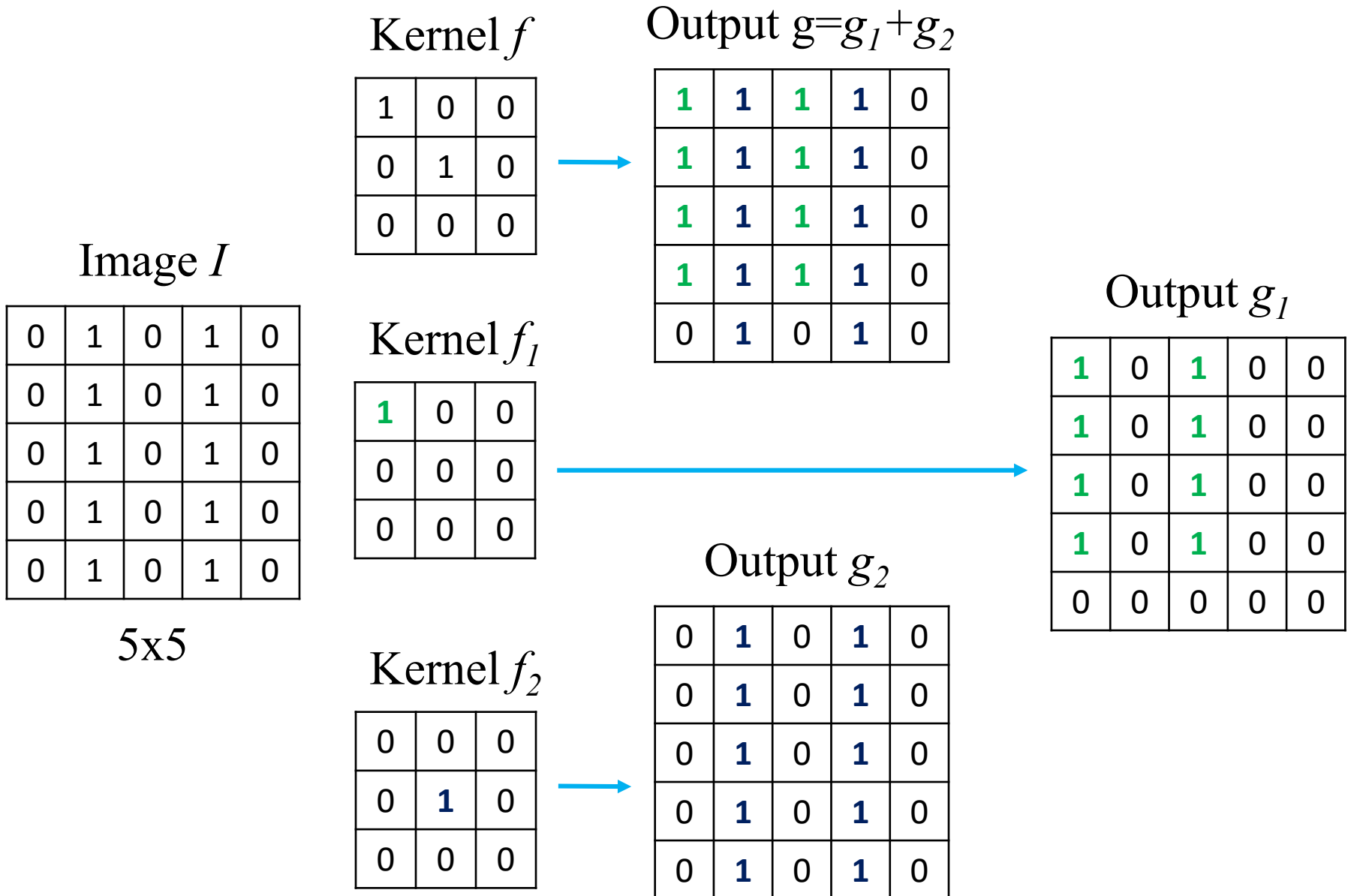
0	0	0
0	0	0
0	0	1

Result $I \otimes f$

e	f	0
h	i	0
0	0	0

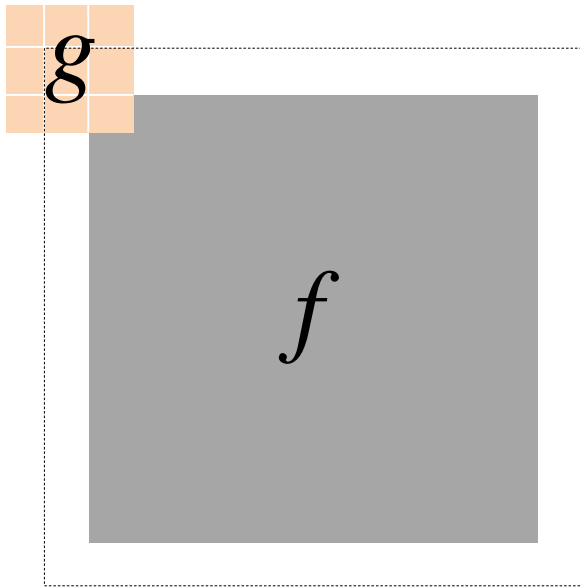
- In this case the resulting image shifted to the upper left

Linear independence

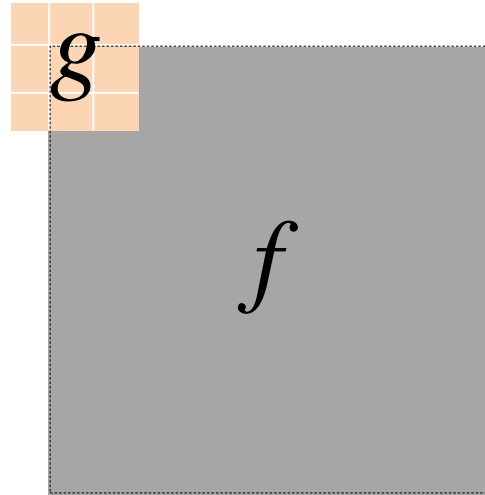


Output Size of Image Convolution

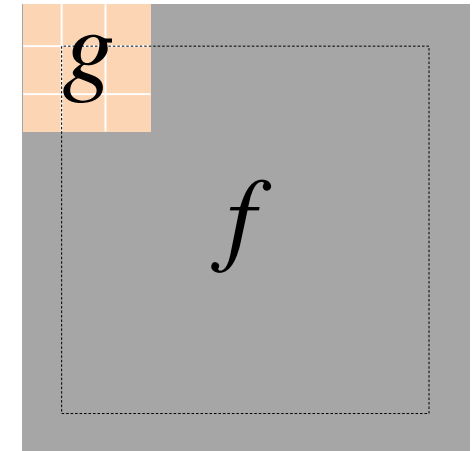
$$f \otimes g$$



Full



Same



Valid

`filter2(g, f, shape)` in MATLAB

Full: $\text{output_size} = \text{f_size} + \text{g_size} - 1$

Same: $\text{output_size} = \text{f_size}$

Valid: $\text{output_size} = \text{f_size} - (\text{g_size} - 1)$

2D visualization of convolution (full)

Image I

1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

8x8

Kernel f

1	2	3
4	5	6
7	8	9

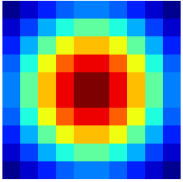
3x3

Output g

1	3	6	6	6	6	6	6	5	3
5	12	21	21	21	21	21	21	16	9
12	27	45	45	45	45	45	45	33	18
12	27	45	45	45	45	45	45	33	18
11	24	39	39	39	39	39	39	28	15
7	15	24	24	24	24	24	24	17	9
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0

10x10

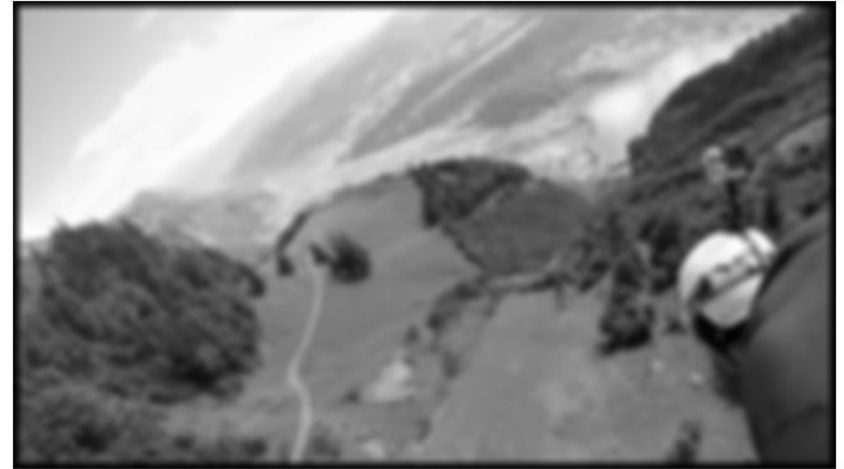
Output Size of Image Convolution



g : 10 x 10 Gaussian kernel



f : 640 x 360 resolution



Full

`filter2(g, f, shape)` in MATLAB

Full: $\text{output_size} = \text{f_size} + \text{g_size} - 1$

```
>> full = filter2(g, im, 'full');  
>> size(full)
```

ans =

369 649

2D visualization of convolution (same)

Image I

1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

8x8

Kernel f

1	2	3
4	5	6
7	8	9

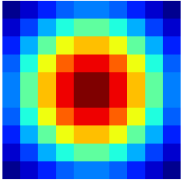
3x3

Output g

12	21	21	21	21	21	21	16
27	45	45	45	45	45	45	33
27	45	45	45	45	45	45	33
24	39	39	39	39	39	39	28
15	24	24	24	24	24	24	17
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

8x8

Output Size of Image Convolution



g : 10 x 10 Gaussian kernel



f : 640 x 360 resolution



Same

`filter2(g, f, shape)` in MATLAB

Full: $\text{output_size} = \text{f_size} + \text{g_size} - 1$

Same: $\text{output_size} = \text{f_size}$

```
>> same = filter2(g, im, 'same');
```

```
>> size(same)
```

```
ans =
```

```
360 640
```

2D visualization of convolution (valid)

Image I

1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

8x8

Kernel f

1	2	3
4	5	6
7	8	9

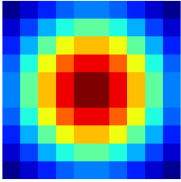
3x3

Output g

45	45	45	45	45	45
45	45	45	45	45	45
39	39	39	39	39	39
24	24	24	24	24	24
0	0	0	0	0	0
0	0	0	0	0	0

6x6

Output Size of Image Convolution



g : 10 x 10 Gaussian kernel



f : 640 x 360 resolution



Valid

`filter2(g, f, shape)` in MATLAB

Full: $\text{output_size} = \text{f_size} + \text{g_size} - 1$

Same: $\text{output_size} = \text{f_size}$

Valid: $\text{output_size} = \text{f_size} - (\text{g_size} - 1)$

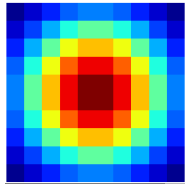
```
>> valid = filter2(g, im, 'valid');
```

```
>> size(valid)
```

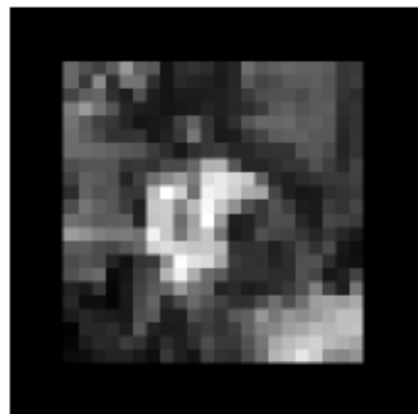
```
ans =
```

```
351 631
```

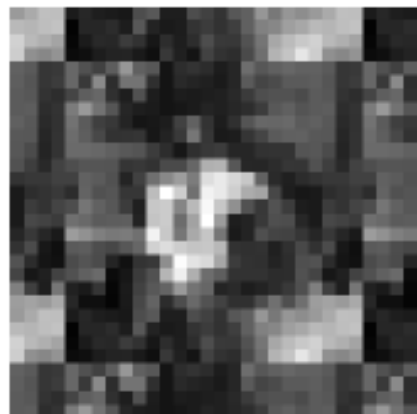

Image Boundary Effect



The filter window falls off at the edge of image.



zero



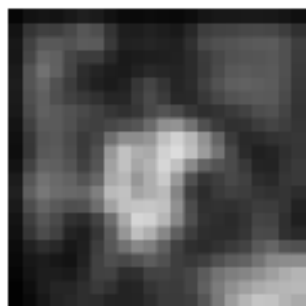
wrap



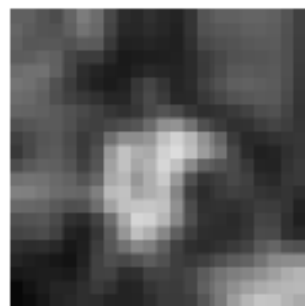
clamp



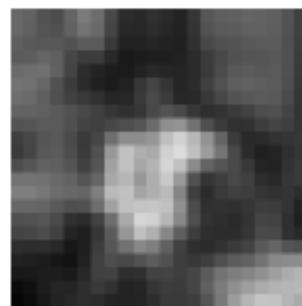
mirror



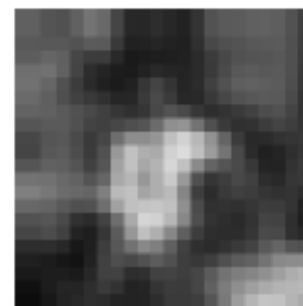
blurred zero



normalized zero



blurred clamp



blurred mirror

Image Extrapolation (Mirroring)

Code

```
J = imread('image.bmp');  
figure; imshow(J);
```



J

Image Extrapolation (Mirroring)

Code

```
boarder = 40;  
[nr,nc,nb] = size(J);  
J_big = zeros(nr+2*boarder, nc + 2*boarder,nb);  
J_big(boarder+1:boarder+nr,boarder+1:boarder+nc,:) = J;
```

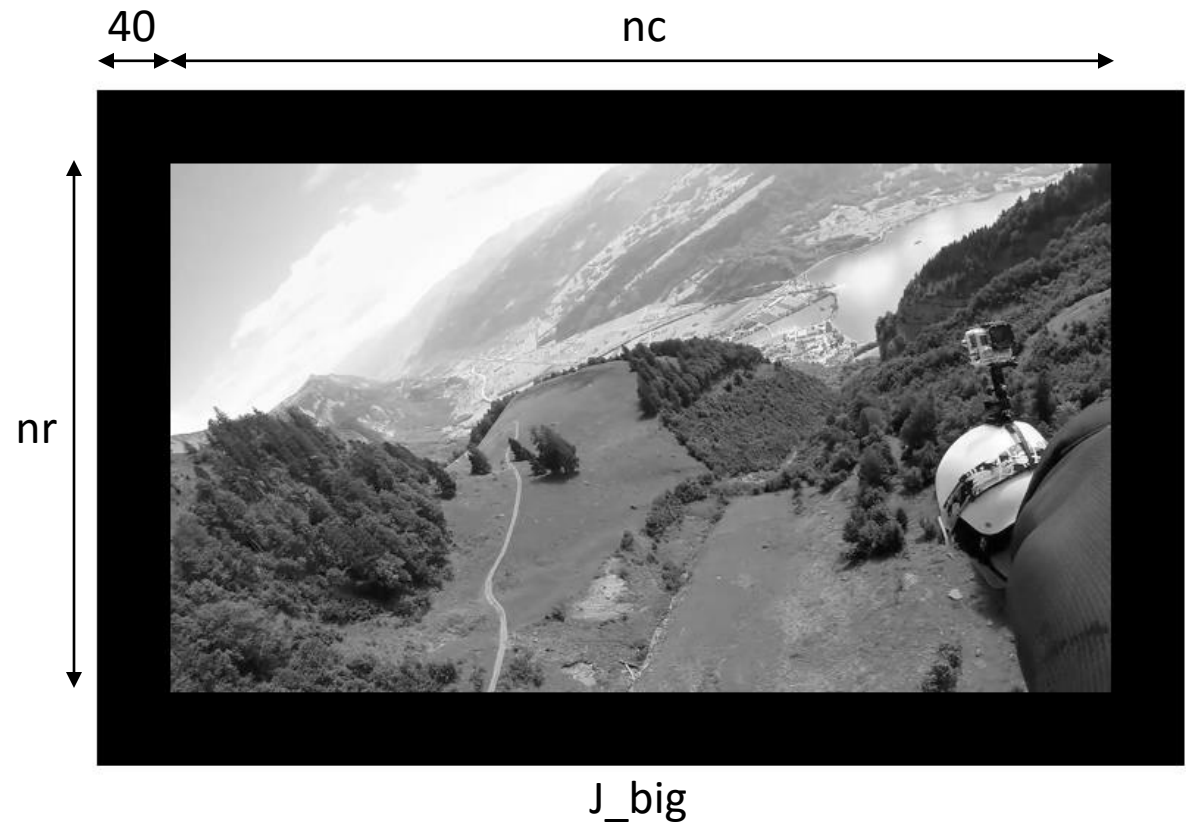


Image Extrapolation (Mirroring)

Code

```
for i=1:border,  
  for j=1:border,  
    J_big(i,j,:) = J(border-i+1,border-j+1,:);  
  end  
end
```

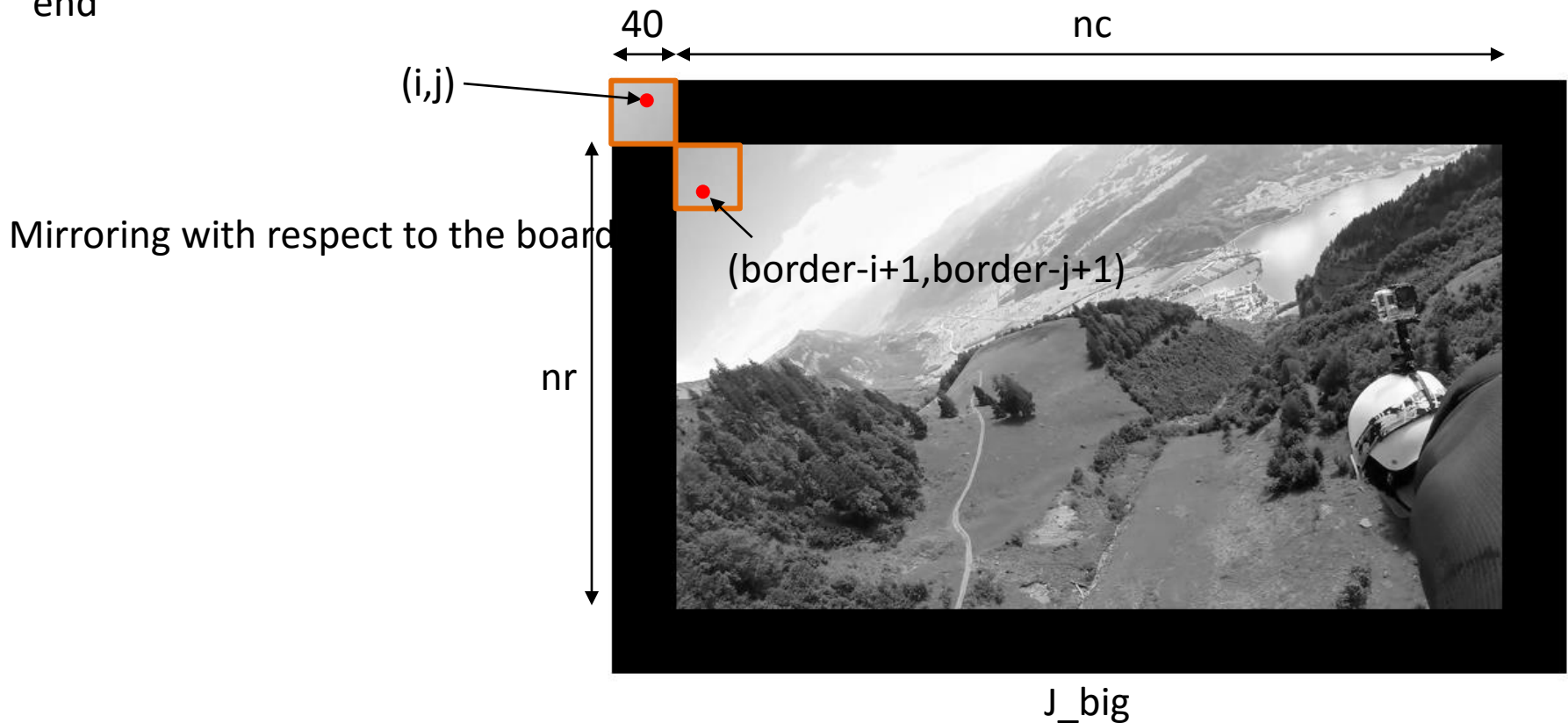


Image Extrapolation (Mirroring)

Code

```
for i=1:boarder,  
  for j=border+1:border+nc,  
    J_big(i,j,:) = J(border-i+1,j-border,:);  
  end  
end
```

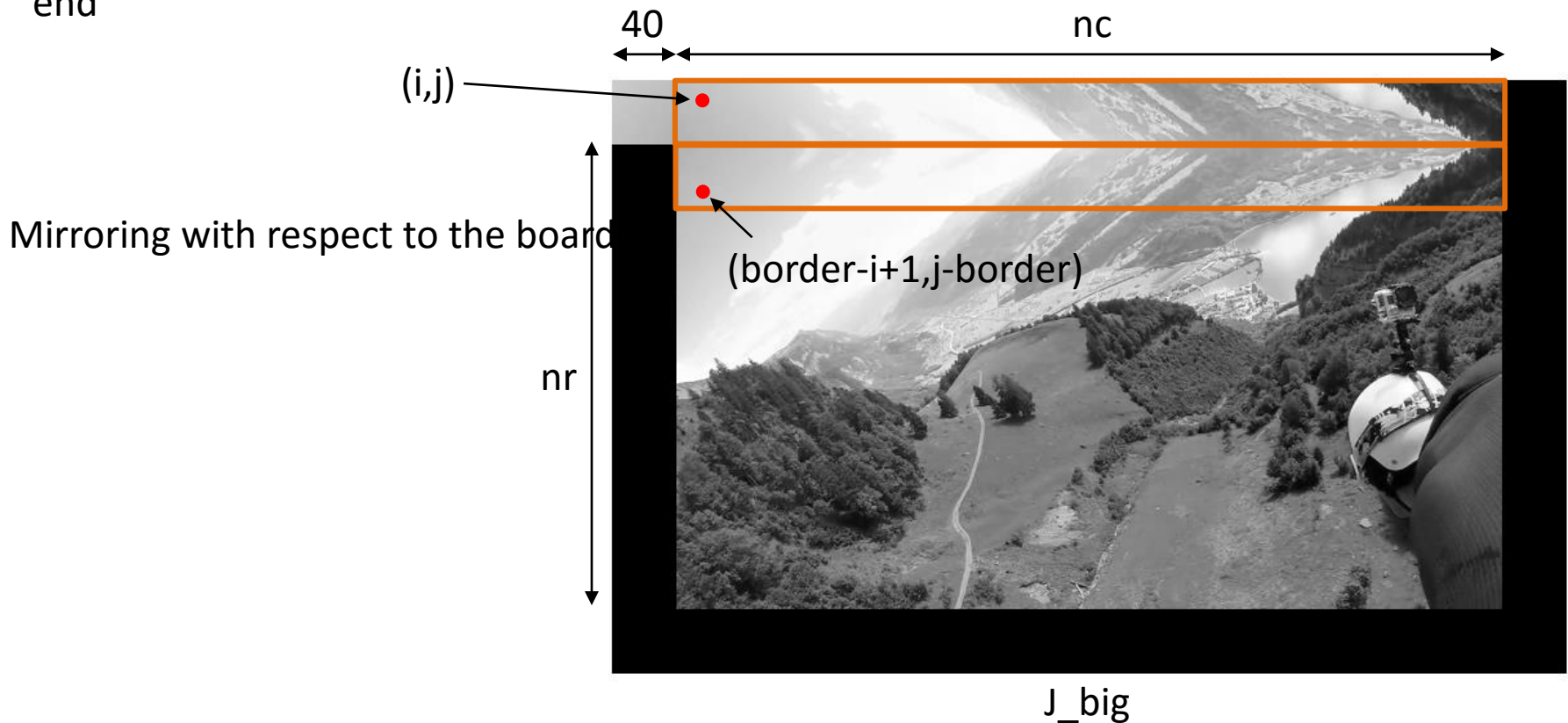


Image Extrapolation (Mirroring)

Code

```
for i=nr+border+1:border*2+nr,  
    for j=border+1:border+nc,  
        J_big(i,j,:) = J(2*nr-i+border+1,j-border,:);  
    end  
end
```

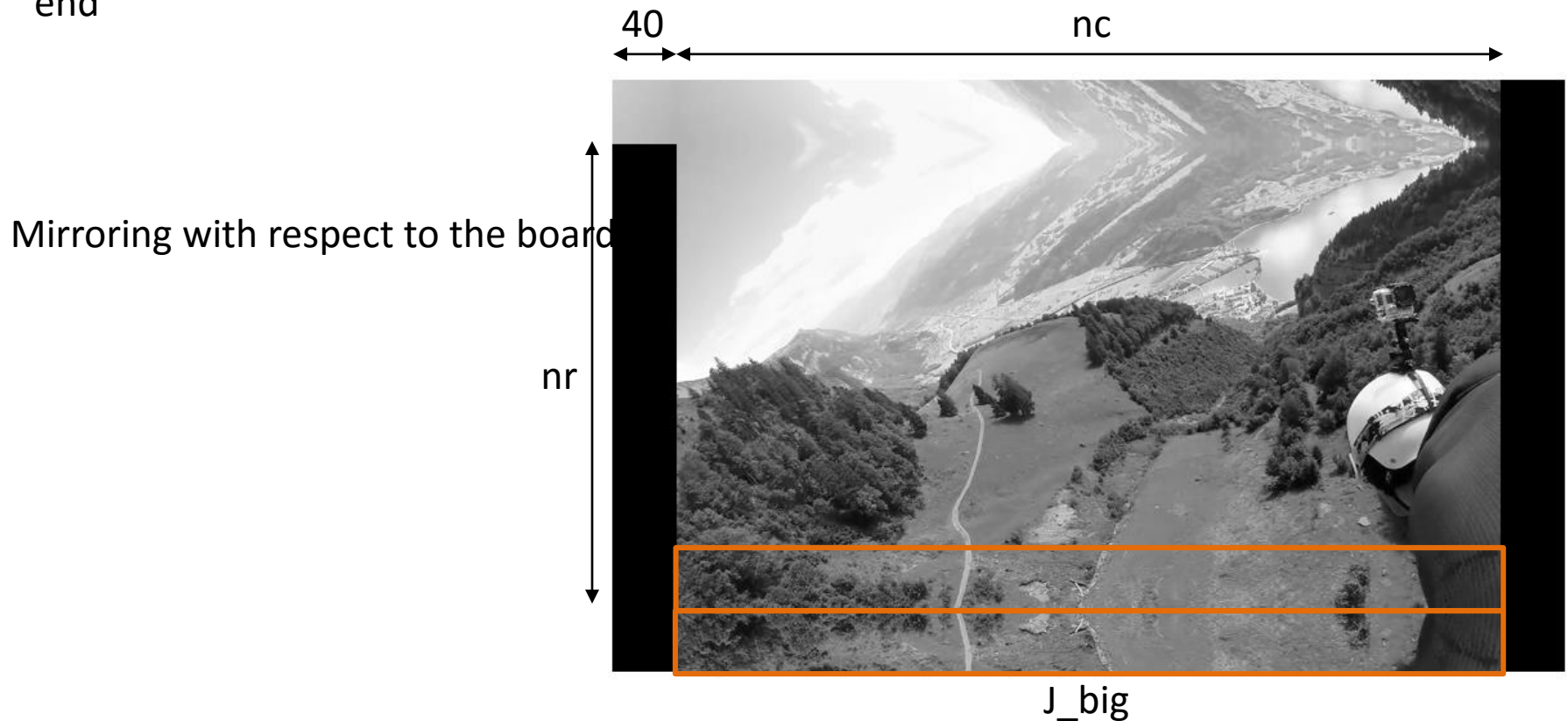
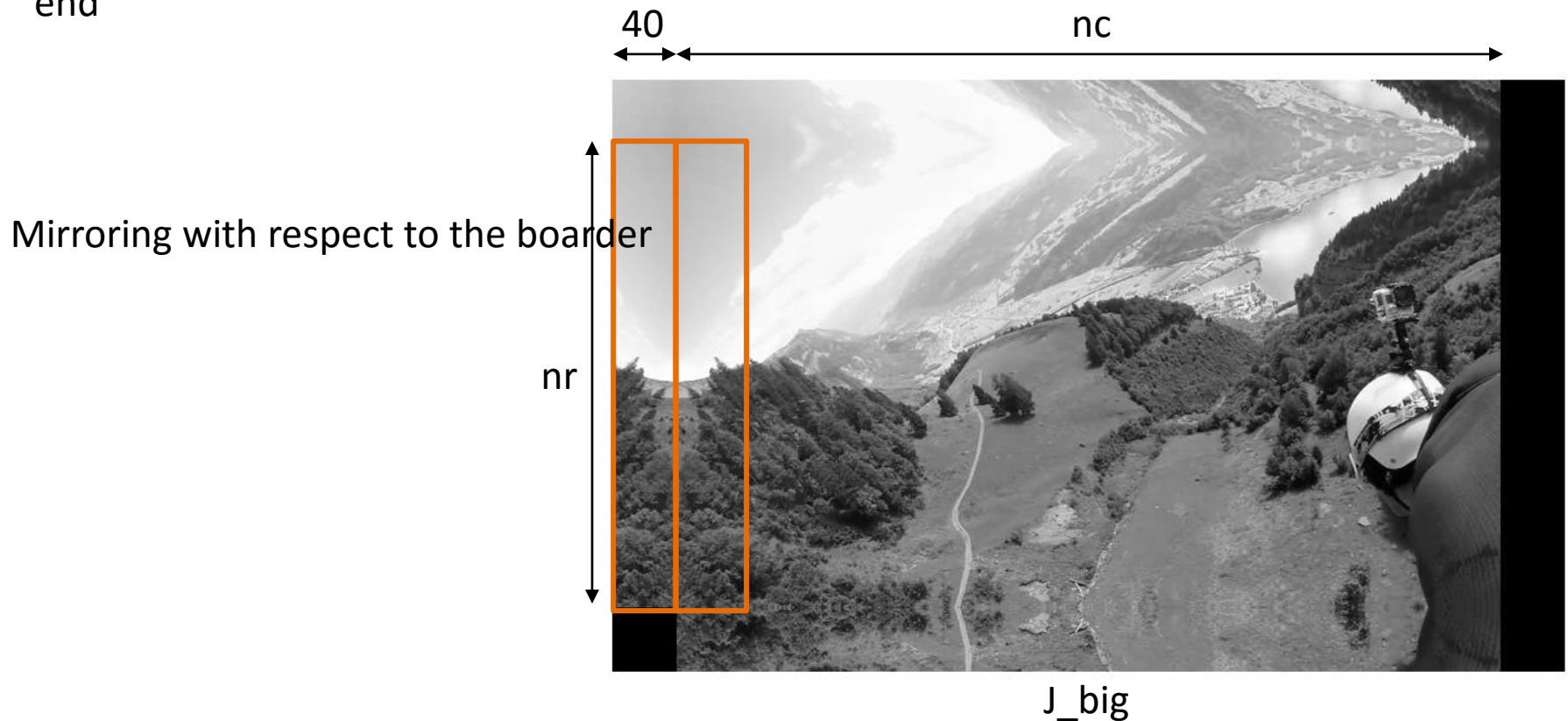


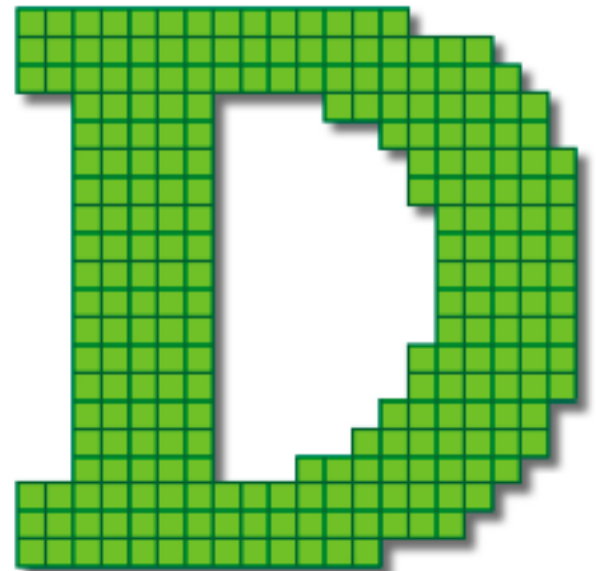
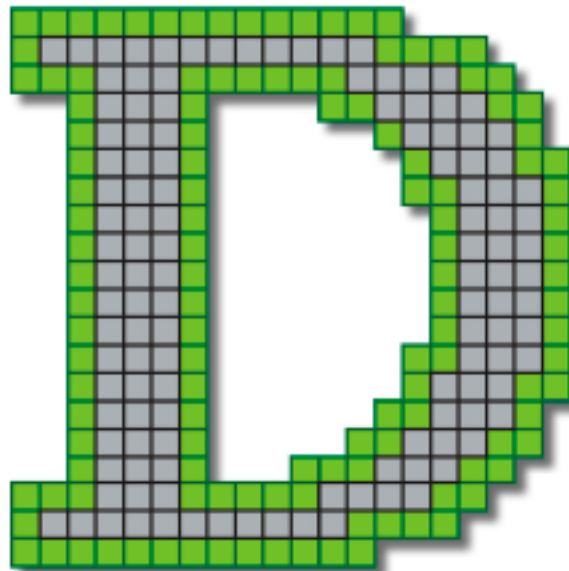
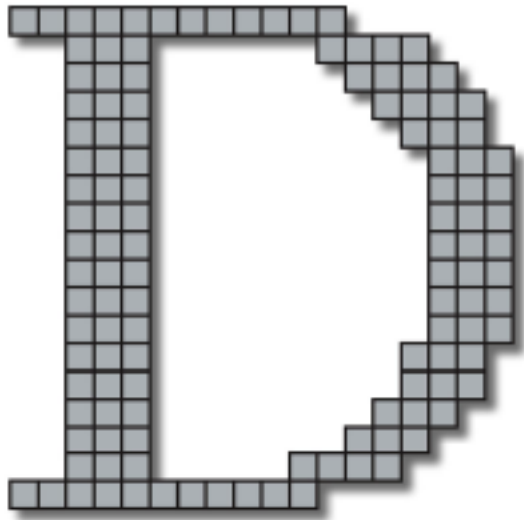
Image Extrapolation (Mirroring)

Code

```
for i=border+1:border+nr;  
    for j=1:border,  
        J_big(i,j,:) = J(i-border,border-j+1,:);  
    end  
end
```

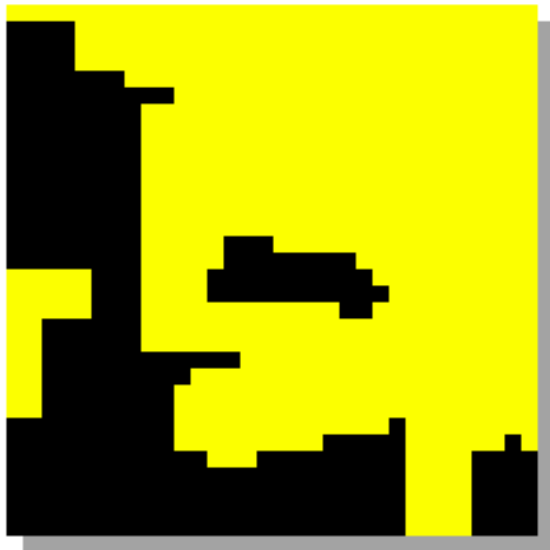


Dilation



Dilation

The locus of pixels $\mathbf{p} \in S_p$ such that $(\check{Z} + \mathbf{p}) \cap I \neq \emptyset$.



dilated image



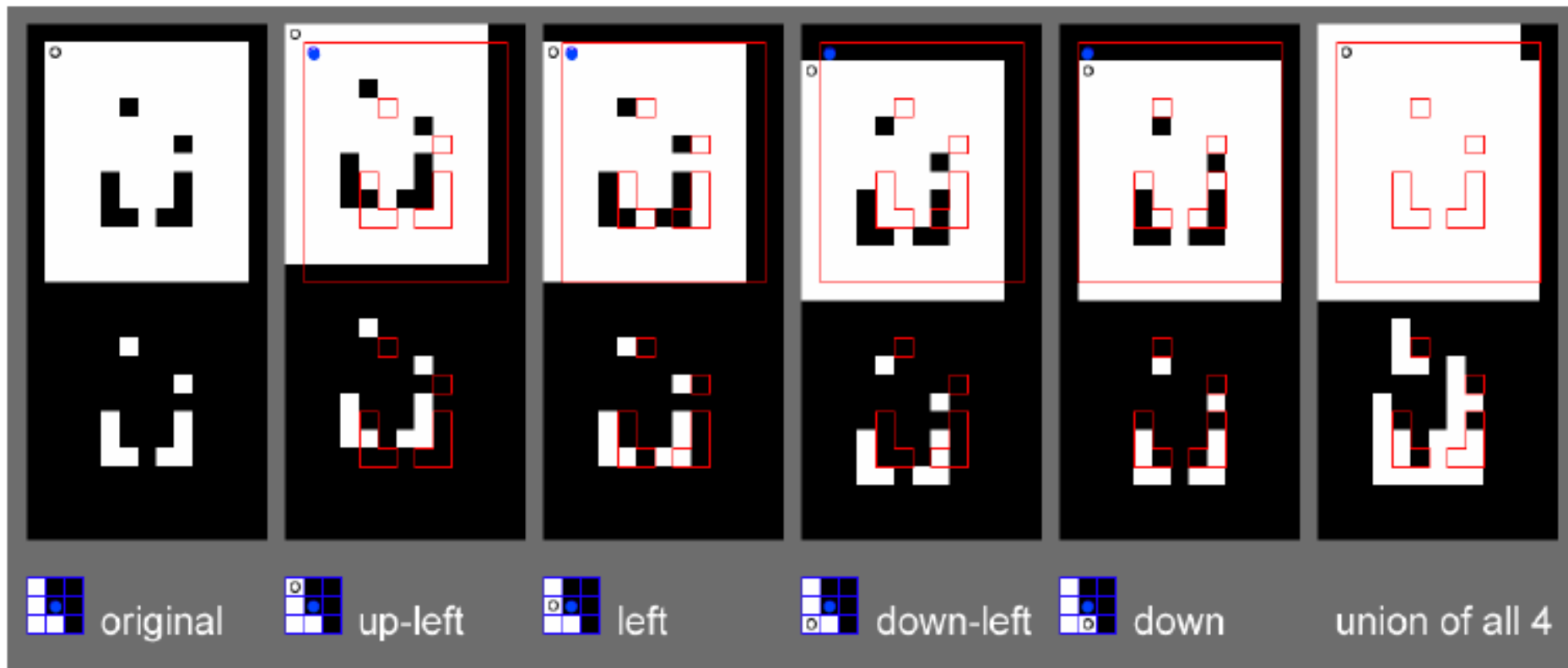
original / dilation



original image

$$SE = Z_8$$

Dilation through Image Shifting



Examples of image operation as convolution

Average Filter

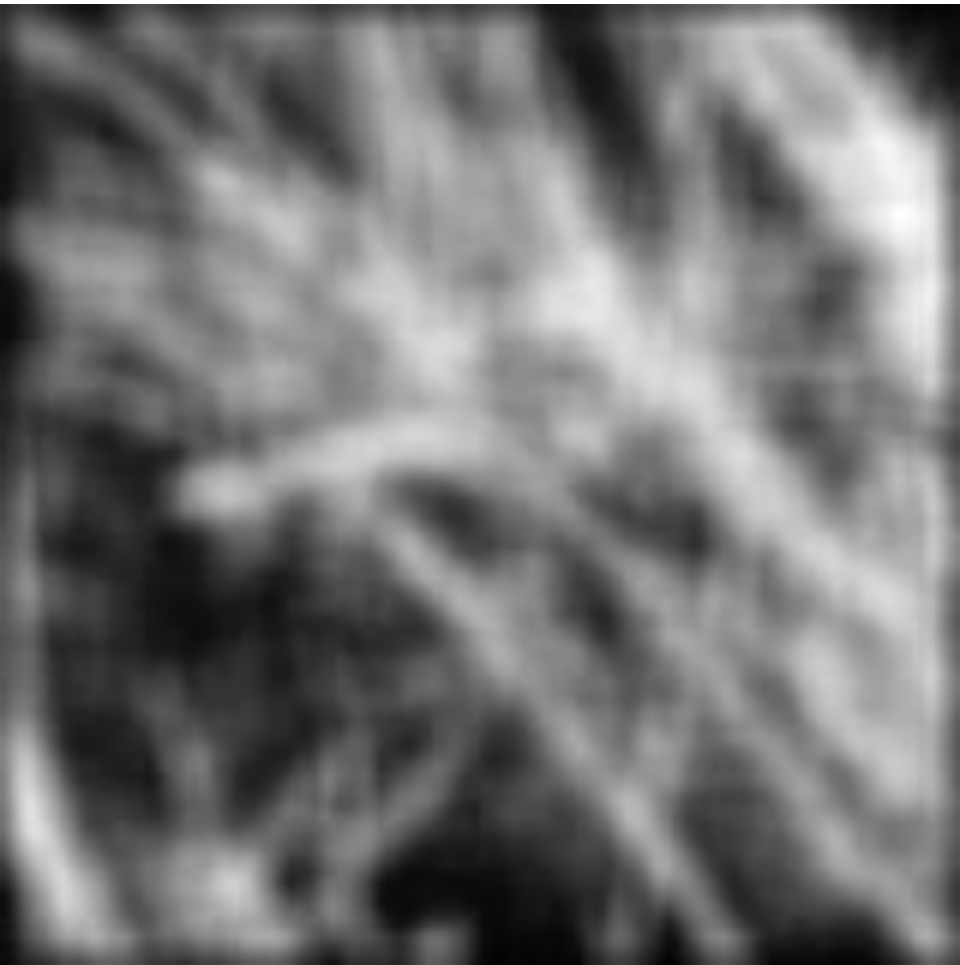
- Mask with positive entries, that sum 1.
- Replaces each pixel with an average of its neighborhood.
- If all weights are equal, it is called a BOX filter.

F

	1	1	1
1/9	1	1	1
	1	1	1

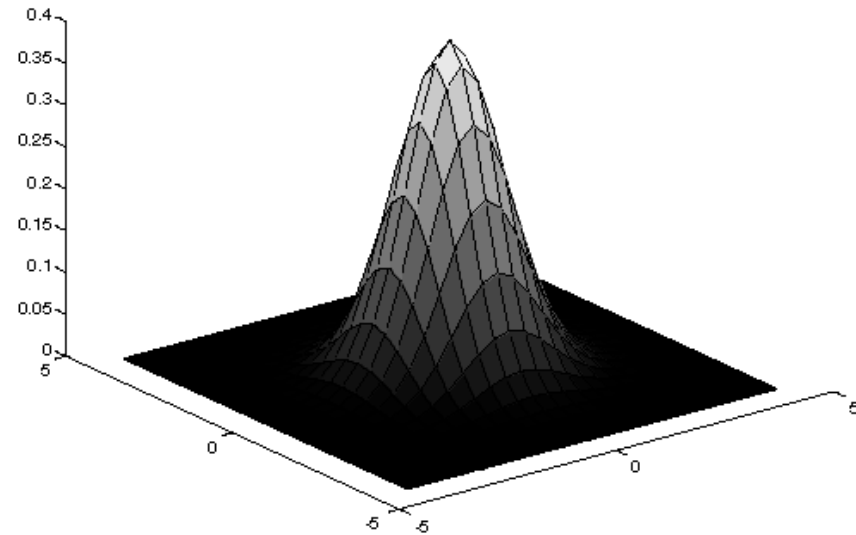
(Camps)

Example 1: Smoothing by Averaging



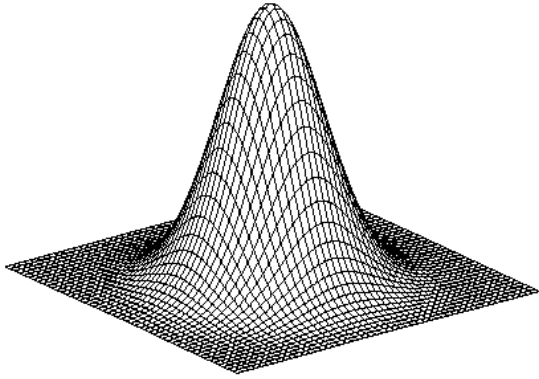
Gaussian Averaging

- Rotationally symmetric.
- Weights nearby pixels more than distant ones.
 - This makes sense as probabilistic inference.



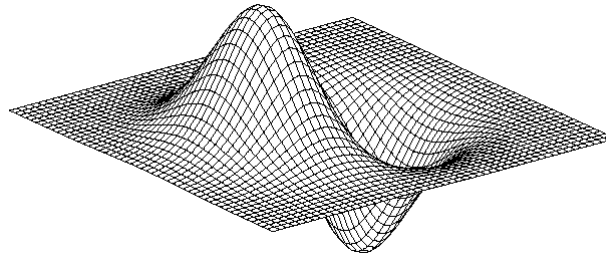
- A Gaussian gives a good model of a fuzzy blob

2D filters, more on this later...



Gaussian

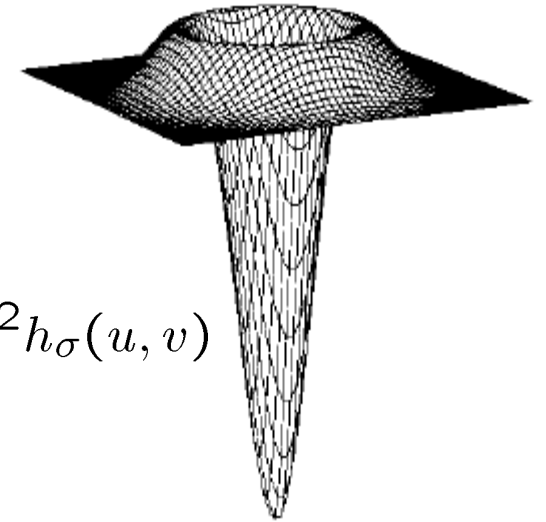
$$h_{\sigma}(u, v) = \frac{1}{2\pi\sigma^2} e^{-\frac{u^2+v^2}{2\sigma^2}}$$



derivative of Gaussian

$$\frac{\partial}{\partial x} h_{\sigma}(u, v)$$

Laplacian of Gaussian

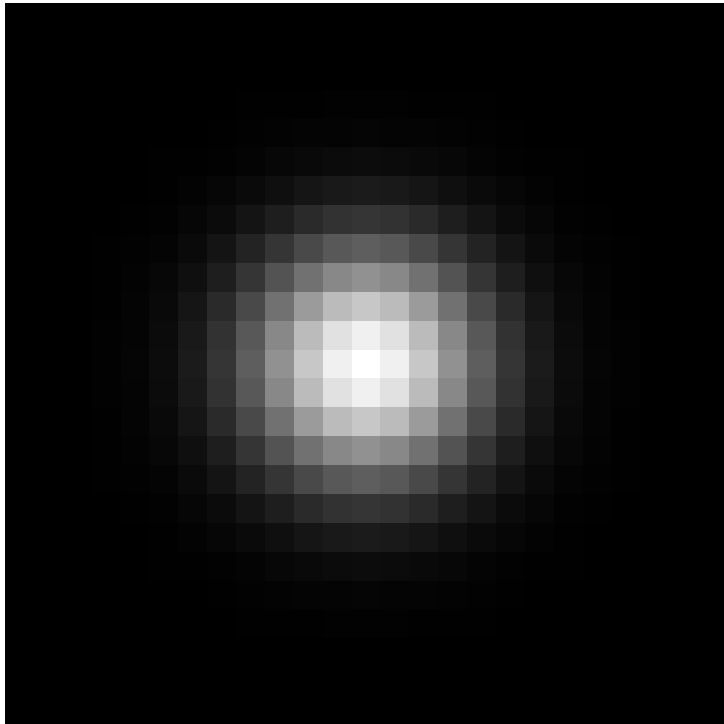


$$\nabla^2 h_{\sigma}(u, v)$$

- is the **Laplacian** operator:

$$\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2}$$

An Isotropic Gaussian

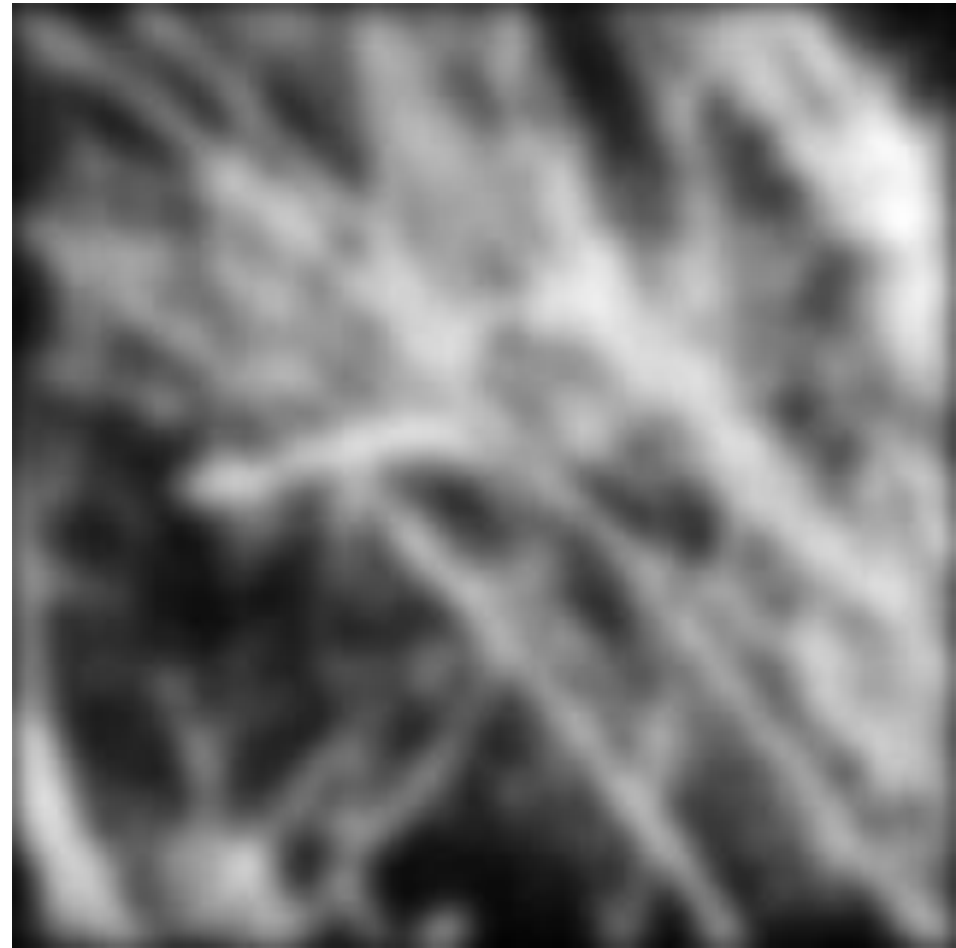


- The picture shows a smoothing kernel proportional to

$$e^{-\frac{x^2 + y^2}{2\sigma^2}}$$

- (which is a reasonable model of a circularly symmetric fuzzy blob)

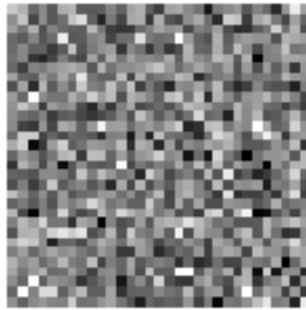
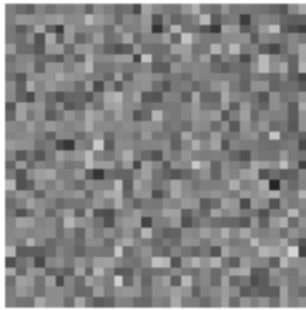
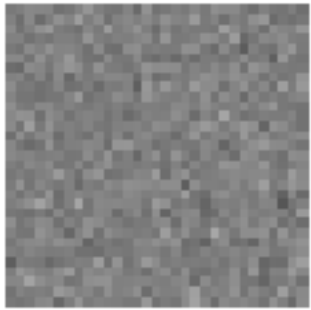
Smoothing with a Gaussian



$\sigma=0.05$

$\sigma=0.1$

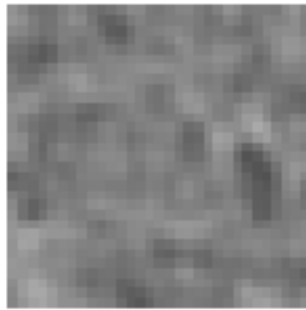
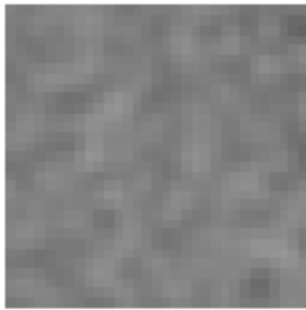
$\sigma=0.2$



no
smoothing

The effects of smoothing

Each row shows smoothing with gaussians of different width; each column shows different realizations of an image of gaussian noise.



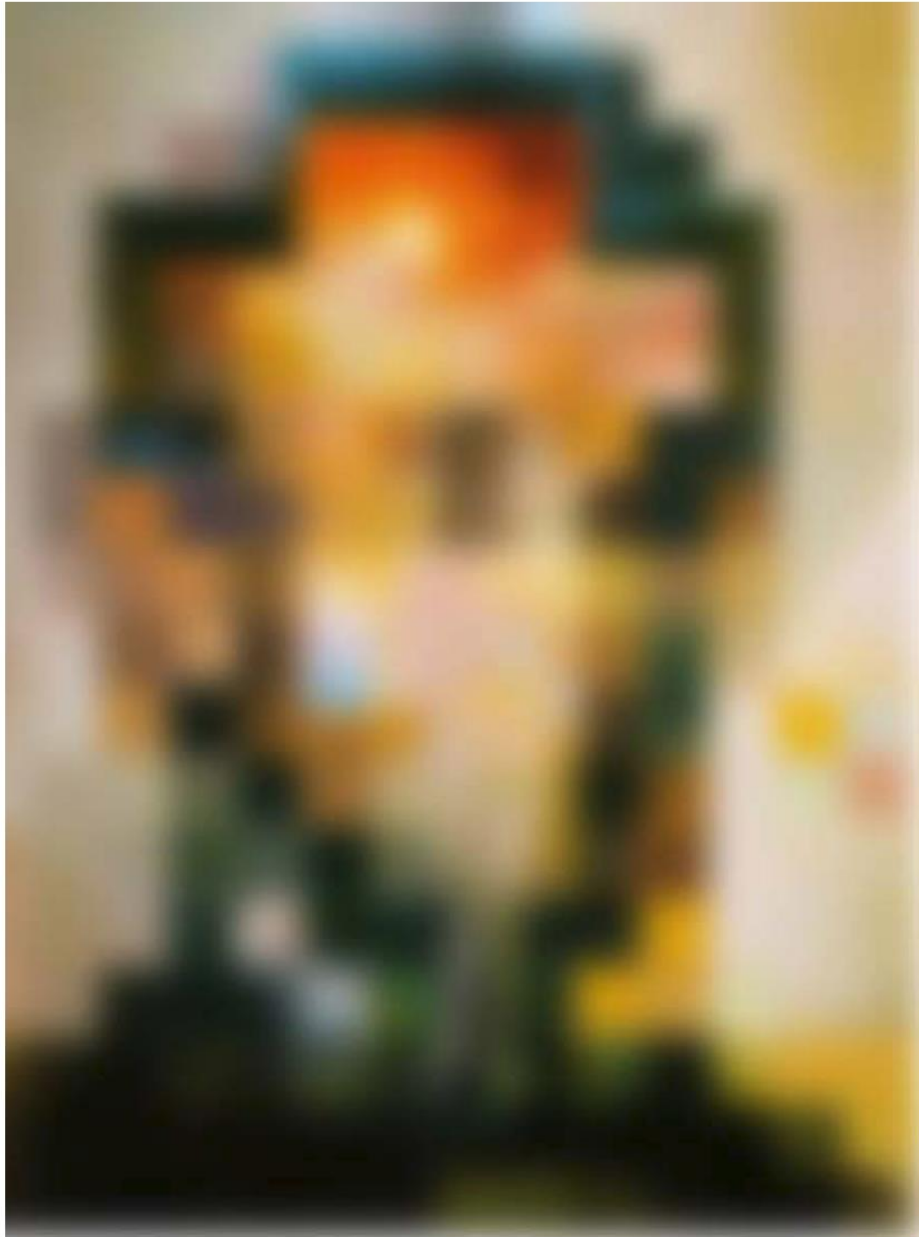
$\sigma=1$ pixel



$\sigma=2$ pixels



Salvador Dalí, *Gala Contemplating the Mediterranean Sea, which at 30 meters becomes the portrait of Abraham Lincoln*, 1976



Salvador Dali, *Gala Contemplating the Mediterranean Sea, which at 30 meters becomes the portrait of Abraham Lincoln*, 1976

Image smoothing can remove noise, and also ...



